Advanced Electronic Systems
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The present document is based on four lectures given for Master of Space and Aeronautics in University of Science and Technology of Hanoi. It consists of four parts. The first one is devoted to filters, while the second one deals with DC/DC converter, the third one discusses the phase locked loop and the last the modulation. For convenience of the readers the work is organized so that each part is self-contained and can be read independently. These four electronic systems are chosen because they are representative of critical elements encountered in spacecraft; whether for power supply or for data transmission.

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Part I

Filters
1.1 Introduction

A filter performs a frequency-dependent signal processing. A filter is generally used to select a useful frequency band out from a wide band signal (example: to isolate station in radio receiver). It is also used to remove unwanted parasitic frequency band (example: rejection of the 50-60 Hz line frequency or DC blocking). Analogue to digital converter also require anti-aliasing low-pass filters.

The most common filters are low-pass, high-pass, band-pass and band-stop (or notch if the rejection band is narrow) filters:

![Transfer function of ideal filter](image1.png)

To do an electronic filter, devices which have frequency-dependent electric parameter as L and C impedances are required. The use of these reactive impedances into a voltage bridge is the most common method to do a filtering; this is called passive filtering. Passive (R,L,C) filter is used at high frequencies due to the low L and C values required. But, at frequency lower than 1 MHz, it is more common to use active filters made by an operational amplifier in addition to R and C with reasonable values. Furthermore, active filter parameters are less affected by load impedances than passive one.

1.2 Filter parameters

1.2.1 Voltage transfer function

Passive low-pass filter example: a first order low-pass filter is made by R-C or L-R circuit as a voltage divider with frequency-dependent impedance. Capacitor impedance \( Z_C = \frac{1}{j\omega C} \) decreases at high frequency\(^\dagger\) while inductor impedance \( Z_L = j\omega L \) increases. Capacitor is then put across output voltage.

---

\*A reactive impedance is a purely imaginary impedance.
\(^\dagger\)Active filter allows to separate the filter parameters with those matching impedance.
\(^\ddagger\)Angular frequency \( \omega = 2\pi f \)
and inductor between input and output voltage (Fig. 1.2) to perform low pass filtering.

![Passive low-pass filter: first order R-C, first order L-R and second order L-C.](image)

**Generalization:** whatever impedances $Z_x$ of the voltage bridge shown in figure 1.3, voltage transfer functions $H$ are generalized as expression 1.1 by calculating the divider’s voltage ratio using Kirchhoff’s voltage law*.

$$v_{in} \xrightarrow{Z_1} v_{out} = \frac{Z_2}{Z_1 + Z_2} v_{in}$$

![Impedance bridge voltage divider.](image)

Voltage transfer functions of filters given in figure 1.2 are then expressed as:

- **$H_{RC}$**
  $$H_{RC} = \frac{Z_C}{R + Z_C} = \frac{1}{R + j\omega C} \quad \Rightarrow \quad H_{RC} = \frac{1}{1 + jRC\omega}$$

  cut-off frequency $\equiv |H_{RC}| = \frac{1}{\sqrt{2}} \rightarrow RC\omega_c = 1 \rightarrow f_{c_{RC}} = \frac{1}{2\pi RC}$

- **$H_{LR}$**
  $$H_{LR} = \frac{R}{R + Z_L} = \frac{R}{R + jL\omega} \quad \Rightarrow \quad H_{LR} = \frac{1}{1 + \frac{1}{R^2L}}$$

  $$f_{c_{LR}} = \frac{R}{2\pi L}$$

- **$H_{LC}$**
  $$H_{LC} = \frac{Z_C}{Z_L + Z_C} = \frac{1}{j\omega L + \frac{1}{j\omega C}} \quad \Rightarrow \quad H_{LC} = \frac{1}{1 - LC\omega^2}$$

&A filter can also be used to convert a current to a voltage or a voltage to a current in addition to a simple filtering†. Considering for example the first R-C low-pass filter in figure 1.2. We can define

*The sum of the voltage sources in a closed loop is equivalent to the sum of the potential drops in that loop: $v_{in} = Z_1 \times \frac{v_{out}}{Z_2} + v_{out}$

†To filter a current, two impedances in parallel are required: current divider. In our example without load impedance $i_{in} = i_{out}$. Current transfer function $\frac{i_{out}}{i_{in}}$ is then always equal to 1.
trans-impedance transfer function \( \frac{v_{\text{out}}}{i_{\text{in}}} \) and also the trans-admittance transfer function
\[ \frac{\"i\_{\text{out}}\,\"}{v_{\text{in}}} = \frac{1}{\frac{1}{jC\omega} + \frac{R}{jC\omega}} = \frac{jC\omega}{1 + jRC\omega} \]

\[ \rightarrow \ \text{Integrator} \quad \text{(1.5)} \]

\[ \frac{\"i\_{\text{out}}\,\"}{v_{\text{in}}} = \frac{1}{\frac{1}{R + Z_C} = \frac{1}{\frac{R}{R} + \frac{1}{jC\omega} = 1 + jRC\omega} \}
\[ \rightarrow \ \text{High-pass filter} \quad \text{(1.6)} \]

1.2.2 S plane (Laplace domain)

For transient analysis, filter transfer function \( H \) must be represented as a function of the complex number \( s \):

\[ s = \sigma + j\omega \]  \hspace{1cm} \text{(1.7)}

Then, reactive impedances are expressed as function of this complex number:

\[ Z_L = Ls \]  \hspace{1cm} \text{(1.8)}

\[ Z_C = \frac{1}{Cs} \]  \hspace{1cm} \text{(1.9)}

Frequency response and stability information can be revealed by plotting in a complex plane (s plane) roots values of \( H(s) \) numerator (zero) and denominator (pole).

- **Poles** are values of \( s \) such that transfer function \( |H| \rightarrow \infty \),
- **Zeros** are values of \( s \) such that transfer function \( |H| = 0 \).

Considering the band-pass filter of the figure 1.4, the transfer function \( H_{\text{LCR}} = \frac{v_{\text{out}}}{v_{\text{in}}} \) is given by equation 1.10.

\[
H_{\text{LCR}}(s) = \frac{R}{R + Ls + \frac{1}{Cs}} = \frac{RCs}{1 + RCs + LCs^2}
\]  \hspace{1cm} \text{(1.10)}

The order of the filter (Fig. 1.4) is given by the degree of the denominator of the expression 1.10. A **zero** corresponds the numerator equal to zero. A **pole** is given by the denominator equal to zero. Each pole provides a -20dB/decade slope of the transfer function ; each zero a + 20 dB/decade \(^*\). Zero and pole can be real or complex. When they are complex, they have a conjugate pair \(^\dagger\).

Expression 1.10 is characterized by a zero at \( s = 0 \) and two conjugate poles obtained by nulling it's denominator (eq. 1.11)\(^\ddagger\).

\[
0 = 1 + RCs + LCs^2 \hspace{1cm} \Delta = (RC)^2 - 4LC \hspace{1cm} s_p = \frac{-RC \pm \sqrt{(RC)^2 - 4LC}}{2LC}
\]  \hspace{1cm} \text{(1.11)}

The discriminant \( \Delta \) could be positive, null or negative as shown in figure 1.5. The boundary (\( \Delta = 0 \)) between negative and positive discriminant is given by the equation \((RC)^2 = 4LC\) and could be rewrite

\[ \frac{1}{2} = \frac{\sqrt{\Delta}}{R} \]  \hspace{1cm} which is the expression of a parameter called the quality factor \( Q \).

\(^*\) \( H[dB] = 20\log|H|_{\text{lin.}} \) and a decade correspond to a variation by a factor of 10 in frequency. A times 10 ordinate increasing on a decade (times 10 abscissa increasing) correspond to a 20dB/decade slope on a logarithmic scale or also 6dB/octave. A - 20dB/decade then correspond to a transfer function decreasing by a factor of 10 on a decade

\(^\dagger\) each conjugate pair has the same real part, but imaginary parts equal in magnitude and opposite in sign

\(^\ddagger\) The roots (zeros) of a polynomial of degree 2 (quadratic function) \( ax^2 + bx + c = 0 \) are \( x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \) where the discriminant is \( \Delta = b^2 - 4ac \)
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Figure 1.5: Discriminant $\Delta = (RC)^2 - 4LC$ value as function of $(RC)^2$ and $4LC$.

Nature (real or imaginary) of the roots is reported in the table 1.1.

<table>
<thead>
<tr>
<th>$\Delta = (RC)^2 - 4LC$</th>
<th>roots $s_p$</th>
<th>$Q = \frac{\sqrt{LC}}{R}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>&gt; 0</td>
<td>2 real</td>
<td>&lt; 1/2</td>
</tr>
<tr>
<td>= 0</td>
<td>1 real double</td>
<td>= 1/2</td>
</tr>
<tr>
<td>&lt; 0</td>
<td>2 complex conjugates</td>
<td>&gt; 1/2</td>
</tr>
</tbody>
</table>

Table 1.1: Link between discriminant sign and nature of the roots. Conditions on the R, L and C device values are reported expressed as the quality factor Q.

Roots are expressed as two complex conjugate roots $^*$: the poles $s_{p1}$ and $s_{p2}$ given on 1.12.

$$s_{p1,2} = \frac{-R}{2L} \pm j \sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2}$$ (1.12)

The natural angular frequency $\omega_0$ is the module of the pole:

$$\omega_0 = |s_{p1,2}| = \frac{1}{\sqrt{LC}}$$ (1.13)

In a s plane, pole and zero allow to locate where the magnitude of the transfer function is large (near pole), and where it is small (near zero). This provides us understanding of what the filter does at different frequencies and is used to study the stability. Figure 1.6 shows pole (●) and zero (●) in a s plane.

A causal linear system is stable if real part of all poles is negative. On the s plane, this corresponds to a pole localization at the left side (Fig. 1.7).

*<sup>+</sup> Laplace notation $s = \sigma + j\omega$ is required to study stability condition and transient (time domain) analysis. However, for steady state signal (frequency domain) analysis, Fourier notation $s = j\omega$ is preferred to do harmonic analysis.

1.2.3 Bode plot (Fourier domain)

The most common way to represent the transfer function of a filter is the Bode plot. Bode plot is usually a combination of the magnitude $|H|$ and the phase $\phi$ of the transfer function on a log frequency axis.

$^*\sqrt{|x|_{x>0}} = i\sqrt{|x|}$
1. FILTERS

1.2. FILTER PARAMETERS

\[ H_{LCR} = \frac{j RC \omega}{1 + j RC \omega - LC \omega^2} = \frac{1}{1 + j \left( \frac{RC \omega}{R} - \frac{1}{RC} \right)} \]  \hspace{1cm} (1.14)

\[ |H_{LCR}| = \frac{1}{\sqrt{1 + \left( \frac{RC \omega}{R} - \frac{1}{RC} \right)^2}} \]  \hspace{1cm} (1.15)

\[ \phi_{LCR} = \arg(H_{LCR}) = -\arctan \left( \frac{RC \omega}{R} - \frac{1}{RC} \right) \]  \hspace{1cm} (1.16)

Numerical Application:  \( L = 1 \text{ mH}, C = 100 \text{ nF} \) and \( R = 100 \Omega \)

• The natural \(^\dagger\) frequency \( f_0 = \frac{1}{2\pi \sqrt{LC}} = \frac{165}{2\pi} \approx 16 \text{ kHz} \)

The band-pass filter could be seen as a cascading high and a low-pass filter:

• The high pass-filter cutoff frequency \( f_{c1} = \frac{R}{2\pi L} \)

• The low pass-filter cutoff frequency \( f_{c2} = \frac{1}{2\pi RC} \)

The Bode diagram of this band-pass filter is plotted on figure 1.8.

\(^\dagger\) With this specific numerical application \( f_0 = f_{c1} = f_{c2} \), \( f_0, f_{c1} \) and \( f_{c2} \) are however not necessarily equal. Nevertheless, whatever the numerical application, \( f_0 = \sqrt{f_{c1} f_{c2}} \)

\(^\dagger\) Absolute value or module

\(^\dagger\) Argument

\(^\dagger\) In the case of band-pass filter, the natural frequency is also called resonance frequency or center frequency corresponding to \( LC\omega_0^2 = 1 \). This is the frequency at which the impedance of the circuit is purely resistive.
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In this numerical application \( f_0 = f_{c1} = f_{c2} \) (Fig 1.8). This correspond to a particular case where the quality factor \( Q = \frac{1}{R} \sqrt{\frac{L}{C}} = \frac{1}{100} \sqrt{\frac{10^{-7}}{10^{-12}}} = 1 \). For other numerical application (i.e. \( Q \neq 1 \)), \( f_0 \) is different than \( f_{c1} \) and \( f_{c2} \) (Fig 1.9).

**Quality factor \( Q \)**

Quality factor \( Q \) is a dimensionless parameter which indicates how much is the sharpness of a multi-pole filter response around its cut-off (or center *) frequency. In the case of a band-pass filter, its expression 1.17 is the ratio of the center frequency by the -3 dB bandwidth \( (BW)^\dagger \) and is given for series and parallel LCR circuit.

\[
Q = \frac{f_0}{BW} = \frac{f_{c2}}{f_{c1}} \quad \text{band-pass filter}
\]

\[
= \frac{1}{R} \sqrt{\frac{L}{C}} \quad \text{series LCR}
\]

\[
= R \sqrt{\frac{C}{L}} \quad \text{parallel LCR}
\]

(1.17)

Quality factor is directly proportional to the selectivity of a band-pass filter (Fig. 1.9):

- \( Q < \frac{1}{2} \) → damped and wide band filter
- \( Q = \frac{1}{2} \) → critically damped
- \( Q > \frac{1}{2} \) → resonant and narrow band filter

We have already see that \( Q = 1/2 \) is related to the denominator roots of the transfer function, see table 1.1.

In practice, \( Q \) factor is proportional to the ratio between the maximum energy stored in the reactive devices and the energy losses in the resistor:

\[
Q = \frac{\omega_0}{\text{Max. Energy Stored}} \quad \frac{\text{Power loss}}{} \quad (1.18)
\]

*for a band-pass filter

\( ^\dagger \) For resonant circuits, \( BW|_{0-3dB} \neq f_{c2} - f_{c1} \). Indeed, for \( Q = 1 \), \( f_{c2} = f_{c1} = f_0 \), but \( BW = f_0 \)
The maximum stored energy is \( L I_{\text{RMS}}^2 \) or \( CV_{\text{RMS}}^2 \); the dissipated power is \( R I_{\text{RMS}}^2 \) or \( V_{\text{RMS}}^2/\sqrt{R} \) and \( \omega_0 = 2\pi f_0 = \frac{1}{\sqrt{LC}} \). In series LCR, \( I_L = I_C = I_R \). In parallel LCR, \( V_L = V_C = V_R \). So, it is easy to link equations 1.17 and 1.18.

We can again rewrite expression 1.14 by using now natural frequency \( f_0 \) and quality factor \( Q \):

\[
H_{\text{LCR}} = \frac{j R C \omega}{1 + j R C \omega - L C \omega^2} = \frac{j \frac{1}{Q} \frac{\omega}{\omega_0} - \omega^2}{1 + j \frac{1}{Q} \frac{f}{f_0} - \frac{f^2}{f_0^2}} = \frac{1}{1 + j Q \left( \frac{f}{f_0} - \frac{f_0}{f} \right)}
\]

(1.19)

with \( R C = \frac{1}{Q \omega_0} \), \( Q = \frac{1}{\sqrt{\pi C}} \), \( \omega_0 = 2\pi f_0 = \frac{1}{\sqrt{LC}} \) and \( \omega = 2\pi f \).

Figure 1.9: Bode plot of a band-pass filter - \( Q = 0.01 ; 0.1 ; 0.25 ; 0.5 ; 1 ; 2 ; 4 ; 10 ; 100 \) (i.e. \( \zeta = 50 ; 5 ; 2 ; 1 ; 0.5 ; 0.25 ; 0.125 ; 0.05 ; 0.005 \)).

Damping ratio \( \zeta \)

Damping ratio \( \zeta \) is generally used in the case of low and high-pass filter (Low Q) when Q is used in the case of narrow band-pass filter, resonator and oscillator (High Q).

\[
\zeta = \frac{1}{2Q}
\]

(1.20)

The more damping the filter, the flatter its response is and likewise, the less damping the filter, the sharper its response is:

- \( \zeta < 1 \) → steep cutoff
- \( \zeta = 1/\sqrt{2} = Q \) → -3dB attenuation at \( f_c \) (as for 1st order)
- \( \zeta = 1 \) → critical damping
- \( \zeta > 1 \) → slow cutoff

Expression 1.14 may now be rewritten using damping factor:

\[
H_{\text{LCR}} = \frac{j R C \omega}{1 + j R C \omega - L C \omega^2} = \frac{j 2\zeta \frac{\omega}{\omega_0} - \omega^2}{1 + j 2\zeta \frac{f}{f_0} - \frac{f^2}{f_0^2}}
\]

(1.21)
1.3 Cascading filter stages

Circuit analysis by applying Kirchhoff’s laws (as before) is usually used for first and second order filter. For a higher order filters, network synthesis approach may be used. A polynomial equation expresses the filtering requirement. Each first and second order filter elements are then defined from continued-fraction expansion of the polynomial expression. In practice, to avoid saturation, highest Q stage is placed at the end of the network.

![Diagram of cascading filter stages](image)

Figure 1.10: Cascading filter stages for higher-order filters.

It exists different type of polynomial equations from which the filter is mathematically derived. These type of filters are Butterworth, Bessel, Chebyshev, inverse Chebyshev, elliptic Cauer, Bessel, optimum Legendre, etc.

- **Butterworth** filter is known as the maximally-flat filter as regards to the flatness in the pass-band. The attenuation is simply -3 dB at the cutoff frequency; above, the slope is -20 dB/dec per order (n).

- **Chebyshev** filter has a steeper rolloff\(^*\) just after the cutoff frequency but ripple in the pass-band. The cutoff frequency is defined as the frequency at which the response falls below the ripple band\(^†\). For a given filter order, a steeper cutoff can be achieved by allowing more ripple in the pass-band (Chebyshev filter transient response shows overshoots).

- **Bessel** filter is characterized by linear phase response. A constant-group delay is obtained at the expense of pass-band flatness and steep rolloff. The attenuation is -3 dB at the cutoff frequency.

- **elliptic Cauer** (non-polynomials) filter has a very fast transition between the pass-band and the stop-band. But it has ripple behavior in both the passband and the stop-band (not studied after).

- **inverse Chebyshev - Type II** filter is not as steeper rolloff than Chebychev but it has no ripple in the pass-band but in the stop band (not studied after).

- **optimum Legendre** filter is a tradeoff between moderate rolloff of the Butterworth filter and ripple in the pass-band of the Chebyshev filter. Legendre filter exhibits the maximum possible rolloff consistent with monotonic magnitude response in the pass-band.

---

\(^*\)rolloff = transition from the pass band to the stop band.

\(^†\)The cutoff frequency of a Tchebyshev filter is not necessarily defined at -3 dB. \(f_c\) is the frequency value at which the filter transfer function is equal to \(\frac{1}{\sqrt{1 + \epsilon^2}}\) but continues to drop into the stop band. \(\epsilon\) is the ripple factor. Chebyshev filter is currently given for a given \(\epsilon\) \((20 \log \sqrt{1 + \epsilon})\) in [dB].
1.3.1 Polynomial equations

Filters are syntheses by using a $H_0$ DC gain and a polynomial equations $P_n$, with $n$ the order of the equation, and so, of the filter. The transfer function of a synthesized low-pass filter is $H(s) = \frac{H_0}{P_n\left(\frac{s}{\omega_c}\right)}$ with $\omega_c$ the cutoff angular frequency and $s = j\omega$ 

The roots of these polynomials occur on a circle of radius $\omega_c$ at equally spaced points in the $s$ plane:

![Figure 1.11: Pole locations of 1st, 2nd, 3rd, 4th and 5th order Butterworth filter.](image)

Poles of a $H(s)H(-s) = \frac{H_0^2}{1 + \left(\frac{s}{\omega_c}\right)^2}$ low pass filter transfer function module are specified by:

$$\frac{-s^2}{\omega_c^2} = (-1)^{\frac{1}{2}n} e^{j\frac{2x-1}{2}n\pi} \text{ with } x = 1, 2, 3, \ldots, n$$

(1.23)

The denominator of the transfer function may be factorized as:

$$H(s) = \frac{H_0}{\prod_{x=1}^{n} \frac{s-x}{\omega_c}}$$

(1.24)

The denominator of equation 1.24 is a Butterworth polynomial in $s$. Butterworth polynomials are usually expressed with real coefficients by multiplying conjugate poles. The normalized Butterworth polynomials has the form:

$$B_0 = 1$$

$$B_1 = s + 1$$

$$B_n = \prod_{x=1}^{\frac{n}{2}} \left[ s^2 - 2s \cos\left(\frac{2x + n - 1}{2n}\pi\right) + 1 \right] \text{ n is even}$$

$$= (s + 1) \prod_{x=1}^{\frac{n-1}{2}} \left[ s^2 - 2s \cos\left(\frac{2x + n - 1}{2n}\pi\right) + 1 \right] \text{ n is odd}$$

(1.25)

Second order Butterworth filter correspond to the particular case where $Q = \zeta = 1/\sqrt{2} \approx 0.71$. Indeed, from equation 1.25 and expressing the Butterworth polynomial as the denominator of the equation 1.19, it is easy to determined for $n = 2$ that:

$$\frac{1}{Q} = 2\cos\left(\frac{2 + 2 - 1}{2\times\frac{3n}{4}}\pi\right) = \sqrt{2} \approx 1.41 \text{ with } Q = \frac{1}{\sqrt{2}} \text{ (Eq. 1.20).}$$
1.3. CASCADING FILTER STAGES

Chebyshev polynomials

Chebyshev polynomials are obtained by using expression 1.26:

\[
P_n = T_n = \begin{cases} \cos(n \arccos(\omega)) & |\omega| \leq 1 \\ \cosh(n \arccosh(\omega)) & |\omega| \geq 1 \end{cases}
\] (1.26)

where the hyperbolic cosine function \( \cosh(x) = \cos(jx) = e^x + e^{-x} \). From the two first values \( T_0 = 1 \) and \( T_1 = \omega \), Chebyshev polynomials \( T_n(\omega) \) could be recursively obtained by using expression 1.27:

\[
T_0 = 1 \\
T_1 = \omega \\
T_n = 2\omega T_{n-1} - T_{n-2} \quad \begin{cases} T_2 = 2\omega^2 - 1 \\ T_3 = 4\omega^3 - 3\omega \\ T_4 = 8\omega^4 - 8\omega^2 + 1 \\ \vdots \end{cases}
\] (1.27)

Chebyshev low-pass filter frequency response is generally obtained by using a slightly more complex expression than for a Butterworth one:

\[
|H(s)| = \frac{H'_0}{\sqrt{1 + \epsilon^2 T_n^2(\omega_c/\omega)}}
\] (1.28)

where \( \epsilon \) is the ripple factor. Even if \( H'_0 = 1 \), magnitude of a Chebyshev low-pass filter is not necessarily equal to 1 at low frequency (\( \omega = 0 \)). Gain will alternate between maxima at 1 and minima at \( \frac{1}{\sqrt{1 + \epsilon^2}} \).

\[
T_n(\omega_c/\omega = 0) = \begin{cases} \pm 1 & n \text{ is even} \\ 0 & n \text{ is odd} \end{cases} \quad \Rightarrow \quad H(\omega/\omega_c = 0) = \begin{cases} \frac{1}{\sqrt{1 + \epsilon^2}} & n \text{ is even} \\ \frac{1}{\sqrt{1 + \epsilon^2}} & n \text{ is odd} \end{cases}
\] (1.29)

At the cutoff angular frequency \( \omega_c \), the gain is also equal to \( \frac{1}{\sqrt{1 + \epsilon^2}} \) (but \( \forall n \)) and, as the frequency increases, it drops into the stop band.

\[
T_n(\omega/\omega_c = 1) = \pm 1 \quad \forall n \quad \Rightarrow \quad H(\omega/\omega_c = 1) = \pm \frac{1}{\sqrt{1 + \epsilon^2}} \quad \forall n
\] (1.30)

Finally, conjugate poles \( s_x \) (equation 1.31 \(^1\)) of expression 1.28 are obtained by solving equation \( 0 = 1 + \epsilon^2 T_n^2 \):

\[
s_x = \sin\left(\frac{2x - 1}{n} \frac{1}{2\pi}\right) \sinh\left(\frac{1}{n} \arcsinh\frac{1}{\epsilon}\right) + j \cos\left(\frac{2x - 1}{n} \frac{1}{2\pi}\right) \cosh\left(\frac{1}{n} \arcsinh\frac{1}{\epsilon}\right)
\] (1.31)

Using poles, transfer function of a Chebyshev low-pass filter is rewritten as equation 1.28:

\[
H(s) = \begin{cases} \frac{1}{\sqrt{1 + \epsilon^2}} & n \text{ is even} \\ \frac{1}{\sqrt{1 + \epsilon^2}} & n \text{ is odd} \end{cases}
\] (1.32)

\(^*\epsilon = 1\) for the other polynomials filter and is then not represented

\(^1\)Poles are located on a centered ellipse in \( s \) plane; with real axis of length \( \sqrt{\frac{1}{2\pi n} \arcsinh\frac{1}{\epsilon}} \) and imaginary axis of length \( \sqrt{\frac{1}{2\pi n} \arcsinh\frac{1}{\epsilon}} \).
1. FILTERS

1.3. CASCADING FILTER STAGES

Bessel polynomials

Bessel polynomials are obtained by using expression 1.33:

\[ P_n = \theta_n = \sum_{x=0}^{n} \frac{s^x (2n-x)!}{2^n x! (n-x)!} \]

\[ \begin{align*}
\theta_1 &= s + 1 \\
\theta_2 &= s^2 + 3s + 3 \\
\theta_3 &= s^3 + 6s^2 + 15s + 15 \\
\ldots
\end{align*} \tag{1.33} \]

Bessel low-pass filter frequency response is given by expression 1.34 and is also given for \( n = 2 \) (delay normalized second-order Bessel low-pass filter).

\[ \frac{\theta_n(0)}{\theta_n \left( \frac{s}{\omega_c} \right)} \rightarrow \begin{array}{c}
n = 2 \\
3 \left( \frac{s}{\omega_c} \right)^2 + 3 \frac{s}{\omega_c} + 1 \rightarrow \frac{1}{\frac{3}{5} \left( \frac{s}{\omega_c} \right)^2 + \frac{s}{\omega_c} + 1} \end{array} \tag{1.34} \]

However, Bessel polynomials \( \theta_n \) have been normalized to unit delay at \( \frac{s}{\omega_c} = 0 \) (delay normalized) and are not directly usable for classical cutoff frequency at -3 dB standard (frequency normalized).

To compare this polynomials to the other one, the table 1.2 gives BCF factors for converting Bessel filter parameters to 3 dB attenuation at \( \frac{s}{\omega_c} = 1 \). These factors were used in preparing the frequency normalized tables given on Appendix I.

<table>
<thead>
<tr>
<th>( n )</th>
<th>BCF</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>1.3616</td>
</tr>
<tr>
<td>3</td>
<td>1.7557</td>
</tr>
<tr>
<td>4</td>
<td>2.1139</td>
</tr>
<tr>
<td>5</td>
<td>2.4274</td>
</tr>
<tr>
<td>6</td>
<td>2.7034</td>
</tr>
<tr>
<td>7</td>
<td>2.9517</td>
</tr>
<tr>
<td>8</td>
<td>3.1796</td>
</tr>
<tr>
<td>9</td>
<td>3.3917</td>
</tr>
</tbody>
</table>

Table 1.2: Bessel conversion factor - BCF

By using BCF factor and for \( n = 2 \) we finally see in expression 1.35 the frequency response of a second order Bessel low pass filter:

\[ H_2 = \frac{1}{BCF^2 / 3 \left( \frac{s}{\omega_c} \right)^2 + BCF \frac{s}{\omega_c} + 1} \approx \frac{1}{0.618 \left( \frac{s}{\omega_c} \right)^2 + 1.3616 \frac{s}{\omega_c} + 1} \tag{1.35} \]

Module and phase are deduced from the equation 1.35:

\[ |H_2| = \frac{1}{\sqrt{\left( 1 - 0.618 \frac{\omega^2}{\omega_c^2} \right)^2 + \left( 1.3616 \frac{\omega}{\omega_c} \right)^2}} \]

\[ \phi = \arg(H_2) = -\arctan \left( \frac{1.3616 \frac{\omega}{\omega_c}}{1 - 0.618 \frac{\omega^2}{\omega_c^2}} \right) \tag{1.36} \]

Bessel filter is characterized by a linear phase response. Group delay could be studied by calculating:

\[ \tau_g = -\frac{d\phi}{d\omega} \tag{1.37} \]

Legendre polynomials

From the two first values \( P_0(x) = 1 \) and \( P_1(x) = x \), (as for Chebyshev) Legendre polynomials \( P_n(\omega^2) \) could be recursively obtained by using expression 1.38:
1.3. CASCADING FILTER STAGES

Filter tables could give complex roots or normalized polynomials coefficients $c_1$, $c_2$, $c_n$ with $P_n = c_n s^n + c_{n-1} s^{n-1} + \cdots + c_1 s + c_0$. However, more currently filter tables show factorized polynomials or directly normalized cutoff frequency (Scaling Factor - SF) and quality factor (Q) of each of stages for the particular filter being designed.

1.3.2 Filter Tables

Filter tables could give complex roots or normalized polynomials coefficients $c_0$, $c_1$, $c_n$ with $P_n = c_n s^n + c_{n-1} s^{n-1} + \cdots + c_1 s + c_0$. However, more currently filter tables show factorized polynomials or directly normalized cutoff frequency (Scaling Factor - SF) and quality factor (Q) of each of stages for the particular filter being designed.

**Remark** Some tables are now given using a Butterworth low-pass filter example.
Roots table

Some filter tables give complex roots of polynomials. Table 1.3 shows roots of Butterworth polynomials (they are obtained by using equation 1.25).

<table>
<thead>
<tr>
<th>order n</th>
<th>σ</th>
<th>jω</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-1</td>
<td>0</td>
</tr>
<tr>
<td>2</td>
<td>-0.7071</td>
<td>±0.7071</td>
</tr>
<tr>
<td>3</td>
<td>-0.5</td>
<td>±0.866</td>
</tr>
<tr>
<td></td>
<td>-1</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>-0.3827</td>
<td>±0.9239</td>
</tr>
<tr>
<td></td>
<td>-0.9239</td>
<td>±0.3827</td>
</tr>
<tr>
<td>5</td>
<td>-0.309</td>
<td>±0.951</td>
</tr>
<tr>
<td></td>
<td>-0.809</td>
<td>±0.5087</td>
</tr>
<tr>
<td></td>
<td>-1</td>
<td>0</td>
</tr>
<tr>
<td>6</td>
<td>-0.2588</td>
<td>±0.9659</td>
</tr>
<tr>
<td></td>
<td>-0.7071</td>
<td>±0.7071</td>
</tr>
<tr>
<td></td>
<td>-0.9659</td>
<td>±0.2588</td>
</tr>
</tbody>
</table>

Table 1.3: Butterworth polynomials complex roots.

This table is also an indication of pole locations (in s plane) of low-pass filter having Butterworth polynomials as a transfer function denominator. Notice that σ is always negative (stability condition).

Polynomials coefficients table

An other table, concerning polynomials, shows directly coefficients \( c_x \) of polynomials as shown in table 1.4 for Butterworth polynomials \( P_n = B_n = \sum_{x=0}^{n} c_x s^x = c_n s^n + c_{n-1} s^{n-1} + \cdots + c_1 s + c_0 \).

<table>
<thead>
<tr>
<th>n</th>
<th>( c_0 )</th>
<th>( c_1 )</th>
<th>( c_2 )</th>
<th>( c_3 )</th>
<th>( c_4 )</th>
<th>( c_5 )</th>
<th>( c_6 )</th>
<th>( c_7 )</th>
<th>( c_8 )</th>
<th>( c_9 )</th>
<th>( c_{10} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>1.41</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>2</td>
<td>2</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>2.61</td>
<td>3.41</td>
<td>2.61</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>1</td>
<td>3.24</td>
<td>5.24</td>
<td>5.24</td>
<td>3.24</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>1</td>
<td>3.86</td>
<td>7.46</td>
<td>9.14</td>
<td>7.46</td>
<td>3.86</td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>1</td>
<td>4.49</td>
<td>10.1</td>
<td>14.59</td>
<td>14.59</td>
<td>10.1</td>
<td>4.49</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>1</td>
<td>5.13</td>
<td>13.14</td>
<td>21.85</td>
<td>25.69</td>
<td>21.85</td>
<td>13.14</td>
<td>5.13</td>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>1</td>
<td>5.76</td>
<td>16.58</td>
<td>31.16</td>
<td>41.99</td>
<td>41.99</td>
<td>31.16</td>
<td>16.58</td>
<td>5.76</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>6.39</td>
<td>20.43</td>
<td>42.8</td>
<td>64.88</td>
<td>74.23</td>
<td>64.88</td>
<td>42.8</td>
<td>20.43</td>
<td>6.39</td>
<td>1</td>
</tr>
</tbody>
</table>

Table 1.4: Butterworth polynomials coefficients \( c_x \). \( P_n = B_n = \sum_{x=0}^{n} c_x s^x = c_n s^n + c_{n-1} s^{n-1} + \cdots + c_1 s + c_0 \).

However, polynomials are generally factored in terms of \( 1^{st} \) and \( 2^{nd} \) order polynomials; particularly to build cascading \( 1^{st} \) and \( 2^{nd} \) order filters.

Factored polynomials table

To cascade \( 1^{st} \) and \( 2^{nd} \) order filters (filter synthesis), a more useful table gives a factored representation of polynomials as the Butterworth quadratic factors in Table 1.5.
1.3. CASCADING FILTER STAGES

<table>
<thead>
<tr>
<th>n</th>
<th>( P_n = B_n )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>( s + 1 )</td>
</tr>
<tr>
<td>2</td>
<td>( s^2 + 1.4142s + 1 )</td>
</tr>
<tr>
<td>3</td>
<td>( (s + 1)(s^2 + s + 1) )</td>
</tr>
<tr>
<td>4</td>
<td>( (s^2 + 0.7654s + 1)(s^2 + 1.8478s + 1) )</td>
</tr>
<tr>
<td>5</td>
<td>( (s + 1)(s^2 + 0.618s + 1)(s^2 + 1.618s + 1) )</td>
</tr>
<tr>
<td>6</td>
<td>( (s^2 + 0.5176s + 1)(s^2 + 1.4142s + 1)(s^2 + 1.9319s + 1) )</td>
</tr>
<tr>
<td>7</td>
<td>( (s + 1)(s^2 + 0.445s + 1)(s^2 + 1.247s + 1)(s^2 + 1.618s + 1) )</td>
</tr>
<tr>
<td>8</td>
<td>( (s^2 + 0.3902s + 1)(s^2 + 1.1111s + 1)(s^2 + 1.6629s + 1)(s^2 + 1.9616s + 1) )</td>
</tr>
<tr>
<td>9</td>
<td>( (s + 1)(s^2 + 0.3473s + 1)(s^2 + s + 1)(s^2 + 1.5321s + 1)(s^2 + 1.8794s + 1) )</td>
</tr>
<tr>
<td>10</td>
<td>( (s^2 + 0.3129s + 1)(s^2 + 0.908s + 1)(s^2 + 1.4142s + 1)(s^2 + 1.782s + 1)(s^2 + 1.9754s + 1) )</td>
</tr>
</tbody>
</table>

Table 1.5: Butterworth polynomials quadratic factors.

Cutoff frequencies and quality factor table

Finally, another useful table for filter designer is table which gives directly cutoff frequency and quality factor of each \( 2^{\text{nd}} \) order filter. Table 1.6 gives frequency scaling factor and quality factor of Butterworth low-pass filter. A first order stage is just defined by a normalized cutoff frequency (SF) without quality factor (Q). Scaling factor is the ratio between the cutoff frequency of the considering stage and the cutoff frequency of the overall cascaded filter. So, finally the polynomial is expressed as in equation 1.42.

\[
2^{\text{nd}} \text{order polynomial form} \rightarrow P_n = 1 + j \frac{f}{Q \text{SF} f_c} - \left( \frac{f}{\text{SF} f_c} \right)^2
\]  

*In the particular case of Butterworth filter, the frequency scaling factor (SF) is always equal to one*.

<table>
<thead>
<tr>
<th>order n</th>
<th>1(^{\text{st}} ) stage</th>
<th>2(^{\text{nd}} ) stage</th>
<th>3(^{\text{rd}} ) stage</th>
<th>4(^{\text{th}} ) stage</th>
<th>5(^{\text{th}} ) stage</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>SF</td>
<td>Q</td>
<td>SF</td>
<td>Q</td>
<td>SF</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>0.7071</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>0.5412</td>
<td>1</td>
<td>1.3065</td>
<td>1</td>
</tr>
<tr>
<td>5</td>
<td>1</td>
<td>0.618</td>
<td>1</td>
<td>1.6181</td>
<td>1</td>
</tr>
<tr>
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<td>1</td>
<td>0.5177</td>
<td>1</td>
<td>0.7071</td>
<td>1</td>
</tr>
<tr>
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<td>1</td>
<td>0.8019</td>
<td>1</td>
</tr>
<tr>
<td>8</td>
<td>1</td>
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<td>1</td>
<td>0.6013</td>
<td>1</td>
</tr>
<tr>
<td>9</td>
<td>1</td>
<td>0.5321</td>
<td>1</td>
<td>0.6527</td>
<td>1</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>0.5062</td>
<td>1</td>
<td>0.5612</td>
<td>1</td>
</tr>
</tbody>
</table>

Table 1.6: Butterworth normalized cutoff frequency (Scaling Factor - SF) and quality factor (Q) for each stages.

1.3.3 The use of filter tables

To build, for example, a second order Butterworth low-pass filter we need to do the transfer function

\[
H(s) = \frac{H_0}{P_n(s)}
\]

where \( P_n \) is a second order Butterworth polynomials i.e. \( P_n = B_2 \).

*each 1\(^{\text{st}} \) and 2\(^{\text{nd}} \) order filter have the same cutoff frequency than the Butterworth cascading filter has at the end. This is not the case for other polynomials filter as Chebyshev for which SF is often different than 1.
Table 1.3 could be used to write $B_2 = \left( \frac{s}{\omega_c} - r_1 \right) \left( \frac{s}{\omega_c} - r_1^* \right)$ with $r_1$ and $r_1^*$ the two conjugate roots $-0.7071 \pm j0.7071$. The transfer function of the Butterworth low-pass filter could be expressed as equation 1.43.

$$H(s) = \frac{H_0}{B_2 \left( \frac{s}{\omega_c} \right)} = \frac{H_0}{\left( \frac{s}{\omega_c} + 0.7071 - j0.7071 \right) \left( \frac{s}{\omega_c} + 0.7071 + j0.7071 \right)}$$  \hspace{1cm} (1.43)

The denominator development of the expression 1.43 gives a quadratic form (expression 1.44) which clearly shows Butterworth polynomial coefficients given on table 1.4 and quadratic factors of table 1.5. It is also clear that expression 1.44 is similar to a classical representation of a transfer function with quality factor where $SF$ and $Q$ are finally what we can directly obtain from the table 1.6.

$$H(s) = \frac{H_0}{\left( \frac{s}{\omega_c} \right)^2 + 1.41 \frac{s}{\omega_c} + 1} = \frac{H_0}{1 + \left( \frac{1}{Q} \frac{\omega}{\omega_c} \right)^2 - \frac{\omega^2}{\omega_c^2}}$$  \hspace{1cm} with \hspace{1cm} \begin{align*}
SF &= 1 \\
Q &\approx \sqrt{1.41} \approx 0.7071
\end{align*}  \hspace{1cm} (1.44)

Bode diagram of this low pass filter could be expressed as equation 1.45 and plotted as figure 1.12.

$$|H(\omega)| = \frac{1}{\sqrt{1 - \left( \frac{\omega}{\omega_c} \right)^2 + 1.41 \left( \frac{\omega}{\omega_c} \right)^2}}$$  \hspace{1cm} with \hspace{1cm} $H_0 = 1$

$$\phi(\omega) = \arg(H) = -\arctan \frac{1.41 \frac{\omega}{\omega_c}}{1 - \left( \frac{\omega}{\omega_c} \right)^2}$$  \hspace{1cm} (1.45)

Figure 1.12: Bode plot of a second order Butterworth low-pass filter.

### 1.3.4 Conversion from low-pass filter

#### Low-pass to high-pass filter

Filter tables give polynomials for low and high-pass filter. To obtain a high pass filter, a first order low pass filter transfer function $H_0 \frac{H_0}{\omega_c + \omega_c \omega}$ becomes $H_\infty \left( \frac{H_0}{\omega_c} \right)^2$; and a second order low pass filter transfer function $H_0 \frac{H_0}{\omega_c + \omega_c \omega + \omega_c \omega}$ becomes $H_\infty \left( \frac{H_0}{\omega_c} \right)^2$. Figure 1.13 shows low and high pass filter with $H_0$ and $H_\infty$.

\*In practice, there is always a frequency limitation which leads to a low-pass filtering. Consequently, an ideal high-pass filter never exists and $H_\infty \rightarrow 0$. So, in the case of real high pass filter, $H_\infty$ corresponds more to the gain just after the cut-off frequency than at infinity.
1.3. CASCADING FILTER STAGES

1. FILTERS

\[ H_{LP_1} = \frac{H_0}{c_0 + c_1 s} \quad \Rightarrow \quad H_{HP_1} = \frac{H_\infty}{c_0 + c_1 / s} \]

\[ H_{LP_2} = \frac{H_0}{c_0 + c_1 s + c_2 s^2} \quad \Rightarrow \quad H_{HP_2} = \frac{H_\infty}{c_0 + c_1 / s + c_2 / s^2} \]

(1.46)

Low to high pass filter conversion: \( s \Rightarrow s^{-1} \)

Band-pass filter For band-pass filter, it exists specific tables which give specific coefficients given for different bandwidth (BW). However, a low pass filter transfer function could be converted in band-pass filter by replacing \( s \) by \( \frac{f_0}{BW} (s + s^{-1}) \); where \( \frac{f_0}{BW} \) is equal to the quality factor Q.

Low to band-pass filter conversion: \( s \Rightarrow Q (s + s^{-1}) \)

Band-reject filter A low pass filter transfer function is converted in band-reject filter by replacing \( s \) by \( \frac{1}{BW} (s + s^{-1}) \).

Low to band-reject filter conversion: \( s \Rightarrow Q^{-1} (s + s^{-1})^{-1} \)

Transposition A synthesis of different transpositions are reported in the table 1.7.

<table>
<thead>
<tr>
<th>Conv.</th>
<th>Filter type</th>
<th>Low-pass</th>
<th>High-pass</th>
<th>Band-pass</th>
<th>Band-reject</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Normalized complex frequency</td>
<td>( s )</td>
<td>( s^{-1} )</td>
<td>( Q (s + s^{-1}) )</td>
<td>( Q^{-1} (s + s^{-1})^{-1} )</td>
</tr>
<tr>
<td></td>
<td>First order transfert function</td>
<td>( \frac{1}{c_0 + c_1 s} )</td>
<td>( \frac{1}{c_0 + c_1 s^2} )</td>
<td>( \frac{1}{c_0 + c_1 / s} )</td>
<td>( \frac{1}{c_0 + c_1 / s^2} )</td>
</tr>
<tr>
<td></td>
<td>Second order transfert function</td>
<td>( \frac{1}{c_0 + c_1 s + c_2 s^2} )</td>
<td>( \frac{1}{c_0 + c_1 / s + c_2 / s^2} )</td>
<td>( \frac{1}{c_0 + c_1 / s} )</td>
<td>( \frac{1}{c_0 + c_1 / s^2} )</td>
</tr>
</tbody>
</table>

Table 1.7: Filter normalized transposition.

*The transfer function is obtained by using filter table after determination of type and order. The next step is to determine a circuit to implement these filters.*
1. FILTERS

1.4 FILTER SYNTHESIS

1.4 Filter synthesis

It exists different topologies of filter available for filter synthesis. The most often used topology for an active realization is Sallen-Key topology (Fig. 1.14).

1.4.1 Sallen-Key topology

Sallen-Key electronic circuit (Fig. 1.14) is used to implement second order active filter.

\[ H_{SK} = \frac{H_0}{1 + \left[ \frac{Z_1 Z_2}{Z_4} + (1 - H_0) \frac{Z_1 Z_3}{Z_4 Z_3} \right]} \]

(Sallen-Key low-pass filter)

A low-pass filter is easily obtained from this circuit. Figure 1.15 shows a Sallen-Key low-pass filter.

\[ H_{SKLP} = \frac{H_0}{1 + \left( \frac{R_1 + R_2}{R_1} \right) C_2 + R_1 C_1 \left( 1 - H_0 \right)} s + R_1 R_2 C_1 C_2 s^2 \]

\[ = \frac{H_0}{c_0 + c_1 s + c_2 s^2} \]

with

\[ SF_{fc} = \frac{1}{2 \pi \sqrt{R_1 R_2 C_1 C_2}} \]

\[ Q = \sqrt{\frac{R_1 + R_2}{R_1 R_2 C_1 C_2}} \]

This second order Sallen-Key filter can be used to realize one complex-pole pair in the transfer function of a low-pass cascading filter. Values of the Sallen-Key circuit could be chosen to correspond to polynomials coefficients (as Butterworth, Chebyshev or Bessel …).
Sallen-Key high-pass filter

To transform a low-pass filter to a high-pass filter, all resistors are replaced by capacitors and capacitors by resistors:

\[ H_{SK,HP} = \frac{R_1 R_2 C_1 C_2 s^2}{1 + \left[ R_1 (C_1 + C_2) + R_2 C_2 (1 - H_0) \right] s + R_1 R_2 C_1 C_2 s^2} \]

The transfer function of this Sallen-Key high-pass filter is given by equation (1.49).

\[ H_{SK,HP} = \frac{H_0}{1 + \frac{1}{C_0 s^2}} \]

Sallen-Key band-pass filter

Band-pass filter could be obtained by placing in series a high and a low-pass filter as illustrated in figure 1.17. The cut-off frequency of the low-pass filter needs to be higher than the high-pass one; unless you want to make a resonant filter.

\[ SFf_c = \frac{1}{2\pi \sqrt{R_1 R_2 C_1 C_2}} \]

\[ Q = \frac{\sqrt{R_1 R_2 C_1 C_2}}{R_1 (C_1 + C_2) + R_2 C_2 (1 - H_0)} \]

Figure 1.16: Sallen-Key high-pass filter.

The transfer function of this Sallen-Key high-pass filter is given by equation (1.49).

\[ H_{SK,HP} = \frac{H_0}{1 + \frac{1}{C_0 s^2}} \]

But we can also found more complicated band-pass filter as figure 1.19 based on voltage-controlled voltage-source (VCVS) filter topology which gives the transfer function expressed in equation 1.50.
1. FILTERS

1.4. FILTER SYNTHESIS

Figure 1.19: Voltage-controlled voltage-source (VCVS) filter topology band-pass filter.

\[
H_{VCVS\text{BP}} = H_0 \frac{R_2 R_3 C_2}{R_1 + R_3} \frac{R_3 R_1 s}{R_1 R_3} \frac{R_3 R_1 s + R_2 R_3 + R_2 R_3 (1 - H_0)}{R_1 + R_3} s^2 + R_1 R_3 C_2 C_1 + R_2 R_3 C_2 = H'_{0s} \frac{R_2 R_3 C_2}{R_1 + R_3}
\]

\[
H'_{0s} = H_0 \frac{R_2 R_3 C_2}{R_1 + R_3}
\]

\[
S = \frac{1}{2\pi \sqrt{R C}} \quad Q = \frac{1}{4 - 2H_0}
\]

Sallen-Key band-reject filter

Unlike the band-pass filter, a notch filter cannot be obtained by a series connection of low and high-pass filters. But a summation of the output \(^*\) of a low and a high-pass filter could be a band-reject filter if cut-off frequency of the low-pass filter is lower than the high-pass one. This correspond to paralleling high and low-pass filter.

Band-reject filter could be obtained by placing in parallel a high and a low-pass filter as illustrated in figure 1.20.

Figure 1.20: Paralleling low and high-pass filter for band-reject filtering.

A band-reject filter is usually obtained by using circuit of figure 1.21.

Parameters of this simplified Sallen-Key band reject filter is given by expression 1.51.

\[
S = \frac{1}{2\pi \sqrt{R C}} \quad Q = \frac{1}{4 - 2H_0}
\]

\(^*\)In practice it is not possible to connect together two outputs without precautions.
1.5 Amplitude responses

1.5.1 Filter specifications

The more common filter specification is the roll-off rate which increases with the order \(^*\). It is 20dB/decade per pole for high and low-pass filter; per pair of poles/zeros for band-pass filter. Ripples in pass-band and stop-band need to be also specified. Around a cutoff frequency, these specifications could be also defined by 5 transfer function requirements:

- maximum amplitude \(|H|_{\text{max}}\)
- pass-band cut-off frequency \(f_p\)
- maximum allowable attenuation in the band-pass \(A_{\text{max}}\)
- frequency at which stop-band begins \(f_s\)
- minimum allowable attenuation in the stop-band \(A_{\min}\)

Figure 1.22 lets appear these various parameters in the case of a low pass filter:

\[ |H|_{\text{max}} - |H| \]
\[ |H|_{\text{max}} - A_{\text{max}} \]
\[ |H|_{\text{max}} - A_{\min} \]

\[ f_p \]
\[ f_s \]

Figure 1.22: Filter amplitude response limits.

\(^*\) The order of the filter is linked to the number of elements (first and second order filter) used in the network (Fig. 1.10).

\(^\dagger\) In the case of low-pass filter, \(|H|_{\text{max}} = H_0\) the DC gain and \(H_\infty\) in the case of high-pass filter \(|H|_{\text{max}}\) is generally equal to 1.

\(^\ddagger\) For a \(-3\text{dB}\) attenuation \(A_{\text{max}}, f_p\) is the cut-off frequency usually noted \(f_c\).

\(^\S\) \(A_{\min} = 3\text{dB}\) in the case of Butterworth or Bessel filter and \(A_{\max} = \frac{1}{\sqrt{1 + \epsilon^2}}\) for Chebyshev filter.
1.5.2 Amplitude response curves

Cebyshev filter has a steeper rolloff near the cutoff frequency when compared to Butterworth and Bessel filters. While, Bessel not exhibit a frequency dependance phase shift as Butterworth and Chebyshev filter. Butterworth is a good compromise as regards to the rolloff, while having a maximally-flat frequency response. Finally, Legendre filter has the steeper rollof without ripple in the band pass. These kind of comparison between Butterworth, Chebyshev, Bessel and Legendre filter is outlined by figure 1.23, tables 1.8 and 1.9.

![Image of filter comparison]

Table 1.8: Butterworth, Chebyshev, Bessel and Legendre filter advantages/disadvantages.

<table>
<thead>
<tr>
<th>Filter</th>
<th>Properties</th>
<th>Advantages</th>
<th>Disadvantages</th>
</tr>
</thead>
<tbody>
<tr>
<td>Butterworth</td>
<td>Maximal flat magnitude response in the pass-band</td>
<td>Overshoot and ringing in step response</td>
<td></td>
</tr>
<tr>
<td>Chebyshev</td>
<td>Better attenuation beyond the pass-band</td>
<td>Ripple in pass-band. Even more ringing in step response</td>
<td></td>
</tr>
<tr>
<td>Bessel</td>
<td>Excellent step response</td>
<td>Even poorer attenuation beyond the pass-band</td>
<td></td>
</tr>
<tr>
<td>Legendre</td>
<td>Better rolloff without ripple in pass-band</td>
<td>Pass-band not so flat</td>
<td></td>
</tr>
</tbody>
</table>

Table 1.9: Butterworth, Chebyshev, Bessel and Legendre filter comparison.

The response of Butterworth, Chebyshev, Bessel and Legendre low-pass filter is compared. To do this, polynomial tables given in Appendix A are directly used as the low-pass filter denominator transfer function. Figure 1.24 shows for example the 5th order of Butterworth, Chebyshev, Bessel and Legendre polynomials as a denominator; only the module (expression 1.52) is plotted.
1.5. AMPLITUDE RESPONSES

1. FILTERS

\[ P_{5\text{Butterworth}} = (s + 1)(s^2 + 0.618s + 1)(s^2 + 1.618s + 1) \]

\[ P_{5\text{Chebyshev}_{3dB}} = (5.6328s + 1)(2.6525s^2 + 0.7619s + 1)(1.0683s^2 + 0.1172s + 1) \]

\[ P_{5\text{Bessel}} = (0.665s + 1)(0.3245s^2 + 0.6215s + 1)(0.4128s^2 + 1.1401s + 1) \]

\[ P_{5\text{Legendre}} = (2.136s + 1)(1.0406s^2 + 0.3196s + 1)(2.0115s^2 + 1.5614s + 1) \]

\[
|P_S| = \sqrt{\left(\frac{f^2}{f_c^2} + 1\right)\left(\frac{f^2}{f_c^2} + 1\right)^2 + 0.618^2} \left(\frac{f^2}{f_c^2} + 1\right)^2 + 1.618^2}\left(\frac{f^2}{f_c^2} + 1\right)
\]

It clearly appears on figure 1.24 differences, concerning frequency response, between Butterworth, Chebyshev, Bessel and Legendre filters. All these filters have been plotted with a cutoff frequency referred to a -3dB attenuation. Thereby, despite the same order, Chebyshev filter has the faster rolloff, then come Legendre, Butterworth and the slower is the Bessel filter. **Far after the cutoff frequency, the slope becomes the same for all 5\text{th} order filters (\propto f^{-5}) but not the attenuation** for a given \( \frac{f}{f_c} \).

![Figure 1.24: Frequency response of a Butterworth, Chebyshev, Bessel and Legendre 5\text{th} order low-pass filter around cutoff frequency and far after it. Dashed line represent a \( f^{-5} \) slope for comparison to 5\text{th} order filter rolloff.](image)

The drawback of a fast rolloff is the increasing of the transit time to step response as shown in figure 1.25. Time response of a Chebyshev filter clearly shows oscillations which increase the settling time*.

**Butterworth frequency response**

Figure 1.26 illustrates the main properties of Butterworth filters which is the flatness in the pass-band ; particularly for high order.

Butterworth attenuation plot on the right side of figure 1.26 could be used to determined the needed order for a given \( A_{\text{min}} \) and \( f_s \) (Fig. 1.22).

*Settling time is the time requires to reach and stay around the final voltage with a specified errors; usually a range of 1%, 2% or 5%.
Chebyshev frequency response

Figure 1.27 shows the ripple in the pass-band of a Chebyshev low-pass filter (3dB) for order from 2 to 5. It also appears that $H_0$ (numerator) is different from 1 for even order. For an even order Chebyshev filter with a ripple factor of 3 dB (which correspond to $\epsilon = 1$), the numerator is equal to $\frac{1}{\sqrt{1+\epsilon^2}} \approx 0.71$.

Figure 1.28 shows more precisely the difference in $H_0$ between odd ($n=5 \rightarrow H_0 = 1$) and even ($n=4 \rightarrow H_0 \approx 0.707$) order. It also illustrates of how it is possible to determine the order of a Chebyshev filter by simply counting the ripple number on the transfer function.

Amplitudes of the ripples in the pass-band is constrained by the $|H|_{\text{max}} - A_{\text{max}}$ and $f_c$ (Fig. 1.22). Sometimes, ripple factor needs to be smaller than 3dB. It is easy to find Chebyshev polynomials table with a ripple factor of 1 dB*, 0.5 dB or 0.1 dB. In Figure 1.29, is plotted the transfer function of a Chebyshev low-pass filter with a ripple factor of 1 dB ($\epsilon = 0.5$) and order going from 2 to 5. The $H_0$ of even order is set at $\frac{1}{\sqrt{1+0.5^2}} \approx 0.894$ as it is shown in figure 1.30.

Finally, a comparison between two Chebyshev low-pass filters with different ripple factor is plotted in figure 1.31. Even if the cutoff frequency is referred to a different level (-1 dB and -3 dB), it appears that the larger the ripple factor, the faster the rolloff.

Bessel frequency response

Figure 1.32 show Bessel low-pass filter transfer function from the 2nd to the 5th order. The rolloff is much slower than for other filters. Indeed, Bessel filter maximizes the flatness of the group delay curve in the pass-band (Fig. 1.33) but not the rolloff. So, for a same attenuation in the stop-band ($A_{\text{min}}$), a higher order is required compared to Butterworth, Chebyshev or Legendre filter.

*Chebyshev polynomials table is given in Appendix A for a ripple factor of 3 and 1 dB
1.5. AMPLITUDE RESPONSES

1. FILTERS

Figure 1.27: Frequency response of a Chebishev ($\epsilon = 1$) low pass filter for $n = 2$ to 5.

Figure 1.28: Zoom in the passband of the frequency response of a Chebishev ($\epsilon = 1$) low-pass filter for $n = 4$ and 5.

Legendre frequency response

To complete this inventory, Legendre low-pass filter frequency response is plotted in figure 1.34 for $n = 2$ to 5.

Legendre filter is characterized by the maximum possible rolloff consistent with monotonic magnitude response in the pass-band. But monotonic does not flat, as we can see in figure 1.35.

As for Chebyshev filter, it is possible to count the number of “ripples” to find the order from a plotted transfer function.
1.6 Switched capacitor filters

A switched capacitor electronic circuit works by moving charges into and out of capacitors when switches are opened and closed. Filters implemented with these elements are termed "switched-capacitor filters".

1.6.1 Switched capacitor

Figure 1.36 gives the circuit of a switched capacitor resistor, made of one capacitor C and two switches $S_1$ and $S_2$ which connect the capacitor with a given frequency alternately to $V_{in}$ and $V_{out}$. Each switching cycle transfers a charge from the input to the output at the switching frequency. When $S_1$ is closed while $S_2$ is open, the charge stored in the capacitor C is $q_{in} = CV_{in}$, when $S_2$ is closed, some of that charge is transferred out of the capacitor, after which the charge that remains in capacitor C is $q_{out} = CV_{out}$.

Thus, the charge moved out of the capacitor to the output is $q_T = q_{in} - q_{out} = C(V_{in} - V_{out})$. Because this charge $q_T$ is transferred each $T_S$, the rate of transfer of charge per unit time is given by expression 1.53.

$$I = \frac{q_T}{T_S} = \frac{C(V_{in} - V_{out})}{T_S}$$

(1.53)

Expression 1.53 gives a link between $V$ and $I$, and then the impedance of the switched capacitor

$q = CV$, $q$ the charge on a capacitor C with a voltage V between the plates.

$T_S$ Periodicity of switch opening and closing.

The rate of flow of electric charge is a current [A].

The impedance of the capacitor could be considered static for a frequency smaller than $\frac{1}{T_S}$. 
1.6. SWITCHED CAPACITOR FILTERS

1.6.2 Switched capacitor filters

Because switching capacitor act as a resistor, switched capacitors can be used instead of resistors in the previous filter circuits (RC, RLC, Sallen-Key ...). A \( R = 10k\Omega \) can be replaced by a switched capacitor following the expression 1.54. Using a switching clock \( f_s = \frac{1}{T_s} = 50kHz \), the capacitor is given by equation 1.55.

\[
R = 10k\Omega \equiv C = \frac{1}{10k\Omega \times 50kHz} = 2nF
\]
A variation of the switching frequency leads to a variation of the equivalent resistance R. If $f_s$ increases, $R = \frac{1}{LC}$ decreases. This link between frequency and equivalent resistance value could be used to modify a filter cutoff frequency by adjusting the switching frequency.

The cutoff frequency of a $RC$ switched capacitor filter (Fig. 1.37) is expressed by equation 1.56.

$$f_c = \frac{1}{2\pi \text{Re} \text{quiv} \times C_2} = \frac{C_1 \times f_s}{2\pi C_2}$$  \hspace{1cm} (1.56)$$

If the switching frequency $f_s$ increases, the cutoff frequency $f_c$ increases too.
1.6. SWITCHED CAPACITOR FILTERS

Figure 1.35: Zoom on the pass-band of the frequency response of a Legendre low-pass filter for $n = 2$ to 5.

\[ V_{in} \rightarrow S_1 \rightarrow S_2 \rightarrow V_{out} \equiv V_{in} \rightarrow R \rightarrow V_{out} \]

Figure 1.36: Equivalence between Resistor and Switched Capacitor.

\[ V_{in} \rightarrow R \rightarrow V_{out} \equiv V_{in} \rightarrow S_1 \rightarrow S_2 \rightarrow V_{out} \]

Figure 1.37: Equivalence between RC filter and switched capacitor filter.
1.7 First order passive filter

Transfer function of the first order filter (Fig. 1.38).

1. Give the expression of the \( \frac{v_{out}(\omega)}{v_{in}(\omega)} \) transfer function.

2. Is it a low or a high-pass filter?

   \( R = 1 \, k\Omega \) and \( L = 1 \, mH \):

3. What is the cutoff frequency?

4. Give the module and the phase of this transfer function as a function of \( f \).

5. Draw the Bode plots of the filter.

6. Same questions for the two following filters:

   \( R = 22 \, k\Omega \) and \( C = 33 \, nF \)

Figure 1.38: First order LR filter.

Figure 1.39: 2 other First order filters.
1.8 Second order passive filter

Transfer function of the second order filter (Fig. 1.40).

\[ L = 1 \text{mH}, R = 1 \Omega \text{ and } C = 100 \text{nF} \]

1. Give the expression of the \( \frac{v_{out}}{v_{in}}(\omega) \) transfer function highlighting the damping factor \( \zeta \).
2. Compute the cutoff frequency and the damping factor
3. Express the module and the phase of this transfer function.
4. Draw the Bode plots of the filter.
5. Is it a low or a high-pass filter?
6. What is the values of R which satisfy \( \zeta = 0.71, \ll 1 \text{ and } \gg 1 \)?
7. Is the cutoff frequency changes with R values?
8. Draw the Bode plots of the filter with \( \zeta = 0.71, \ll 1 \text{ and } \gg 1 \).
9. What is the correspondence between \( \zeta \) and Q ?

![Second order LRC filter](image1)

Figure 1.40: Second order LRC filter.

1.9 Active filter - Sallen-Key topology

Sallen-Key topology is given in Fig. 1.41.

![Sallen-Key generic topology](image2)

Figure 1.41: Sallen-Key generic topology.

Find the transfer function of the Sallen-Key topology using Kirchhoff’s current law:

1. Give the link between \( v_+ \) and \( v_{out} \).
2. Apply the Kirchhoff’s current law to the \( v_+ \) node.
3. Apply the Kirchhoff’s current law to the \( v_+ \) node.
4. Use 1) and 3) to give an expression of \( v_+ \) as a function of \( v_{out} \).
5. Use 2) and 4) to give an expression of \( v_{out} \) as a function of \( v_{in} \).
6. Rearrange equation from 5) to obtain \( \frac{v_{out}}{v_{in}} \) transfer function as in the Lecture.
1. FILTERS

1.10 5\textsuperscript{th} order Butterworth low-pass filter

1. Give the transfer function of a 5\textsuperscript{th} order Butterworth low-pass filter by using polynomials table from Appendix A.

2. What is the number of filter stages required, and the order of each. Give Q and \( SFF_c \) for each second order.

3. Suggest a circuit, using cascading and Sallen-Key topology. Give the expression of each cutoff frequency and quality factor as a function of R and C values.

1.11 4\textsuperscript{th} order Chebyshev (3dB) low-pass filter

• Same question as before, to build a 4\textsuperscript{th} order Chebyshev low-pass filter.

1.12 6\textsuperscript{th} order Bessel high-pass filter

• Same question as before, to build a 6\textsuperscript{th} order Bessel high-pass filter.

1.13 Filter synthesis from template

1.13.1 Low pass-filter synthesis

We search to build a low pass filter to satisfy the following specifications :

• maximum amplitude \(|H|_{\text{max}} = 0 \, dB\)

• pass-band cut-off frequency \(f_c = 5 \, kHz\)

• maximum allowable attenuation in the band-pass \(A_{\text{max}} = 3 \, dB\)

• frequency at which stop-band begins \(f_s = 20 \, kHz\)

• minimum allowable attenuation in the stop-band \(A_{\text{min}} = 40 \, dB\)

The template of this filter is given in figure 1.42.

![Diagram of a low pass filter specifications](image)

Figure 1.42: Low pass filter specifications.
1. What is the minimum filter order needed to satisfy previous constraints. Consider, Butterworth and Chebyshev 1 dB filters. Use plots given in Appendix B to graphically estimate attenuation of different filters.

2. From these 2 filters, what is the one which exhibit a 10% settling time* smaller than 330μs. Use step responses given in Lecture to estimate settling time. For Chebyshev, consider the 1dB response time.

\[ R_0 = 10k\Omega, \omega_c = \frac{1}{R_0\sqrt{C_1C_2}}, H_0 = 1 \text{ and } Q = \frac{\sqrt{C_1C_2}}{2C_2} \]

3. Give the circuit (and the capacitor values, SF and Q) of the filters Butterworth n=4 using Sallen-Key topology (for 2\textsuperscript{nd} order filters) given in figure 1.43.

![Figure 1.43: Sallen-Key 2\textsuperscript{nd} order low-pass filter. R1 = R2 = R0](image)

This circuit is now used to filter a 500 Hz square signal before a 10 kHz digitizer. The filter is needed to avoid aliasing but shall not add distortions.

1.13.2 Removing harmonics frequencies

Saturations and distortions generate unwanted harmonics that we search to suppress by filtering.

1. Consider the distorted signal as a square one (at frequency \( f_{in} \)) and the number 3 harmonic\(^\dagger\) as the main distortion. Suggest filter specifications (in the same manner as figure 1.42) to have the harmonic \( 3 \) 60 dB smaller than fundamental signal.

2. What is the minimum order required for each type of filter (Butterworth, Chebyshev, Bessel, Legendre)?

3. Choose filter which require the smaller order and give circuit from Sallen-Key topology (\( f_0 = f_{in} = 1k\text{Hz} \) and \( R_0 = 10k\Omega \))

---

*Settling time is the time required to get within some specified amount of the final value (10% here) and stay there. This is different from rise time which is the time required to reach 90% of the final value.

\(^\dagger\)Harmonic \( 3 \) is the harmonic at 3 times the fundamental frequency \( f_{in} \)
1.14 Passive filter

![First order filters](image)

Figure 1.44: First order filters.

1. Implement the 2 RC circuits (Fig. 1.44) and measure Bode diagram (amplitude and phase) by using a sine wave (from a function generator) and an oscilloscope. $R = 22k\Omega$ and $C = 33nF$.

2. What type of filters is it? Low or high pass filters?

3. Now, connect in series this two circuit as in figure 1.45. What kind of filter do you obtain?

4. Measure its characteristics in the two cases. Draw the Bode diagram. Comment the difference between the two circuits.

5. Same questions with circuit connected as figure 1.46.

6. Place a voltage follower between the two stages for figure 1.45 and 1.46 circuits (Aop are TL081 biased under ±12 V). Comment.

![First order filters in series](image)

Figure 1.45: First order filters in series.
1.15 Low pass-filter synthesis

We search to build a low pass filter to satisfy the following specifications:

- maximum amplitude $|H|_{\text{max}} = 0 \text{ dB}$
- pass-band cut-off frequency $f_c = 5 \text{ kHz}$
- maximum allowable attenuation in the band-pass $A_{\text{max}} = 3 \text{ dB}$
- frequency at which stop-band begins $f_s = 20 \text{ kHz}$
- minimum allowable attenuation in the stop-band $A_{\text{min}} = 40 \text{ dB}$
- 1% settling time < $330 \mu \text{s}$

Such specifications are satisfy by using a $4^{th}$ order Butterworth filter (Fig 1.48).

1. Implement this circuit (Aop are TL081 biased under ±12 V) and measure Bode diagram (amplitude and phase) by using a sine wave (from a function generator) and an oscilloscope. Add error bars to the graph.

2. We are now considering the phase response. To do this, measure the delay and the phase of the fundamental and the $4^{th}$ first harmonics’ of a 500 Hz square signal. Use a sine wave of 1 V amplitude for each frequencies. Use 2 probes to measure the delay.

3. Determine the 10% settling time.

4. Change the value of the square signal frequency around the cutoff frequency. comment.

**keep the Butterworth filter.**

---

*4th first harmonic of a square wave are $h_3, h_5, h_7$ and $h_9$*
1.16 Removing harmonics frequencies

4\textsuperscript{th} order Chebyshev low pass filter (Fig. 1.49) is used to suppress harmonics of a 1 kHz square signal.

\[ v_{in} \rightarrow 68nF \parallel 47nF \rightarrow 2.2nF \rightarrow 10k\Omega \rightarrow v_{out} \]

\[ 47nF \rightarrow 10k\Omega \rightarrow 33nF \text{ series } 47nF \]

Figure 1.49: Sallen-Key 4\textsuperscript{th} order Chebyshev low-pass filter.

1. Replace capacitors of the Butterworth filter to obtain the Chebyshev filter of figure 1.49. Check quickly performances of the filter: \( f_c \) and \( n \).

2. Measure the attenuation of a sine wave at 1 kHz and at 3 kHz. Give the attenuation (at the output of the filter) of the harmonique\textsubscript{3} as compared to fundamental of a 1 kHz square signal.

3. Trace the Bode plot of the filter.

\[ \text{Disassemble and clean} \]
1.16. REMOVING HARMONICS FREQUENCIES

1. FILTERS
Part II

DCDC Converters
2.1 Introduction

A DC/DC converter is an electronic circuit which converts a Direct Current (DC) source from one voltage level to another. For example, 12 V to 5 V or 12 V to -48 V. Power for a DC/DC converter can come from any suitable DC sources, such as batteries, solar panels, rectifiers and DC generators.

DC/DC converter is a class of switched-mode power supply containing at least two semiconductor switches (a diode and a transistor) and at least one energy storage element, a capacitor, inductor, or both (see for instance the figure 2.3). Filters made of capacitor in combination with inductor reduce output voltage ripple. It is an efficient technique to provide DC voltage as compare to "linear power supplies" presented in figure 2.1.

2.1.1 Advantages/Disadvantages

Pros:

DC/DC converters offer three main advantages compared to linear regulators:

1. Efficiency: Switching power supplies offer higher efficiency than traditional linear power supplies. Unlike a linear power supply, the pass transistor of a switching-mode supply, continually switches between low-dissipation, full-on and full-off *, states †, and spends very little time in transitions to minimize wasted energy. Ideally, a switched mode power supply dissipates no power. This higher efficiency is an important advantage of a switched mode power supply.

\*no resistances, ie no voltage drop or no dissipative current
\†A switching regulator uses an active device that switches "on" and "off" to maintain an average value of output.
2.2 DC/DC CONVERTERS

2. Size: Switched mode power supplies may also be substantially smaller and lighter than a linear supply due to the smaller transformer's size and weight; and due to the less thermal management required because less energy is lost in the transfer.

3. Output voltages can be greater than the input or negative: DC/DC converter can transform input voltage to output voltages that can be greater than the input (boost), negative (inverter), or can even be transferred through a transformer to provide electrical isolation with respect to the input. By contrast linear regulator can only generate a lower voltage value than input DC one.

Cons:

However, DC/DC converter are more complicated; their switching currents can cause electrical noise and interference problems if not carefully suppressed. Linear regulators provide lower noise; their simplicity can sometimes offer a less expensive solution. Even if the most of low noise electronic circuits can tolerate some of the less-noisy DC/DC converters; some sensitive analog circuits require a power supply with so little noise that it can only be provided by a linear regulator.

2.1.2 Applications

DC/DC converter is used in many domestic products to supply whatever voltages are needed in personal computers, mobile phone chargers, as well as in embedded instrument powered by battery and/or solar generator. This is typically used for DC distribution in satellite (see Fig. 2.2). Indeed, aerospace industry requires small, lightweight, and efficient power converters.

Figure 2.2: DC/DC converter for space applications - CLYDE SPACE

2.2 DC/DC converters

We will discuss 4 different common topologies of DC/DC converter:

1. step-down voltage converter ⇒ buck converter.
2. step-up voltage converter ⇒ boost converter.
3. inverter voltage converter ⇒ inverting buck-boost converter.
4. isolated voltage converter ⇒ flyback converter.

*many linear power supplies use large transformer to changes AC amplitude before rectifier diode.
†DC/DC converters have switching noise at the switching frequency and its harmonics. Electrical noise can be emitted from the supplying power lines as RF noise which should be prevented with proper filtering.
2.2.1 *Buck* converters

*Buck* converter is a *step-down DC/DC converter*. It is composed of an inductor L and two switches (usually a transistor and a diode) that control the inductor charge and discharge (see figure 2.3). Indeed, switches alternate between connecting the inductor to source voltage (store energy in the inductor\(^*\)) and discharging the inductor into the load.

![Buck topology of a step-down DC/DC converter.](image)

It is useful to consider that components are perfect (Fig. 2.4) to simplify the analysis. So the switch and the diode have zero voltage drop when they conduct (*i.e.* ON) and zero current flow when they block (*i.e.* OFF). Moreover, the inductor L has zero series resistance. Further, it is assumed that the input and output voltages do not change over a switching cycle\(^†\).

![Simplified Buck converter circuit for the two configurations: left when the transistor T conducts (ON); right when it is OFF.](image)

**Continuous operation** \(\equiv I_L \neq 0 \forall t\)

We consider that the current through the inductor L never falls to zero (continuous mode) during the commutation cycle; this imply minimum switching frequency and capacitor value.

**Charge phase** \(T_{ON}\) : When the transistor conducts (diode is reverse biased), because the inductor current not evolves quickly, the voltage across the inductor \(V_L = V_{in} - V_{out}\) is considered as a constant voltage to a first approximation. So the current through the inductor \(I_L\) rises linearly with time following expression 2.1 with a \(\frac{V_L}{L}\) slope\(^‡\).

\[
dI_L = \frac{1}{L} \int_{t=T_{ON}} V_L \, dt \tag{2.1}
\]

During the charge phase \(T_{ON}\), \(I_L\) increases by the value \(\Delta I_{ON}\) following expression 2.2.

\[
\Delta I_{ON} = \frac{V_{in} - V_{out}}{L} T_{ON} \tag{2.2}
\]

\(^*\)An inductor is a reactor, it reacts to current changes. A current flowing through it leads to a magnetic field in the coil which is equivalent to energy store. If the current changes, the stored magnetic flux opposed a voltage accross the inductor : \(v = L di/dt\).

\(^†\)this would imply the output capacitance C being large enough.

\(^‡\)We consider here the current charge of the inductor. The capacitor is assumed charge at a constant voltage.
Discharge phase $T_{OFF}$: When the transistor is no longer biased (i.e. OFF), diode is forward biased and conducts. The voltage across the inductor becomes equal to $-V_{out}$ and $I_{L}$ flows to the load through the diode. $I_{L}$ decreases by the value $\Delta I_{OFF}$ given by expression 2.3 due to the linear discharge of the inductor.

$$\Delta I_{OFF} = \frac{-V_{out}}{L} T_{OFF} \quad (2.3)$$

Entire switching cycle: In a steady-state operation condition, $I_{L}$ at $t = 0$ is equal to $I_{L}$ at $t = T = T_{ON} + T_{OFF}$. So the increase of $I_{L}$ during $T_{ON}$ is equal† to the decreasing during $T_{OFF}$.

$$\Delta I_{ON} + \Delta I_{OFF} = 0 \quad (2.4)$$

We can then establish the relationship 2.5 which allows to obtain the conversion factor between $V_{in}$ and $V_{out}$ as a function of the duty cycle $D = \frac{T_{ON}}{T}$. It appears that $V_{out}$ varies linearly with the duty cycle for a given $V_{in}$.

$$\frac{(V_{in} - V_{out})}{L} T_{ON} - \frac{V_{out}}{L} T_{OFF} = 0 \quad \Rightarrow \quad V_{out} = DV_{in} \quad (2.5)$$

Because the duty cycle $D$ is equal to the ratio between $T_{ON}$ and the period $T$, it cannot be more than 1. Therefore, $V_{out} \leq V_{in}$. This is why this converter is named a step-down converter.

Figure 2.5 shows the evolution of voltage and current of an ideal buck converter during charge and discharge phases.

2.2.2 Boost converters

A boost converter (step-up converter) is a DC/DC converter with an output voltage value greater than its input voltage value. The key principle that drives the boost converter is the tendency of an inductor to oppose to current changes a voltage $v = L \frac{di}{dt}$. A schematic of a boost converter is shown in figure 2.6.

*Voltage drop across diode is neglected.
†in absolute value, but not in sign.
When the transistor conduct (i.e. ON), the current flows through the inductor and energy is stored in it.

When the transistor block the current (i.e. OFF), the energy stored in the inductor $L$ is returned holding the current through it. To do this, the inductor $L$ voltage polarity changes such that it is added to the input voltage. Thus, the voltage across the inductor and the input voltage are in series and they charge together the output capacitor to a voltage higher than the input voltage.

Figure 2.7 shows the evolution of voltage and current of an ideal boost converter during charge and discharge phases.

As for buck converter we consider the current through the inductor $I_L$ during the "ON" and "OFF" states:

\[
\begin{align*}
\Delta I_{\text{ON}} &= \frac{1}{L} \int_{T_{\text{ON}}} V_{\text{in}} dt \\
\Delta I_{\text{OFF}} &= \frac{1}{L} \int_{T_{\text{OFF}}} (V_{\text{in}} - V_{\text{out}}) dt
\end{align*}
\]

Over the all switching cycle, the equation 2.4 is again true. so:

\[
\frac{V_{\text{in}}}{1 - D} = V_{\text{out}} - V_{\text{in}} - V_{\text{out}} L T_{\text{OFF}}
\]
\[ \Delta I_{\text{ON}} = -\Delta I_{\text{OFF}} \Rightarrow \frac{V_{\text{in}}}{L} T_{\text{ON}} = \frac{V_{\text{out}} - V_{\text{in}}}{L} T_{\text{OFF}} \Rightarrow V_{\text{out}} = V_{\text{in}} \frac{T_{\text{ON}} + T_{\text{OFF}}}{T_{\text{OFF}}} \] (2.7)

As for buck converter, conversion factor of a boost converter could be expressed as a function of the duty cycle \( D = \frac{T_{\text{ON}}}{T_{\text{ON}} + T_{\text{OFF}}} \) and is given in equation 2.8.

\[ V_{\text{out}} = \frac{1}{1-D} V_{\text{in}} \] (2.8)

### 2.2.3 Buck-boost inverting converters

A Buck-boost converter is a DC/DC converter that has an output voltage magnitude that is either greater than* or smaller than the input voltage magnitude. The Buck-boost converter presented in figure 2.8 is also called inverting converter because its output voltage is of the opposite polarity as the input.

![Buck-boost inverting topology of DC/DC converter.](image)

Figure 2.8: Buck-boost inverting topology of DC/DC converter. \( V_{\text{out}} \) is of the opposite polarity as \( V_{\text{in}} \).

When the transistor conduct (*i.e.* ON), the input voltage source is directly connected to the inductor. This results in accumulating energy in \( L \). In this step, this is the capacitor \( C \) which supplies energy to the output load.

When the transistor blocks (*i.e.* OFF), the inductor is connected to the capacitor, so energy is transferred from \( L \) to \( C \) and therefore also to the output load.

Figure 2.9 shows the evolution of voltage and current of an ideal buck-boost converter during charge and discharge phases.

![Voltages and current as a function of time for an ideal buck converter operating in continuous mode i.e. \( I_L \) never falls to zero.](image)

Figure 2.9: Voltages and current as a function of time for an ideal buck converter operating in continuous mode *i.e.* \( I_L \) never falls to zero.

---

*in absolute magnitude.
Again, we consider the current $I_L$ during the "ON" and "OFF" states as expressed in equation 2.9.

\[
\begin{align*}
\Delta I_{L,\text{ON}} &= \frac{1}{L} \int_{t=0}^{T_{\text{ON}}} V_{\text{in}} dt = \frac{V_{\text{in}}}{L} T_{\text{ON}} \\
\Delta I_{L,\text{OFF}} &= \frac{1}{L} \int_{t=0}^{T_{\text{OFF}}} V_{\text{out}} dt = \frac{V_{\text{out}}}{L} T_{\text{OFF}}
\end{align*}
\]

Equation (2.9)

Assuming a continuous mode over the all switching cycle, we consider the increase of $I_L$ during $T_{\text{ON}}$ equal to the decreasing during $T_{\text{OFF}}$ leading to equalities 2.10 for the buck-boost converter.

\[
\Delta I_{L,\text{ON}} = -\Delta I_{L,\text{OFF}} \Rightarrow -\frac{V_{\text{in}}}{L} T_{\text{ON}} = \frac{V_{\text{out}}}{L} T_{\text{OFF}} \Rightarrow V_{\text{out}} = -V_{\text{in}} \frac{T_{\text{ON}}}{T_{\text{OFF}}}
\]

Equation (2.10)

Conversion factor of the buck-boost converter is finally given by the equation 2.11 as a function of the duty cycle D.

\[
V_{\text{out}} = -\frac{D}{1-D} V_{\text{in}}
\]

Equation (2.11)

Compared to the buck and boost converters*, buck-boost converter has an output voltage opposite in sign and which can vary continuously from 0 to $\infty$.

2.2.4 Flyback converters

The flyback converter is used when it is needed to have a galvanic isolation between the input and the outputs. The flyback converter is a buck-boost converter with the inductor split to form a transformer, so that the conversion factor is multiplied by the transformer ratio ($n_2/n_1$). Moreover, transformer provides an additional advantage: the galvanic isolation (no DC connections) between output and input voltage which allows to referred the output voltage to a desired common mode and sign.

The schematic of a flyback converter can be seen in figure 2.10. It is equivalent to that of a buck-boost converter but with a transformer instead of inductor. Therefore the operating principle of both converters is very similar:

When the transistor conducts, the primary of the transformer is directly connected to the input voltage source. The primary current and magnetic flux in the transformer increase, storing energy in the transformer. The voltage induced in the secondary winding is negative, so the diode is reverse-biased (i.e. blocked). The output capacitor supplies energy to the output load.

When the transistor is blocked, the primary current and magnetic flux drops. The secondary voltage is positive, forward-biasing the diode, allowing current to flow from the transformer. The energy from the transformer core recharges the capacitor and supplies the load.

\[V_{\text{in}} \rightarrow T \rightarrow n_1:n_2 \rightarrow C \rightarrow V_{\text{out}} \rightarrow \text{Load} \]

Figure 2.10: Flyback topology of an isolated DC/DC converter.

Conversion factor is given by equation 2.12 as a function of the duty cycle D.

\[
V_{\text{out}} = \frac{n_2}{n_1} \frac{D}{1-D} V_{\text{in}}
\]

Equation (2.12)

*The output voltage ranges for a buck and a boost converter are respectively 0 to $V_{\text{in}}$ and $V_{\text{in}}$ to $\infty$.
2.3. CONTROL

2. DC/DC CONVERTERS

A DC/DC converter using a transformer as the flyback converter is unavoidable if there is a large difference of voltage between \( V_{in} \) and \( V_{out} \). Indeed, using buck, boost or buck-boost converter, an output voltage value 100 times smaller (or larger) than the input, require a duty cycle of the order of 0.01 or 0.99 which is not easy to realized (considering that rise and fall time are not 0).

**Numerical application**: \( V_{in} = 300 \text{ V} \), \( V_{out} = 5 \text{ V} \): a buck converter require a 0.017 duty cycle (!) while with a flyback converter it is possible to stay with a duty cycle close to 50 % by choosing a transformer with a ratio \( n_2/n_1 \approx V_{out}/V_{in} \approx 0.017 \).

Disadvantage: A transformer, heavy and lossy, is needed.

### 2.3 Control

A voltage regulator is designed to automatically maintain a constant output voltage level even if \( V_{in} \) changes. It require **negative feedback control loops**.

We have see that changing the duty cycle of the switching (i.e. Transistor ON/OFF) controls the steady-state output with respect to the input voltage. Then, act on the duty cycle of the transistor driver allows to regulate the output voltage around a constant voltage even if \( V_{in} \), loads or other parameters change.

#### 2.3.1 Feedback regulation

Feedback principle consist in subtracting\(^1\) from the "input signal" a fraction of the output one. However, in the case of a DC/DC converter, the "input signal" is more the duty cycle \( D \) than \( V_{in} \) (Fig. 2.11).

![Figure 2.11: Principle of a DC/DC converter feedback voltage regulation. D is the duty cycle of the switching transistor.](image)

#### 2.3.2 Voltage regulation

To do a voltage regulation with a DC/DC converter, a sample of the output voltage is compared to a reference voltage\(^2\) to establish a small error signal \( V_{err} \). This error signal is used to modulate the duty cycle \( D \) \((D \propto 1/V_{err})\) of the transistor driver (Fig. 2.21). This modulation of the duty cycle is simply obtained by comparing the error signal with a triangle signal (Fig. 2.13). Duty cycle modulation is also called Pulse Width Modulation (PWM) because if the duty cycle changes, the pulse width also changes.

Regulation is finally obtained because feedback changes the duty cycle from \( V_{out} \) then moves the \( V_{out} \) to reduce the error signal to zero, thus completing the control loop. The higher the error voltage, the longer the transistor conducts\(^3\). \( V_{err} \) is derived in the feedback system from the error amplifier that amplifies the difference between the output voltage and the reference voltage:

\[
\text{if } V_{out} > V_{err} > D_{PWM} > D_T > V_{out} \quad \text{(2.13)}
\]

This type of voltage regulation of a DC/DC converter is classified as a voltage-mode controller\(^4\) because the feedback regulates the output voltage. So, if the loop gain is \( \gg 1 \), the output impedance of the

---

\(^1\)by using a proper filtering with a large capacitor.

\(^2\)Only negative feedback is considered here, because stable operation is required. Moreover, a frequency compensation is needed.

\(^3\)The reference voltage could be obtained by using a zener diode \( D_z \) biased by the \( V_{in} \) through a resistor \( R \).

\(^4\)Considering that the output voltage value is lower than what we want.

\(^5\)Another type of control is current-mode control. This method regulates the output current and, with infinite loop gain, the output is a high-impedance source.
regulated voltage converter is $0 \, \Omega$. Indeed, output impedance of an ideal voltage source is $0 \, \Omega$; $V_{out}$ is constant whatever the output load (no resistive voltage divider).
2.3. CONTROL

2. DC/DC CONVERTERS
2.4 DC/DC converter and duty cycle

A solar panel provides to a satellite a 12V DC power supply refereed to the ground.

1. What types of DC/DC converter allows to generate 5 V? What is the switching duty cycle required?
2. What types of DC/DC converter allows to generate 48 V? Duty cycle?
3. What types of DC/DC converter allows to generate a range of [-5 V : -48 V]? Duty cycles?

2.5 Triangle wave oscillator for PWM

A square signal with a variable duty cycle is required to address transistor of a DC/DC converter. The simplified circuit of a Pulse Width Modulation (PWM) is given in figure 2.14.

Modulation of the duty cycle is obtain by comparing the $V_{ref}$ reference voltage to a triangle signal. Consider the triangle oscillator given in figure 2.15 with operational amplifiers biased under $\pm V_{bias}$.

Due to the positive feedback of the Schmitt trigger: $V_+ \neq V_-$ and $V_{out} = V_{ot} = +$ or $-V_{bias}$ only.
1. Assuming that saturation voltage of operational amplifier $= V_{bias}$, give a graphic representation (hysteresis curve with arrows) of $V_o$ as a function of $V_i$ of the Schmitt trigger alone (Fig. 2.16).

2. Give the waveform of $V_o$ and $V_i$ of the triangle oscillator (Fig. 2.15) as a function of time.

3. Determine the oscillation frequency $f_0$.

4. Show that $f_0$ is independent to the bias while amplitude of the triangle varies with $V_{bias}$.

![Figure 2.16: Schmitt trigger.](image)

### 2.6 Preparation of the practical work

#### 2.6.1 Triangle wave oscillator under a single $V_{CC}$ power supply

To bias the circuit of the figure 2.15 under a single $V_{CC} = +20V$ power supply, previous triangle oscillator is modified as figure 2.17 shows.

![Figure 2.17: Triangle wave generator biased under a single $V_{CC}$ power supply.](image)

A dedicated comparator LM311† is used instead of operational amplifier for the Schmitt trigger. Intermediate 5 V and 10 V voltage references are obtained by using Zener diodes (respectively $D_{Z1}$ and $D_{Z2}$). $R_0 = 1k\Omega$.

1. Give the value of $R_{Z1}$ and $R_{Z2}$ of the two 5V and 10V Zener diodes to limit current at 10 mA in this two diodes.

2. Determine the value of $R$, $C$, $R_1$ and $R_2$ to have a 20 kHz oscillation frequency with a triangle amplitude of $5V_{pp}$. Current is limited to about 500 $\mu A$ in $R$ and $R_2$.

3. Check that the slew rate of the TL081 operational amplifier is compatible with the triangle wave slope.

---

† independent common-mode frequency

† The LM311 has an open collector $\rightarrow D_{Z2}$ fix the maximum output voltage.
2.6.2 Comparator

Circuit of the comparator using the triangle signal \((V_{oi})\) is given in figure 2.18. A voltage divider bridge is proposed to test the operation of the comparator and of the PWM.

![Comparator Circuit](image)

Figure 2.18: Pulse Width Modulation generator using triangle signal and adjustable reference voltage.

1. Give the value of \(R_3\) and \(R_4\) to have \(V_{pot}\) which allows to describe the overall amplitude of the \(V_{oi}\) signal, at the output of the potentiometer (at the slider).

2. Give the link between the duty cycle of \(V_{opWM}\) and the slider voltage value \(V_{pot}\).

2.6.3 Switching transistor

Pulse Width Modulation signal is applied to a PNP transistor BDX54 as shown in figure 2.19.

![Switching Transistor](image)

Figure 2.19: Switch transistor for buck converter. \(V_D\) is connected to the cathode of the diode of the buck converter.

1. Explain the operation of the transistor BDX54 if PWM signal is \(V_{CC}\) and ground.

Consider the necessity of the \(R_b\) resistor. Indeed, switching circuit can not operate well without this resistor because LM311 are "open" collector output (Emitter is connected to the ground; see datasheet) which not fix by itself the output voltage*. Without \(R_b\), transistor conducts well (saturation region) for a 0V LM311 output, but does not block for a high impedance LM311 output (or only after a long time thanks to leakages). So, \(R_b\) is crucial to avoid a permanent transistor saturation and for a good operation of the transistor on switching-mode with good control of the duty-cycle value.

\(R_b\) value is then chosen to be the smallest to allow a fast transition between saturation and cut-off mode of the transistor (see datasheet of the transistor BDX54).

*Low LM311 output voltage = 0V, but high "output level" correspond only to a high impedance state which not set the voltage value.
2. Give the minimum value of $R_b$ which still allows the transistor saturation.

### 2.6.4 DC/DC buck converter

Circuit of the DC/DC buck converter without control is given in figure 2.20.

![Figure 2.20: DC/DC Buck converter using the PWM as a driver of the transistor.](image)

$L = 1 \text{ mH}$ and $C = 1000 \mu \text{F}$

1. Give a graphic representation of $I_L$, $V_D$, $V_{out}$ and $V_L = V_D - V_{out}$ in the continues case (i.e. $I_L$ is never null).

2. Give the expression of the average value of the output voltage $\overline{V_{out}}$ as a function of $V_{CC}$ and the duty cycle $D$.

3. Deduce the expression of $\overline{V_{out}}$ as a function of $V_{CC}$ and $\Delta V_{pot}$ for a $V_{pot}$ which go from 2.5 V to 7.5 V.

### 2.6.5 Voltage regulation

Figure 2.21 shows a part of the regulation circuit, for an open loop studies.

![Figure 2.21: Open loop regulation of a DC/DC Buck converter.](image)

A 5V voltage reference ($D_{Z1}$ of the triangle generator) will be used for the regulation of the output voltage of the DC/DC buck converter at around $V_{out} = 10V$.

1. Compute the maximum power dissipation in the 500 $\Omega$. What kind of resistor is required.

2. Found values ($\gg R_{LOAD}$) of $R_5$ and $R_6$ to have $V'_{out} = 5V$

A transfer function of the open loop $\frac{V'_{out}}{V_{pot}}$ is given in figure 2.22.

This open loop gain is measured around a 10V output average value, by applying a 1 V sine wave in addition to a static value in $V_{pot}$. 

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3. Give the transfer function $\frac{v'_{\text{out}}}{v_{\text{pot}}}$ if the loop is closed?

4. Show that a proportional (P*) control could increase static performances.

5. What is the drawback of this correction on the loop stability?

An operational amplifier LM158, could be used to realize both comparator and proportional controller (Fig. 2.23).

![Comparator proportional with a LM158.](image)

You will obtain a high open loop gain with a negative feedback as shown in figure 2.24.

![Block diagram of the control.](image)


7. What is the new performances of the system? Is it stable?

8. What kind of control (P, PI, PD) allows to increase static performance without instability?

We finally prefer the use of a PI control given in figure 2.25.

9. Give the small signal transfer function $\frac{v_{\text{pot}}}{v'_{\text{out}}}$ with $V_{DZ1} = DC$.

10. Give a value of $C_0$ which increases static performances while keep stable operation. Illustrate by a graphic representation of the open loop gain this last control.

*As the P of a Proportional, Integral and Derivative (PID) controller of a generic control loop feedback
Figure 2.25: Comparateur proportional/integrator with a LM158.
The purpose of this practical work is to build a DC/DC buck step-down converter, 20 V to 10 V on a 30 Ω load resistor and with voltage regulation.

**Preliminary settings**

Set the current limitation of the 20 V power supply at a maximum current of 600 mA (O.C.P = 600 mA; O.V.P = 21 V).

**2.7 Pulse Width Modulation (PWM)**

Build on the solder-less breadboard the three parts of the Pulse Width Modulation given in figure 2.26.

![Pulse Width Modulation Circuit](image)

*Figure 2.26: Building blocks needed for the Pulse Width Modulation generator biased under a single V\text{CC} = 20V power supply.*
2. Bias the triangle generator of the figure 2.26 under 20 V and plot the triangle signal obtained.

2. Check that \( V_{\text{pot}} \) give well a voltage from 2.5 V to 7.5 V. Give the \( V_{\text{pot}} \) extreme values obtained.

3. Connect the triangle signal to the non-inverting input of the comparator, and \( V_{\text{pot}} \) to the inverting one. Look the PWM signal and check that the duty-cycle \( D \) evolves well with \( V_{\text{pot}} \). Measure the \( V_{\text{pot}} \) corresponding to \( D=0 \) and \( D=1 \).

### 2.8 Transistor driver

Connect the PWM signal to the base of the Darlington PNP transistor BDX54 (Fig. 2.27) loaded by a 30 \( \Omega \) resistor. Be careful to this load resistance: \( \triangle \) it can be VERY hot \( \triangle \).

![Figure 2.27: Transistor driver and loading.](image)

1. Look the output voltage across \( R_{\text{LOAD}} \) with and without \( R_b \). Draw waveforms of the PWM signal and of the BDX54 collector voltage in the two cases.

2. What is the duty-cycle obtained with and without \( R_b \).

### 2.9 Waveform signals in a buck converter

Build the DC/DC Buck step-down converter as figure 2.28 with \( L = 1 \) mH, \( C = 1000 \) \( \mu \)F and \( R_{\text{LOAD}} = 30 \) \( \Omega \). Set the potentiometer to have \( V_{\text{out}} = 10V \).

![Figure 2.28: DC/DC Buck converter with transistor driver.](image)

1. Add a 1 \( \Omega \) resistor in series with \( L \) to measure the current \( I_L \). Give a graphic representation of the measured \( \Delta I_L \) and \( \Delta V_{\text{out}} \).

2. Compare \( \Delta I_L \) with \( \frac{V_{\text{out}}}{L} T_{\text{OFF}} \).
2.10 Voltage regulation

We are now interested in the open loop $\frac{V'_{\text{out}}}{V_{\text{pot}}}$ of a control feedback (Fig. 2.29). Choose $R_5 = R_6$ large as compared to $R_{\text{LOAD}}$. Apply an offset (DC voltage $\approx 5V$) in addition to an input 1V sine wave instead of $V_{\text{pot}}$ so as to have $V_{\text{out}} = 10V$.

1. Measure the $V'_{\text{out}}$ ripple amplitude as a function of the frequency. Give the transfer function $V'_{\text{out}}/V_{\text{pot}}$. Compare with tutorial.

![Figure 2.29: DC/DC Buck converter with open loop control feedback.](image)

2. Use the control given in figure 2.30 to close the control loop. Slightly change the $V_{\text{CC}}$ voltage value around 20V to check that the output voltage is well regulated at 10V whatever $V_{\text{CC}}$.

![Figure 2.30: Proportional/integrator comparator with a LM158.](image)

**Disassemble and clean**
Part III

Phase Locked Loop
3.1 Introduction

The Phase Locked Loop (PLL) plays an important role in modern electronic and particularly for space communications. Indeed, PLL is a crucial part of modulator, demodulator or synchronization systems. As example of space application (Fig. 3.1), PLL is particularly essential to estimate the instantaneous phase of a received signal, such as carrier tracking from Global Positioning System (GPS) satellites.

Figure 3.1: PLLs used for space applications (Peregrine Semiconductor); GPS constellation around the Earth.

PLL allows to extract signals from noisy transmission channels. Indeed, communications between satellites and ground stations are usually buried in atmospheric noise or some type of interferences (frequency selective fading* or doppler shift†) which one manage by a PLL.

PLL circuits can also be used to distribute clock signal, or set up as frequency multipliers or dividers for frequency synthesis.

3.2 Description

PLL is a feedback electronic circuit (control system) as shown in figure 3.2. It includes an oscillator which is constantly adjusted in order to match the instantaneous phase (therefore the frequency) of the PLL input signal. The oscillator is a Voltage Controlled Oscillator (VCO)‡ whose frequency varies with an "error" signal $\epsilon \approx V_{\text{VCO}}$. This "quasi-DC" voltage come from a phase detector (ϕ comp.). It is proportional to the phase difference between the input signal which varies in frequency as $f_{\text{in}}(t)$ and

---

*Frequency selective fading: Radio signal arrives at the receiver by two different paths.
†Doppler shift: Shift in frequency for a receiver moving relative to the emitter.
‡A VCO is an electronic oscillator (output) designed to be controlled in oscillation frequency by a voltage input. The frequency of oscillation is varied by the applied DC voltage.
3.2. DESCRIPTION

VCO output frequency $f_{out}(t)$. Frequency noises (jitter*) are suppressed after phase comparison, by adding a filter before the VCO. Thus, PLL recovers, at the output, the original signal from a noisy version of the received signal.

Phase comparison can also be made after a division of the VCO frequency, which allows to have a PLL output signal with a larger frequency. This technique is used for frequency synthesis.

A Phase Locked Loop is thus mainly composed by two key ingredients:

- Phase detector/comparator more or less associated to a filter
- Voltage Controlled Oscillator (VCO)

3.2.1 Phase detector/comparator

One key element of the PLL, is the phase comparator. A phase comparator is a frequency mixer, analog multiplier or logic circuit that generates a voltage signal whose mean value is proportional to the difference in phase between two input signals.

### Analog phase detector

Mixing (or product) of two sine waves at similar frequencies as $f_{in}$ and $f_{out}$ gives, in frequency domain, a signal at the sum and at the difference of the two input signal frequencies. The high frequency at $f_{in} + f_{out}$ is removed by filtering. The low frequency (static if $f_{in} = f_{out}$) could be expressed as a function of phase difference $\Delta \phi$ (equation 3.1).

\[
\sin(2\pi f_{in} t + \phi_{in}) \times \sin(2\pi f_{out} t + \phi_{out}) \propto \cos(\Delta \phi) - \cos(2\pi (f_{in} + f_{out}) t + \phi_{in} + \phi_{out})
\]

So multiplication allows to detect phase difference between two sine waves. This is why phase comparator is currently represented by the symbol $\otimes$ as in figure 3.2.

A circuit diagram of an analog multiplier (mixer) is given in figure 3.3. This is a simple analog circuit playing the role of phase detector§ using a “diode ring” and transformers having middle point of the secondary winding.

### Digital phase detector

Phase locked loop device as the popular CD4046 integrated circuit (see Datasheet in Appendix I) includes two kind of digital phase comparators:

- **Type I** phase comparator is designed to be driven by analog signals or square-wave digital signals and provides an output pulse at twice the input frequency. this waveform must be filtered before to drive the VCO (the average voltage is proportional to the phase difference).

---

*The jitter is an undesired deviation from time periodicity of an assumed periodic signal. PLL is a jitter suppressor.

§The IF (Intermediate Frequency) varies as the cosine of the phase different between the RF (Radio-Frequency) and LO (Local Oscillator) inputs. 0 V correspond to a phase difference = 0; min and max voltages are therefore linked to a phase = π; at multiples of $2\pi$.

---
Figure 3.3: Diode ring (double balanced) multiplier used as an analog phase detector. LO and RF can be used as inputs of the phase comparator. IF provides a voltage following the phase difference of the two inputs.

- **Type II** phase comparator is sensitive only to the relative timing of the edges of the inputs. In steady state (both signals are at the same frequency), it produces a constant output voltage proportional to the phase difference. This output will tend not to produce ripple in the control voltage of the VCO.

**Type I phase detector: XOR** The simplest phase comparator is the eXclusive OR (XOR) gate. A XOR gate is a digital logic gate which computes the binary addition \(^*\) which is symbolized by \(\oplus\). XOR truth table is shown in figure 3.1.

<table>
<thead>
<tr>
<th>A</th>
<th>B</th>
<th>A (\oplus) B</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
</tr>
</tbody>
</table>

Table 3.1: XOR truth table.

Type I comparator will be appropriate for square waves (\(v_1\) and \(v_2\) in figure 3.4) but could also be used with sine wave inputs. Its operation is highly dependent on the duty cycle of the input signals and is not really usable for duty cycle too different from \(\frac{1}{2}\).

\[
\Delta \phi = 2\pi \frac{\Delta t}{T} = 2\pi f \Delta t \quad (3.2)
\]

\(^*\)Binary addition \(\oplus\) addition modulo 2.
3.2. DESCRIPTION

For a duty cycle $= \frac{1}{2}$, XOR provides pulse train with twice the frequency of $v_1$ and $v_2$. This periodic square wave signal $v_{out}$ has a duty cycle ($D_{v_{out}} = \frac{\Delta \phi}{\pi} = 2f \Delta t$) given by expression 3.3, function of input phase difference $\Delta \phi$.

$$D_{v_{out}} = \frac{\Delta \phi}{\pi}$$ (3.3)

Then, the output of the XOR gate can be expressed as a static value $V_{out}^{static}$ and harmonics ($\frac{f}{2}$ frequency at least) as a Fourier series: see the equation 3.4 with $v_n$ and $\phi_n$ the amplitude and the phase of the $n^{th}$ harmonic at the frequency $\frac{2n}{T}$.

$$v_{out} = V_{out}^{static} + \sum_{n=1}^{\infty} v_n \sin \left( \frac{2 \pi}{T} t - \phi_n \right)$$ (3.4)

This pulse train is averaged before the VCO to keep only the static signal. The averaging value of the XOR output could be linked to the pulse width as expressed on 3.5.

$$V_{out} = D_{v_{out}} V_{dd} = \frac{2 \Delta t}{T} V_{dd}$$ (3.5)

Finally, we could obtain the information about the phase difference $\Delta \phi$ from the XOR output averaging value using the expression 3.6. This expression allows to show the phase comparator gain $K_p$.

$$\frac{V_{out}}{\Delta \phi} = \frac{V_{dd}}{\pi} = K_p \Delta \phi$$ (3.6)

The characteristics of an XOR phase comparator is represented in figure 3.5. It is periodic in $\Delta \phi$ with period of $2\pi$. The range $0 \leq \Delta \phi \leq \pi$ is the range where the PLL can operate in the locked condition (linear regime).

![Figure 3.5: Periodic characteristic of an XOR phase comparator and a typical operating point. The slope $K_p$ is the gain of the comparator.](image)

The transfer function of this phase comparator on this linear part is given by expression 3.7. $K_p$ is called the gain of the phase detector.

$$\frac{V_{out}}{\Delta \phi} = K_p = \frac{V_{dd}}{\pi} \left|_{0 \leq \Delta \phi \leq \pi} \right. [V/\text{Rad}]$$ (3.7)

When PLL is in lock condition with this type of comparator, the steady-state phase difference at the inputs is usually near $\frac{\pi}{2}$ (depend on the VCO) - often in the middle of the phase comparator (linear regime).

So, this kind of phase comparator generates always an output "digital" signal in the PLL loop. Therefore, despite low-pass filter, it always remain residual ripples, and consequent periodic phase variations at two times the frequency signals.

*The loop filter acts as a low pass filter (or integrator), smoothing this full-swing logic-output signal.*
3. PHASE LOCKED LOOP

3.2. DESCRIPTION

**Type II phase detector: charge pump** A scheme of a type II phase comparator is given in figure 3.6.

![Type II phase detector scheme](image)

**Figure 3.6: Dual D-Type phase detector: a type II phase detector.**

By contrast to the type I comparator, the type II phase detector generates output pulses **only when there is a phase error** between the input and the VCO signal and follow the characteristic illustrated on figure 3.6:

![Periodic characteristic of a Type II charge pump detector](image)

**Figure 3.7: Periodic characteristic of a Type II charge pump detector.**

- **If the two input are in phase**: The phase detector looks like an open circuit and the loop filter acts as a voltage-storage device, holding the voltage that gives the VCO frequency.
- **If the input signal moves away in frequency**: The phase detector generates a train of short pulses*, charging the capacitor of the filter to the new voltage needed to keep the VCO locked.

So, the output pulses disappear entirely when the two signals are in lock†. This means that there is no ripple in the output as compared to type I phase detector.

### 3.2.2 Voltage Control Oscillator - VCO

The other key ingredient of the PLL is the VCO. It exists two different types of controlled oscillators:

- Resonant/Harmonic oscillators ($\geq 50$ MHz)
- Relaxation oscillators ($\leq 50$ MHz)

For microwave applications, resonant oscillators implemented with devices as LC tank circuit is used. C value is adjusted (tuning) thanks to a varactor diode.

However, we will concentrate on non-microwave applications, and thus on the relaxation oscillators more easily implementable on integrated circuit (similar to the triangle oscillator of the DC/DC part). This is typically the VCO that we can find in the CD4046 PLL integrated circuit (see data sheet). $V_{VCO}$ controls the **charging and discharging** currents through an external capacitor $C$, and therefore determines the time needed to charge and discharge the capacitor to a pre-determined **threshold level**. As a result, the frequency $f_{VCO}$ changes as a function of $V_{VCO}$.

*The short pulses contain very little energy and are easy to filter out of the VCO control voltage. This results in low ripples.

†A charge pump phase detector must always have a "dead frequency band" where the phases of inputs are close enough leading to no phase error in the comparator phase. So, charge pump introduce necessarily a significant peak-to-peak jitter, because of drift within the dead frequency band.

‡Not implemented on the CD4046 to allow tuning of the $f_{VCO}$ center frequency.
3.3. FREQUENCY RANGE

If $V_{\text{VCO}}$ evolves, a linear VCO transfer function can be expressed as equation 3.8.

$$\frac{f_{\text{max}} - f_{\text{min}}}{V_{\text{max}} - V_{\text{min}}} = K_0 \quad \text{[Hz/V]}$$

$$= \frac{df_{\text{VCO}}}{dV_{\text{VCO}}} = \frac{f_{\text{VCO}}}{V_{\text{dd}}/2} \quad \text{if no "offset" ie } f_{\text{min}} = 0 \quad \text{and} \quad V_{\text{min}} = 0$$  \hfill (3.8)

In practice $V_{\text{max}}$ is limited by $V_{\text{DD}}$ and $V_{\text{min}}$ by $0V$ (or $V_{\text{SS}}$). Assuming a linear response as in figure 3.8, $f_{\text{max}}$ and $f_{\text{min}}$ are adjusted and therefore fix the gain $K_0$.

![Figure 3.8: VCO characteristic: $V_{\text{VCO}}$ as a function of $f_{\text{VCO}}$.](image)

The VCO transfer function can also be expressed using the angular frequency $\omega_{\text{VCO}}$ as eq. 3.9.

$$\frac{\omega_{\text{VCO}}}{V_{\text{VCO}}} = 2\pi K_0 = K_v \quad \text{[Rad/(V.s)]}$$ \hfill (3.9)

The VCO gain is usually expressed as a radian frequency per voltage; so its units are rad/(V.s) even if the "rad" is often omitted.

However, for a PLL, this is the phase instead of the frequency which is interesting. It is then more useful to express the phase output of the VCO:

$$\int \omega_{\text{VCO}}(t) \, dt = \phi_{\text{VCO}}(t) \quad \rightarrow \quad \frac{\omega_{\text{VCO}}(s)}{s} = \phi_{\text{VCO}}(s) \quad \text{(3.10)}$$

Then the transfer function between the phase and the input voltage of the VCO is finally given by expression 3.11

$$\frac{\phi_{\text{VCO}}(s)}{V_{\text{VCO}}(s)} = \frac{K_v}{s} \quad \text{[Rad/V]}$$ \hfill (3.11)

### 3.3 Frequency range

Operating frequency range of a PLL is graphically represented in figure 3.9. Two main frequency ranges appear:

- Lock range
- Capture range

#### 3.3.1 Lock range $2\Delta f_L$

The Lock range (also called Hold range) is the frequency range in which a PLL is able to stay locked. It correspond to a "static stable frequency range"; this means that the PLL remains locked if the input signal is a fixed frequency signal comprised in this range.

The Lock range is mainly defined by the VCO range.
3. PHASE LOCKED LOOP

3.3. FREQUENCY RANGE

\[ f_{\text{in}} - \Delta f_L \approx f_{\text{min}} \]
\[ f_{\text{in}} - \Delta f_C \]
\[ f_{\text{in}} \]
\[ f_{\text{in}} + \Delta f_C \]
\[ f_{\text{in}} + \Delta f_L \approx f_{\text{max}} \]

Figure 3.9: Scope of the 2 main frequency ranges of a PLL: Lock (or Hold) range and Capture range (more or less defines because of “pull-in” effect). \( f_0 \) correspond to the VCO center frequency.

Figure 3.5 shows that when the phase comparator is used on a PLL, the phase difference \( \Delta \phi \) need to be small enough to stay on a linear regime. So, VCO is used to operate around a center frequency \( f_{\text{VCO}} = f_0 \) and around \( V_{\text{VCO}} = \frac{V_{\text{dd}}}{2} \) as it is represented in figure 3.8. Thus, \( \Delta \phi_{\text{max}} = \pi \) around this operating point (eq. 3.12 and Fig. 3.5).

\[ 0 \leq \Delta \phi \leq \pi \] (3.12)

Knowing that \( \Delta \phi \) must be included in \([0; \pi]\) range, we can expressed the maximum range in frequency at the output of the VCO as equation 3.13 (from Fig. 3.8 \( f_{\text{max}} - f_{\text{min}} = K_0 V_{\text{dd}} \) and Fig. 3.5 \( V_{\text{dd}} = \pi K_p \)).

\[ \frac{f_{\text{max}} - f_{\text{min}}}{\text{Lock range}} = \pi K_0 K_p = \frac{K_v K_p}{2} \] (3.13)

From this expression, lock range \( 2\Delta f_L = f_{\text{max}} - f_{\text{min}} \) is defined as equation 3.14.

\[ 2\Delta f_L = \frac{K_v K_p}{2} \] (3.14)

If \( f_{\text{in}} \) exceeds \( f_{\text{max}} \) (or if \( f_{\text{in}} \) becomes smaller than \( f_{\text{min}} \)), the PLL fails to keep \( f_{\text{VCO}} = f_{\text{in}} \) and the PLL becomes unlocked. When the PLL is unlocked, the VCO generally oscillates at the frequency \( f_0 \) (the “free-running” of the VCO). The lock can be established again if the incoming signal frequency \( f_{\text{in}} \) gets close enough to \( f_0 \) i.e. as close as the Capture range.

The VCO output frequency \( f_{\text{VCO}} \) can be plotted (Fig. 3.10) as a function of the input PLL frequency \( f_{\text{in}} \).

This characteristic simply shows that \( f_{\text{VCO}} = f_{\text{in}} \) in the locked condition, and that \( f_{\text{VCO}} = f_0 \) when the PLL is unlocked. A hysteresis is observed if the Lock range is larger than the Capture range.

3.3.2 Capture range \( 2\Delta f_C \)

The capture range is the frequency range where the PLL is able to “quickly” lock-in, starting from unlocked condition. Indeed, in most practical applications, it is desirable that the locked state is obtained within a short time period. So, the capture range point out that the PLL can become locked within ”one single-beat”. This is called a lock-in process. Beyond this frequency range, a pull-in process also allows the PLL to lock, but slowly. There is obviously a blurred boundary (Fig. 3.9) between Capture range and pull-in range, but we can notice that:

- Lock-in process is much faster than pull-in process
- Capture range is smaller than pull-in range

\*In this operating point, the two compared signals are in quadrature.


Capture range refers to the dynamic behavior of the PLL loop. So $2\Delta f_c$ depends on the loop bandwidth. In the case of a single pole filter and a $Q < 1$, the Capture range is simply equal to the Lock range: $2\Delta f_c = 2\Delta f_L$.

Capture range is not necessarily centered on $f_0$.

### 3.4 Frequency response

For a small phase difference ($\sin \phi \approx \phi$) between PLL input signal and VCO output, PLL can be accurately described by a linear model expressed as regard to the phase instead of frequency. Block diagram of this linear model is given in figure 3.11. $K_v$ is the gain of the VCO (small signal analysis) expressed as equation 3.11 as regard to the phase. The loop filter plays a crucial role in the frequency response of the PLL. Its transfer function is called $H_{filter}(s)$, or more simply $H(s)$.

\[
\phi_{out} = \frac{\phi_{in}}{1 + \text{loop gain}} = \frac{K_p K_v H(s)}{1 + K_p K_v H(s)}
\]

The transfer function $H(s)$ of the filter averages the output of the phase comparator and suppresses noise of the input signal.
3.4.1 One pole loop filter

For a simple first order RC filter (Fig. 3.12), the H(s) transfer function is given by expression 3.16

\[ H(s) = \frac{V_{out}}{V_{in}} = \frac{1}{1 + RCs} \]  

(3.16)

Using this one pole filter, the PLL response is expressed as 3.17.

\[ \frac{\phi_{out}}{\phi_{in}} = \frac{1}{1 + \frac{1}{K_pK_v}s + \frac{RC}{K_pK_v}s^2} \]  

(3.17)

Denominator could be rewritten as expression 3.18 to show the natural angular frequency \( \omega_n = 2\pi f_n \) and the quality factor \( Q \) (damping factor \( \zeta = \frac{1}{2Q} \)) of the PLL response.

\[ 1 + \frac{1}{Q} + \frac{s^2}{\omega_n^2} \left\{ \begin{array}{l} \omega_n = \sqrt{\frac{K_pK_v}{RC}} \\ Q = \sqrt{\frac{K_pK_v}{RC}} \end{array} \right. \]  

(3.18)

The natural frequency of the PLL gives information about the response time of the locked system. Moreover, the quality factor inform us to overshoot and ringing. Ideally, the natural frequency should be high and the quality factor should be near unity (critical damping). But, with a single pole filter, it is not possible to control the loop frequency and quality factor independently.

Assuming a critical damping \((Q = 0.5 \text{ i.e. } \zeta = 1)\) for stable PLL operation : \(RC = \frac{1}{4K_pK_v} \rightarrow \omega_n = 2K_pK_v\).

In other words, the ability of the PLL to filter the input "frequency noise" is limited by the stable condition of the loop.

3.4.2 One pole - one zero loop filter (like PID)

A One pole - one zero filter allows to adjust independently the bandwidth of the PLL response and the damping factor. It is composed of two resistors and one capacitor (Fig. 3.13). The transfer function of this filter is given in expression 3.19 and plot in figure 3.14. It is characterized by two time constants : \( \tau_1 \) and \( \tau_2 \).

\[ H(s) = \frac{V_{out}}{V_{in}} = \frac{1 + \tau_2s}{1 + \tau_1s} \left\{ \begin{array}{l} \tau_1 = (R_1 + R_2)C \\ \tau_2 = R_2C \end{array} \right. \]  

(3.19)

Using this one pole - one zero filter, the PLL response is now expressed as 3.20.
3.4. FREQUENCY RESPONSE

Figure 3.14: Amplitude Bode plot of a one pole \((RC=t0)\) and a one pole - one zero \(((R_1 + R_2)C=t1\) and \(R_2C=t2)\) filter.

\[
\frac{\phi_{\text{out}}}{\phi_{\text{in}}} = \frac{K_p K_v \frac{1+\tau_2 s}{1+\tau_1 s}}{1 + K_p K_v \frac{1+\tau_2 s}{1+\tau_1 s}} = \frac{1}{1 + \frac{1}{K_p K_v} \frac{1+\tau_1 s}{1+\tau_2 s}} = \frac{1}{1 + \frac{1+K_p K_v \tau_1}{K_p K_v} s + \frac{\tau_1}{K_p K_v} s^2}
\]

Denominator could be rewrite as expression 3.21.

\[
1 + \frac{1}{Q} \frac{s}{\omega_n} + \frac{s^2}{\omega_n^2} \quad \begin{cases} \omega_n = \sqrt{\frac{K_p K_v}{\tau_1}} \\ Q^{-1} = \frac{1}{\omega_n \tau_1 + \omega_n \tau_2} \end{cases}
\]

The loop filter time constants (equation 3.22) can now be calculated independently for a given natural frequency \(f_n\) and damping factor \(\zeta\).

\[
\begin{cases} 
\tau_1 = \frac{K_p K_v}{\omega_n^2} \\ \tau_2 = \frac{1}{Q \omega_n} - \frac{1}{K_p K_v} 
\end{cases}
\]
3.5 Frequency Shift Keying (FSK) demodulation

We will study the use of a PLL in the case of FSK demodulation. Frequency-shift keying is used for data transfer in space communications. It is a frequency modulation scheme in which digital information is transmitted through two different frequencies: mark frequency the "1" (binary ones) and space frequency the "0" (binary zeros). The time domain of a FSK modulation is illustrated in the figures 3.15.

Digital information

```
"1"    "0"    "1"    "0"    "0"
```

Figure 3.15: Digital information FSK modulated.

Specification of the FSK modulation studied in this tutorial

- \( f_{mark} = 2200 \text{ Hz} \equiv "1" \)
- \( f_{space} = 2000 \text{ Hz} \equiv "0" \)
- bit rate = 300 bit/s

Demodulation To do the FSK demodulation, a specific voltage value is associated to each frequency in order to recover bit digital data. This is performed by using a PLL (Fig. 3.16) characterized by following specifications:

\[ \text{In telecommunications the symbol-rate is also named } \text{baud} [\text{Bd}]; \text{ for binary code } 1 \text{ Bd} = 1 \text{ bit/s. In the case of the figure 3.15, the bit rate is equal to } \frac{1}{T} = \frac{1}{t_{1} - t_{2}} = \frac{1}{t_{3} - t_{4}} \ldots \]
3.5. FREQUENCY SHIFT KEYING (FSK) DEMODULATION

- PLL continuously locked
- Capture range * \( \Delta f_C \geq 2(f_{\text{mark}} - f_{\text{space}}) \)
- feedback slightly underdamped : \( \zeta = 0.5 \)

![Diagram of FSK demodulation using PLL](image)

Figure 3.16: FSK demodulation using PLL.

- Give the shape of the \( V_{\text{VCO}} \) of the figure 3.16 for a FSK modulation signal following the FSK signal of the Figure 3.15.

### 3.5.1 VCO setting

VCO of the PLL must provides at its output a square signal whose frequency varies between \( f_{\text{min}} = 1900 \) Hz and \( f_{\text{max}} = 2300 \) Hz in order to be sure to cover mark and space frequencies. See data sheet to understand the operation of the CD4046 and to determine \( R_1, R_2 \) and \( C_1 \) to obtained a VCO frequency which can go from 1900 Hz to 2300 Hz \( (f_{\text{max}} - f_{\text{min}} = 2\Delta f_L = 400 \) Hz). The circuit of the CD4046 used as a VCO is given in figure 3.17.

Use the data sheet of the CD4046 to choose \( R_1, R_2 \) and \( C_1 \):

1. Knowing \( f_{\text{max}} \) and \( f_{\text{min}} \), what is the ratio \( \frac{R_2}{R_1} \)? Give the value of \( R_1 \) for \( R_2 = 10k\Omega \).
2. Knowing \( Vdd = 10V \) (+5V - -5V), \( f_{\text{min}} = 1900 \) Hz and \( R_2 = 10k\Omega \), give the \( C_1 \) value.
3. How can we adjust the central frequency?
4. What happens if we decrease \( R_1 \)?

![Diagram of CD4046 used as a VCO](image)

Figure 3.17: CD4046 used as a VCO.

### 3.5.2 Loop filter and PLL response

We will first use the XOR phase comparator (type I) of the CD4046 associated to a one pole filter (Fig. 3.18).

*Capture range : frequency range where the PLL is able to lock-in, starting from unlocked condition.

\( ^\dagger \zeta \) is the damping factor of the locked PLL response.
### 3.6 PLL as a Frequency Multiplier

To recover a clock signal from transmitted digital data, it could be interesting to use a PLL as a frequency multiplier. The scheme of a frequency multiplier is given in figure 3.19.

**Figure 3.19: Frequency multiplier.**

1. Give the value of the product of phase detector gain $K_p$ [V/Rad] and the VCO gain $K_v$ [Rad/Vs] : $K = K_p \times K_v$.
2. Give the value of $R_f$ for a 100 nF $C_f$ capacitor of the loop filter knowing that $Q = 0.5$.
3. Give the theoretical value of the frequency lock range $2\Delta f_L$.
4. Where must be the mark and space frequencies relatively to the locked range?
5. What is the natural frequency $f_n$ of the loop in the case of a one pole RC filter?

#### 3.6.1 PLL with one pole - one zero loop filter

We start with the circuit of a simple PLL with a **type I phase comparator and a one pole filter**.

1. Give the value of $R$ for a capacitor $C_1 = 2nF$ to have a $f_0 = 20 \text{ kHz}$.

Express the loop gain of the PLL with one pole filter as in figure 3.20 with $R_f = 15k\Omega$ and $C_f = 100nF$.

2. Compute the value of $K = K_v K_p$.
3. What is the quality factor of the loop?
4. What is the natural frequency of the loop?
5. Compute the lock ranges.

We replace the one pole filter $R_f C_f$ by a **one pole one zero filter** (Fig. 3.21)

---

*Lock range: frequency range where the PLL is able to stay locked.*
3.6. PLL AS A FREQUENCY MULTIPLIER

3. PHASE LOCKED LOOP

**Figure 3.20:** PLL locked using the type I comparator associated to a 1st order $R_f$ and $C_f$ filter.

![Image](figure3.20.png)

**Figure 3.21:** Filter 1 pole 1 zero.

6. Compute the loop gain with a type I comparator and a one pole one zero filter.

7. How to choose $R'_f$ ($R_f$ and $C_f$ stay the same as for one pole filter) to have $Q = 0.5$?

### 3.6.2 Loop with multiplication

Now we want to synthesize a frequency of 20 kHz from a reference frequency $F_{ref}$ submultiple of $F_{out}$.

The circuit of the multiplier (by N) is given on figure 3.22. A divider by N is placed between the output of the VCO (pin 4) and the input of the phase comparator (pin 3) as in the figure 3.19. By doing this, we force the VCO to provide a frequency N times larger than the reference one (Eq. 3.23).

The loop with the type I comparator has the disadvantage to ring on harmonics of the input signal. To avoid this problem, it is preferable to use a loop with a type II phase comparator.

![Image](figure3.22.png)

**Figure 3.22:** PLL as a frequency multiplier.
Considering $N$ values: 1, 2, 4, 6, 8 and 10. A CMOS divide by $N$ counter CD4018 will be used.

1. Compare the expression of the transfer function of the PLL multiplier given in figure 3.22 with those without divider.

2. What is the value of the damping factor if we keep the previous $R_f$, $R'_f$, $C$ values of the loop filter?

3. Give the value of the lock range for each cases:
   - $N = 1$ and $F_{ref} = 20kHz$
   - $N = 2$ and $F_{ref} = 10kHz$
   - $N = 4$ and $F_{ref} = 5kHz$
   - $N = 6$ and $F_{ref} = 3.3kHz$
   - $N = 8$ and $F_{ref} = 2.5kHz$
   - $N = 10$ and $F_{ref} = 2kHz$

4. See the data sheet of the CD4018 and suggest a diagram using this device to perform the division by $N$.

### 3.6.3 Frequency synthesizes

To synthesize a frequency, which is not necessarily a submultiple frequency of a reference frequency $F_{ref}$, a second frequency divider (by $M$) is required. Then, the synthesize frequency could be express as equation 3.24.

$$F_{out} = \frac{N}{M} \times F_{ref}$$

The multiplication by $N$ has been previously studied. To build the divider by $M$, an other CD4018 could be used, at the input of the PLL ($\frac{F_{ref}}{M}$) or after the PLL ($\frac{NF_{ref}}{M}$). Consider a goal synthesis frequency of $\frac{5F_{ref}}{3}$.

- Which of the two solutions is the preferred one to be used for $F_{ref} = 1kHz$, $10kHz$ and $30kHz$?
3.7 Frequency Shift Keying (FSK) demodulation

3.7.1 FSK demodulation using a CD4046 PLL

Now, we will study the FSK demodulation by using a CD4046 PLL integrated circuit.

VCO of the CD4046 supply a signal frequency from 1900 Hz to 2300 Hz which includes \( f_{\text{mark}} \) and \( f_{\text{space}} \).

- \( f_{\text{min}} = 1900 \text{ Hz} \)
- \( f_{\text{max}} = 2300 \text{ Hz} \)

**VCO setting**

1. Start to build the VCO as in figure 3.23 with \( C_1 = 90 \text{nF} \) and \( R_2 = 10 \text{k} \Omega \) and \( R_1 = 27 \text{k} \Omega \). To do the VCO setting, apply successively \(-5V\) and \(+5V\) to the VCO input and measure the output with the frequency meter. Adjust the \( R \) and \( C \) values to cover \( f_{\text{min}} \) and \( f_{\text{max}} \) range.

2. Measure the VCO frequency for \(-5V\), \(-2.5V\), \(0V\), \(2.5V\) and \(5V\) input \( VCO_{\text{in}} \).

3. Use a ramp signal going from \(-5V\) to \(+5V\) to see the evolution of the frequency in \( VCO_{\text{out}} \).

![Figure 3.23: VCO part of the CD4046](image)
3.7.2 Frequency Shift Keying (FSK) signal using the function generator

Use the "CH1" of the function generator as a square signal $\pm 5V$ ($VCO_{in}$ centered in 0V) at 2 kHz.

Switch to the modulation function "MOD" (type "FSK"):

- "Fsk Rate" = 150 Hz (use 0.1 Hz to measure $f_{\text{mark}}$ and $f_{\text{space}}$ with multimeter.)
- "Hop Freq" = 2.2 kHz

So, FSK modulation is emulated by the function generator.

- Check the good operation of the modulation by setting the "Fsk Rate" at 0.1 Hz. During the 5s of each half period, $f_{\text{mark}}$ and $f_{\text{space}}$ are measured using the frequency meter.

After $f_{\text{mark}}$ and $f_{\text{space}}$ setting, increase the "Fsk Rate" to 150 Hz to simulate a digital rate information of 300 bit/s.

**"A function generator is used here to emulate a frequency modulation. Note that a VCO can also do the job!"

PLL with type I comparator

Figure 3.24 shows the PLL connected with a type I comparator and a one pole loop filter. $R_f = 3.3k\Omega$ and $C_f = 100nF$. From the previous figure (3.23) remove the $-5V$ of the pin14 and add a $10k\Omega$ resistor to applied the FSK signal to the comparator, and thus to the PLL.

2. Measure the lock range ($2\Delta f_L$) and the capture range ($2\Delta f_C$) of the loop. To do this, apply a $\pm 5V$ square signal instead of the FSK modulated signal. Varying the frequency of this signal and check the two input of the comparator simultaneously. Check that $f_{\text{mark}}$ and $f_{\text{space}}$ are in the capture range.

3. Measure the frequency for which the PLL is unlocked.

4. Measure the shape of the output of the comparator in correspondence with the input signal and the VCO output for frequency going from $f_{\text{min}}$ to $f_{\text{max}}$.

5. Connect the FSK modulation to the input of the PLL. Measure the overshoots on the $FSK_{\text{demodulated}}$ for a low frequency bit rate. Deduce if the damping factor of the loop is large or small as compared to 1.

6. Increase progressively the bit rate up to 300 bit/s (150 Hz). See the output signal. Conclude.

7. What is the maximum bit rate achievable?
8. We want to increase the bandwidth of the loop. To do this, we reduce the resistance \( R_f \) to achieve effectively a 300 bit/s. What happen?

\[ \text{Disassemble} \]

### 3.8 Frequency multiplier

#### 3.8.1 PLL with one pole - one zero loop filter

1. Start to build the VCO as given on figure 3.25. Adjust the R value to obtain a \( f_0 = 20 \text{kHz} \) with a \( C = 2.2 \text{nF} \) (the input of the VCO is fixed to 2.5 V). R is composed of a 4.7 kΩ resistor in series with a 10 kΩ potentiometer.

![Figure 3.25: VCO.](image)

Then build the PLL as given on figure 3.26:

![Figure 3.26: PLL locked using the type II comparator associated to a one pole one zero \( R_f, R'_f \) and \( C_f \) filter.](image)

2. Close the loop with the \( R_f, R'_f \) and \( C_f \) one pole one zero filter. \( R_f = 5.6 \text{kΩ}, R'_f = 1.6 \text{kΩ} \) and \( C_f = 100 \text{nF} \). Applied to the PLL input a 0–5V square signal. Measure the capture range by sweeping the square frequency. Observe the two phase detector inputs. See also the output of the \( V_{out} \) signal when the loop unlocks. Comment.

#### 3.8.2 Loop with multiplication

Now we want to synthesize a frequency of 20 kHz from a reference frequency \( F_{ref} \) submultiple of \( F_{out} \). The circuit of the multiplier (by N) is given on figure 3.27 with \( R_f = 27 \text{kΩ}, R'_f = 4.7 \text{kΩ} \) and \( C_f = 1 \mu \text{F} \).
3.8. FREQUENCY MULTIPLIER

Divider by N is realized by a CD4018 as shown on figure 3.28.

Figure 3.28: CD4018 as a divider by 1, 2, 4, 6, 8 and 10. "dat" need to be connected to the alone Qx corresponding to the desired N value.

Give the value of the lock and capture range for each cases:

1. \(N = 1\) and \(F_{ref} = 20 kHz\)
2. \(N = 2\) and \(F_{ref} = 10 kHz\)
3. \(N = 4\) and \(F_{ref} = 5 kHz\)
4. \(N = 6\) and \(F_{ref} = 3.3 kHz\)
5. \(N = 8\) and \(F_{ref} = 2.5 kHz\)
6. \(N = 10\) and \(F_{ref} = 2 kHz\)

3.8.3 Frequency synthesizes

To synthesize a frequency, which is not necessarily a submultiple frequency of a reference frequency \(F_{ref}\), a second frequency divider (by M) is required. then, the synthesize frequency could be expressed as equation 3.25.

\[
F_{out} = \frac{N}{M} \times F_{ref}
\]

(3.25)

The multiplication by N is realized by the previous circuit. To do the divider by M, an other CD4018 is used between \(F_{ref}\) and the input of the PLL \(\frac{F_{ref}}{M}\).
• Considering a goal synthesis frequency of $\frac{5F_{\text{ref}}}{3}$, fixe N=10 and M=6.

☞ Disassemble and clean
Part IV

Modulation
4.1 Introduction

Modulation is a technique used in electronic communications for transmitting information by using a higher frequency carrier such as a radio wave. This frequency transposition (Fig. 4.1) of the information signal (baseband signal) to a higher frequency band (radio frequency) allows to transmit it, through an electromagnetic medium. So, the carrier can be physically transmitted.

For communication between satellites and ground station, a carrier higher than some 10 MHz is required due to ionospheric opacity (figure 4.2). In radio communications or switched telephone network for instance, electrical signals can only be transferred over a limited pass-band frequency spectrum, with specific lower and upper cutoff frequencies (channel).

Figure 4.2: Radio atmospheric windows - from wikipedia

Modulation could have other application than electromagnetic transmission, for example for fre-
4.2. AMPLITUDE MODULATION

Amplitude modulation (AM) is a method of transmitting information by varying the amplitude of a carrier wave in accordance with the input signal. The input signal modulates the carrier signal, creating an envelope that carries the data. AM is widely used in radio and television broadcasting, as well as in many other communication systems.

There are several types of AM, each with its own characteristics and applications:

- **Frequency division multiplexing**\(^1\). There is also some cases where the modulation is used to down convert (at lower frequency) a use-full high frequency signal. This down conversion facilitates data-processing as **sampling, filtering, detection** (lock-in amplifier\(^2\)) or **amplification** (parametric amplifier\(^3\); mixer\(^4\)).

Many parameters can be modulated. In the case of simple sine wave (or square wave) carrier, there are three obvious parameters than can be varied:

- **Frequency** modulation (or Frequency-Shift Keying) - the frequency of the carrier signal is varied in accordance to the instantaneous amplitude of the modulating signal. A VCO could be used to do a frequency modulation and a PLL to do the demodulation as we have seen in the last practical work for the FSK demodulation.

- **Phase** modulation (or Phase-Shift Keying) - the phase shift of the carrier signal is varied in accordance to the instantaneous amplitude of the modulating signal.

- **Amplitude** modulation (or Amplitude-Shift Keying for digital modulation) - the amplitude of the carrier signal is varied in accordance to the instantaneous amplitude of the modulating signal.
  - Double-SideBand (DSB)
    - DSB modulation with carrier - used for the AM radio broadcasting band
    - DSB modulation with Suppressed-Carrier (DSB-SC) - to reduce the transmitted power
  - Single-SideBand (SSB)
    - SSB modulation with carrier - one sideband suppressed to reduce occupied channel bandwidth
    - SSB modulation with Suppressed-Carrier (SSB-SC) - to reduce both power and bandwidth

4.2 Amplitude modulation

A continuous wave radio-frequency signal (a sinusoidal carrier wave) has its amplitude modulated by the input waveform before transmission. Input waveform changes the amplitude of the carrier wave and creates the envelope of the waveform. A simple form of amplitude modulation, often used for digital communications, is on-off keying\(^5\). For instance, this is used by radio amateurs to transmit Morse code.

Without transmission of the carrier, this modulation is obtained by simple multiplication of an input signal by carrier signal. Figure 4.3 shows waveform and spectrum of a multiplication of a sine-wave input signal \(f_s\) by a sine-wave carrier \(f_0\).

Indeed, multiplication transposes the input signal \(S\) at each side of the \(C\) carrier frequency (frequency domain). Each sideband is equal in bandwidth, and is a mirror image of the other. Moreover, for demodulation consideration, the carrier is generally added (see figure 4.4 and equation 4.1 with \(1/k\) a factor corresponding to the proportion of carrier added) forming a full amplitude modulation \(AM\), with carrier transmission, as waveform illustrated at the end of the figure 4.3.

\[
AM \equiv S \times C + \frac{C}{k} \quad \text{(DSB with carrier)}
\] (4.1)

Most of the time, the carrier signal \(C\) is only a sine wave as expressed in equation 4.2.

\[
C = C_0 \sin(2\pi f_0 t)
\] (4.2)

---

\(^1\) Frequency division multiplexing is a technique by which the total bandwidth available in a communication medium is divided into a series of non-overlapping frequency sub-bands (channels), each of which is used to carry a separate signal.

\(^2\) A lock-in amplifier is a type of amplifier that can extract a signal with a known carrier wave from an extremely noisy environment. It uses mixing, through a frequency mixer, to transpose the input signal to low-frequency.

\(^3\) Parametric amplifier is a highly sensitive ultra-high-frequency or microwave amplifier having as its basic element a device whose reactance can be varied periodically following a pumping frequency.

\(^4\) A frequency mixer is a nonlinear electrical circuit that creates new frequency signals at the sum and difference of the original frequencies (as a multiplier).

\(^5\) A type of amplitude-shift keying in which binary data is represented by the presence or absence of a carrier.
4. MODULATION

4.2. AMPLITUDE MODULATION

Figure 4.3: Time waveform and spectrum of a double side band (DSB) amplitude modulation without \((S \times C ; k = \infty)\) and with \((S \times C + C ; k = 1)\) transmission of the carrier.

\[ S = S_0 \sin(2\pi f_s t) \] (4.3)

In these conditions, amplitude modulation is given by equation 4.4.

\[ AM = S_0 \sin(2\pi f_s t) \times C_0 \sin(2\pi f_0 t) + \frac{C_0}{k} \sin(2\pi f_0 t) \]

\[ = \frac{S_0 C_0}{2} \left[ \cos(2\pi (f_0 - f_s) t) - \cos(2\pi (f_0 + f_s) t) \right] + \frac{C_0}{k} \sin(2\pi f_0 t) \] (4.4)

Using trigonometric functions\(^*\), equation 4.4 clearly shows that amplitude modulation produces, in addition to the adjacent sidebands \(f_0 - f_s\) and \(f_0 + f_s\), a signal with power concentrated at the carrier frequency \(f_0\). Amplitude modulation resulting in two sidebands and a carrier is called *double side band amplitude modulation* (DSB). This simplest kind of amplitude modulation is *inefficient* because of the large fraction of wasted power for transmission of the carrier and in the redundancy of information signal in the two sidebands.

\[^*\sin(a) \sin(b) = \frac{\cos(a-b) - \cos(a+b)}{2}\]
4.2. AMPLITUDE MODULATION

Increasing the efficiency: The carrier and/or one sideband may be suppressed at the expense of increased transmitter and receiver complexity. For reception, suppression of the carrier imply to restore it by the use of a local oscillator generated by a phase locked loop for example. Whereas in the case of carrier transmission, a simple rectifier diode could be used for demodulation (detection).

Suppressing both the carrier and one of the sidebands also reduces bandwidth occupancy. This is single-sideband modulation (SSB), widely used in amateur radio and other low consumption communication applications. This could be obtained by using a IQ modulator.

4.2.1 Modulation index

The modulation index (also called "modulation depth") quantify the evolution of the carrier signal around its unmodulated level. It is defined differently in frequency and amplitude modulation. In the case of amplitude modulation, modulation index \( m \) is the ratio between the "envelope" amplitude \( S_0 C_0 \) and the unmodulated transmitted carrier amplitude \( C_0/k \) (defined as expression 4.5).

\[
m = \frac{S_0 C_0}{C_0/k} = k S_0
\]  

(4.5)

Indeed, modulation index referred to a normalized comparison between modulation amplitude and carrier amplitude. So, the expression 4.4 could be rewrite by factoring \( C \) which is common to the envelope amplitude and to the carrier (eq. 4.6). Finally, a normalization of the carrier amplitude added, leads to highlight \( m \):

\[
AM \equiv C_0 \sin(2\pi f_0 t) \left[ \frac{1}{k} + S_0 \sin(2\pi f_S t) \right] = \frac{C}{k} \left[ 1 + k S_0 \sin(2\pi f_S t) \right]
\]

(4.6)

So if carrier amplitude varies by 50% above and below its "unmodulated level", the modulation index is equal to 0.5. \( m = S_0 \) in the case of full adding of the carrier i.e. \( k = 1 \). Figure 4.5 shows in time domain and frequency domain, the waveform of amplitude modulation for different modulation index.

---

* A IQ modulator, for in-phase (I) and quadrature (Q), is a modulation using two carrier shifted in phase by \( \pi/2 \).
4. MODULATION

4.3 AMPLITUDE DEMODULATION

Given in the frequency domain (Fig 4.5), the amplitude at each frequency can be easily obtained by using the equation 4.4. Techniques to graphically estimate the modulation index are also reported on this figure for \( m \leq 1 \) (usual case).

Graphic estimation of the modulation index given by expression 4.7 is easy to use for \( m \leq 1 \). However, if \( m > 1 \), it could be more complicated to estimate \( V_{\text{max}}, V_{\text{min}} \), and therefore \( m \). In practice, the modulation index is usually \(< 1\) to avoid distortions and noise.

\[
m = \frac{V_{\text{max}} - V_{\text{min}}}{V_{\text{max}} + V_{\text{min}}} \quad \text{with} \quad S_0 C_0 = \frac{V_{\text{max}} - V_{\text{min}}}{2} \quad \text{and} \quad C_0 = \frac{V_{\text{max}} + V_{\text{min}}}{2}
\]  

(4.7)

Indeed, if the modulation index is larger than 100%, the input signal is distorted and could not be demodulated correctly. But a too small modulation index leads to a large fraction of the transmitted power put in the useless carrier signal alone. So, a good tradeoff could correspond to a modulation index between 1 and 0.1.

\( \Rightarrow \) in the case of AM without carrier \((1/k = 0)\), the modulation index is \( \infty \).

4.3 Amplitude demodulation

Demodulation is used to recover the information content \((S)\) from the modulated carrier wave. Demodulation is traditionally used in connection with radio receivers, but many other systems need demodulators.

There are two main methods used to demodulate AM signals:

1. Envelope detection
2. Multiplication

4.3.1 Envelope demodulation

An amplitude modulated signal can be rectified without requiring a coherent* demodulator. For example, the signal can be passed through an envelope detector: a rectifier diode \(D\) (or a diodes bridge) and a low-pass RC filter as shown on figure 4.6. The output \(S'\) follows the same shape as the input baseband signal \(S\) (Fig. 4.7). Only a DC offset (inversely proportional to the modulation index) remains and is easily removed by using a high pass filter (as a coupling capacitor). Note that the polarity of the diode does not matter in the presented case of single-phase rectifiers.

\[ \text{Rectifying can be modelized by an absolute value function}^1: \text{absolute value} \ |\ | \text{and a low pass filtering noted "LPF" in the equations. So, envelope detection can be expressed as equation 4.8.} \]

\[
\text{LPF} \left[ \frac{S \times C + \frac{C}{K}}{K} \right] \propto S + \text{cst}
\]

(4.8)

*Coherence describes all properties of the correlation between physical quantities. In the case of amplitude demodulation, it referred to the need of use a local oscillator \(C'\) locked (synchronized) to the carrier \(C\). As opposed to envelope demodulation which doesn't need local oscillator at all.

†Absolute value correspond in fact to a full-wave rectification requiring larger number of diodes. However, the single-phase rectification shown in figure 4.6 introduce a factor of 0.5 in the demodulated amplitude.
4.3. AMPLITUDE DEMODULATION

Figure 4.7: Waveform of an envelope detection: Signal S, Carrier C, AM with a unity modulation index $S \times C + C$, Rectifying as an absolute value $|S \times C + C|$ and low pass filtering $\text{LPF}(|S \times C + C|)$ for a complete reconstruction of the input signal S.
4. MODULATION

4.3. AMPLITUDE DEMODULATION

- **The rectifier** may be in the form of a single diode D, or anything that will pass current in one direction only.

- **The filter** is usually a RC low-pass filter when the difference in frequency between the signal and the carrier is very large. Furthermore, the filter function can sometimes be achieved by the limited frequency response of the rectifier itself or of other part of the readout.

However, **only amplitude modulation with a modulation index smaller than 100% can be demodulated by envelope detection.** Indeed, for a modulation index larger than 100%, or downright without carrier, envelope detection introduces necessarily large distortions. Figure 4.8 shows, for example, a rectifying detection of an amplitude modulation without carrier (S×C). In this extreme case where \( m = \infty \), the demodulated signal is roughly a sine wave, but at twice (!) the frequency of the input signal.

To avoid this kind of distortions, a coherent demodulation is required.

4.3.2 Product demodulation

The product detector, illustrated by figure 4.9, multiplies the incoming modulated signal \( AM \) by the signal of a local oscillator \( C' \). \( C' \) need to have the **same frequency as the carrier** \( C \) of the incoming signal. The original \( S \) signal is finally recovered after low pass **filtering** (LPF) and suppression of the DC offset (eq. 4.9).

\[
LPF \left[ \left( S \times \frac{C}{k} \right) \times C' \right] \propto S + \text{cst} \tag{4.9}
\]

Using the same example as for modulation equation 4.4 and for \( C' = C \), a product detection before the filtering could be expressed as equation 4.10. Using trigonometric functions, this expression shows that the information content \( S \) is restored in the base-band \( f_s \), while the carrier and harmonics are pushed around \( 2f_0 \) and are therefore easily filtered.

\[
\begin{align*}
C \times \left( S \times \frac{C}{k} \right) & = C_0 \sin(2\pi f_0 t) \left\{ \frac{S_0 C_0}{2} \left[ \cos(2\pi(f_0 - f_s)t) - \cos(2\pi(f_0 + f_s)t) \right] + \frac{C_0}{k} \sin(2\pi f_0 t) \right\} \\
& = S_0 \frac{C_0^2}{2} \left[ \sin(2\pi f_0 t) \cos(2\pi(f_0 - f_s)t) - \sin(2\pi f_0 t) \cos(2\pi(f_0 + f_s)t) \right] \\
& \quad + \frac{C_0^2}{k} \sin^2(2\pi f_0 t) \\
& = \frac{S_0 C_0^2}{4} \left[ \sin(2\pi(2f_0 - f_s)t) + \sin(2\pi f_s t) - \sin(2\pi(2f_0 + f_s) t) + \sin(2\pi f_s t) \right] \\
& \quad + \frac{C_0^2}{2k} \left[ 1 - \cos(2\pi 2f_0 t) \right]
\end{align*} \tag{4.10}
\]

Figure 4.10 gives the waveform to illustrate this product detection in the particular case where \( k = C_0 = S_0 = 1 \). In this case, equation 4.10 can be simplified as equation 4.11. This last equation highlights the different spectral lines of the demodulated signal before filtering (DC, \( f_s \), \( 2f_0 - f_s \), \( 2f_0 + f_s \)).

\[ \sin(a) \cos(b) = \frac{\sin(a+b) + \sin(a-b)}{2} \quad ; \quad \sin^2(a) = \frac{1 - \cos(2a)}{2} \quad ; \quad \sin(-a) = -\sin(a) \]

---

\(^1\) Many natural substances exhibit rectifying behavior, which is why envelope demodulation was the earliest demodulation technique used in radio.

\(^2\) In the case of AM radio broadcast, a carrier from few 100 kHz to few MHz is used for 10 kHz signal bandwidth (audio). Regarding satellite communications, frequency carrier is of the order of several GHz; far away the signal bandwidth. For these kind of applications of the modulation, a simple first order low-pass filter is generally enough to attenuate residuals carrier harmonics.
Figure 4.8: Waveform of an envelope detection of an amplitude modulation without transmission of the carrier: Signal S, AM without carrier $S \times C$, Rectifying as an absolute value $|S \times C|$ and low pass filtering LPF($|S \times C|$). This figure clearly shows distortions introduced by envelope detection in the case of modulation index larger than 100%. Signal resulting from envelope detection is at twice the frequency of the input signal. We also can see other harmonics $4f_S$, $6f_S$, ... in the spectrum.
The difference between envelope and product detection results on the lower number of harmonics introduced by coherent technique as compared to rectifier. Spectrum frequencies higher than $2f_0$ are shown in figure 4.11 for the two demodulation techniques. This comparison of the demodulated signal before filtering highlights harmonics at $4f_0$ introduced by rectifying.

But high frequency part of the spectrum can be easily filtered. Then the main difference between envelope and product detection is that the second technique can demodulate both amplitude modulation with or without carrier. So modulation without or with reduced carrier, i.e. with $m > 100\%$, requires necessarily (to avoid distortion as shown on figure 4.8) this kind of coherent demodulation. Figure 4.12 shows demodulation of a modulated signal without carrier $(S \times C)$.

This product detection of a modulated signal without carrier can be expressed as equation 4.12. We see in this expression, the baseband demodulated signal and the radio frequency signal that we need to filter. Finally, it appears that there is no DC on this demodulated signal. This is due to the absence of carrier.

$$C \times (S \times C + C) \text{ with } C_0 \text{ and } S_0 = 1$$

$$= \frac{1}{2} + \frac{1}{2} \sin(2\pi f_0 t) + \frac{1}{4} \sin(2\pi (2f_0 - f_S) t) - \frac{1}{2} \cos(2\pi 2f_0 t) - \frac{1}{4} \sin(2\pi (2f_0 + f_S) t)$$

(4.11)

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$$C \times S \times C$$

$$= C_0 \sin(2\pi f_0 t) \frac{S_0 C_0}{2} [\cos(2\pi (f_0 - f_S) t) - \cos(2\pi (f_0 + f_S) t)]$$

$$= \frac{S_0 C_0^2}{2} [\sin(2\pi f_0 t) \cos(2\pi (f_0 - f_S) t) - \sin(2\pi f_0 t) \cos(2\pi (f_0 + f_S) t)]$$

(4.12)

$$= \frac{S_0 C_0^2}{4} [\sin(2\pi (2f_0 - f_S) t) + \sin(2\pi f_S t) - \sin(2\pi (2f_0 + f_S) t) + \sin(2\pi f_S t)]$$

$$= \frac{S_0 C_0^2}{4} [\text{baseband} \; 2 \sin(2\pi f_s t) + \sin(2\pi (2f_0 - f_S) t) - \sin(2\pi (2f_0 + f_S) t)]$$

radio frequency - filtered
Figure 4.10: **Waveform of a product detection**: Signal $S$, Carrier $C$, AM signal $S \times C + C$, demodulation $C \times (S \times C + C)$ and low pass filtering $\text{LPF}[C \times (S \times C + C)]$. 

4.3. **AMPLITUDE DEMODULATION**  

4. **MODULATION**
Figure 4.11: **Rectified vs Multiplied AM** demodulated signal. Rectifying introduce higher frequency harmonics. The difference is also visible on the lower part of the time frames.
Figure 4.12: **Waveform of a product detection of an amplitude modulation without transmission of the carrier**: Signal S, AM without carrier S × C, Demodulation by product S × S × C and low pass filtering LPF(S × S × C). With this product detection, there is no distortion, even if the carrier is not transmitted. Moreover, due to the fact that there is no carrier, there is no DC signal (offset) associated to the demodulated signal S′.
We plan to transmit an information content \( S \) from 0–30\( kHz \) baseband frequencies to a radio channel \( C \) centered around 200\( kHz \).

### 4.4 Double Side Bande Amplitude Modulation

Considering \( S \) and \( C \), two sine waves at \( f_S = 30 \) kHz and \( f_0 = 200 \) kHz respectively:

- \( S = S_0 \cos(2\pi f_S t) \)
- \( C = C_0 \cos(2\pi f_0 t) \)

#### 4.4.1 Modulation without carrier transmission

Starting by a simple multiplication \( AM_1 = S \times C \) as figure 4.13.

\[ S \times C \rightarrow AM_1 \]

Figure 4.13: Modulation by simple multiplication.

1. Give the expression of \( S \times C \) while revealing frequencies which form the modulated signal.
2. Plot the spectrum of \( AM_1 \).
3. What is the value of the modulation index?
4. What happens if the carrier \( C \) is a square signal? Plot the \( AM_1 \) spectrum in this case.
5. Now, plot the \( AM_1 \) spectrum in the case of a sin-wave carrier \( C \), but with a non monochromatic input signal. Consider the spectrum of \( S \) given on figure 4.14.
6. What happens if the frequency carrier \( f_0 \) is lower than 30 kHz? Plot the \( AM_1 \) spectrum in the case of a sine-wave carrier \( C \) at \( f_0 = 20 \) kHz. What can we expect from such a modulation?
4.4 DOUBLE SIDE BANDE AMPLITUDE MODULATION

4.4.2 The use of an AD633 as multiplier

The AD633 device is an analog multiplier including a summing input Z useful to add carrier for a complete amplitude modulation. The expression of the output pin W of the AD633 as a function of inputs is given on equation 4.13.

\[ W = \frac{(X_1 - X_2) \times (Y_1 - Y_2)}{10V} + Z \] (4.13)

Figure 4.15 gives the pin configuration of the AD633 and connections to build a simple multiplication \(S \times C\). Inverting input \(X_2\) and \(Y_2\) are not used and connected to ground.

1. Considering \(S = 6V \cos(2\pi 30kHz \ t)\) and \(C = 10V \cos(2\pi 200kHz \ t)\); what is the numerical expression of the \(AM_1(t)\) modulated signal?

2. What would happen if \(S\) and \(C\) had an amplitude of 12V?

4.4.3 Product detection

1. Propose a scheme using another AD633 to realize the demodulation of \(AM_1\).

2. Plot the spectrum of the output of the second multiplier before filtering.

3. What is the cut-off frequency needed to restore \(S\)? Give numerical value of filter elements* needed to achieve a complete demodulation.

4. Plot the spectrum after filtering.

4.4.4 Modulation with carrier transmission using an AD633

A modulation with transmission of the carrier could be expressed as \(AM_2 = \frac{C \times S}{10V} + C\).

1. Propose a simple modification of the scheme of the figure 4.15 to obtain \(AM_2\), using a unique AD633 device.

*Choose R value = 1 k\(\Omega\).
2. What is the numerical expression of the $AM_2(t)$ modulated signal showing the modulation index? What is the modulation index value?

3. Plot the spectrum of $AM_2$.

4.4.5 Modulation index adjustment

Now, we want to change the modulation index of this amplitude modulation. To do that we used an operational amplifier (TL081) to adjust the amplitude of the carrier added to the product $S \times C$.

![Diagram of amplitude modulator with adjustable modulation index.]

1. Give the expression of the gain $G$ obtained using the operational amplifier ($10k\Omega$ potentiometer $= R_1; 4.7k\Omega = R_2$).

2. Give the expected range of modulation index $m$ using the potentiometer from 0 $\Omega$ to 10 $k\Omega$.

3. Taking into account the 50 $\Omega$ output impedance of the generator which supply C, what is the range of $m$?

4. Using a TL081 as a variable gain amplifier; what is the cutoff frequency?

5. Plot the spectrum of $AM_3$ for an index modulation of 2, 1 and 0.5.

4.4.6 Envelope detection

Consider the rectifier of the figure 4.17:

![Diagram of a half wave rectifier.]

1. Give the output voltage of the rectifier for a sine wave input signal (assuming that the diode is ideal - i.e. without threshold).

2. Give the output voltage in the case of a 0.6 V threshold voltage for a sine wave input signal of 0.5V, 1V and 6V amplitude.

3. What happens if we invert the polarity of the diode?

Now, we consider the envelope detector of the figure 4.18 with low pass filter:

4. Give the output voltage of the rectifier for a sine wave input signal (ideal diode).

5. What is the expression of the cutoff frequency $f_c$ associated to the 10 $k\Omega$ and $C$?
6. What happens for an input sine-wave of frequency smaller than $f_c$?

7. Same question for an input sine-wave of frequency larger than $f_c$.

8. Plot the output signal (time domain) for a sine wave at a frequency $= f_c$.

   We will use this detector to demodulate AM3 with an index factor $m \leq 1$.

9. Considering $f_S = 30kHz$ and $f_0 = 200kHz$, what range of cutoff frequency do we need to demodulate AM3?

10. Calculate C value for a first order $f_C = 50kHz$ low pass filter.

11. What is the attenuation of the first "carrier harmonic"?
4.5 Amplitude modulation as a simple multiplication

4.5.1 Modulation

Using the AD633 multiplier, achieve the multiplication 4.19 of two sine waves issued from the function generator:

$CH_1$: sine wave of $200\,kHz$ and $10\,V_{pp}$

$CH_2$: sine wave of $30\,kHz$ and $6\,V_{pp}$

Figure 4.19: Pin configuration of an AD633 for multiplication (top view).

Check that the output of the AD633 correspond well to the multiplication of the two inputs. Use the FFT function of your oscilloscope ($Math\ function\rightarrow FFT$) to watch the spectrum of this modulation.

1. Measure and plot the waveform and the spectrum of the obtained modulation.

2. Use a square signal on the $CH_1$ (carrier) instead of sine wave. Measure and plot the waveform and the spectrum of the modulation.

3. Restore the sine wave on $CH_1$, and change $CH_2$ (signal) from sine to square. Measure and plot the waveform and the spectrum of the modulation.

4. Finally, choose two square signals as for carrier and for signal. Comment.
4.5. AMPLITUDE MODULATION AS A SIMPLE MULTIPLICATION

4.5.2 Product detection

1. Build a second multiplier AD633 (as for modulation Fig. 4.19) to demodulate $AM_1$ (first part of the figure 4.20).

2. Measure and plot the waveform and the spectrum of the demodulated signal.

3. Build the R-C low-pass filter (Fig. 4.20) to attenuate carrier harmonics. Measure and plot the waveform and the spectrum of the filtered signal.

4. Same question using a square carrier.

![Figure 4.20: Product demodulator.](image)

4.5.3 Modulation with adding carrier

A modulation with transmission of the carrier, and a unity modulation index, could be built using the scheme of the figure 4.21.

![Figure 4.21: Pin configuration of an AD633 for amplitude modulation with carrier.](image)

Build the modulator and check that the output of the AD633 correspond well to an amplitude modulation with carrier.

1. Measure and plot the waveform and the spectrum of the obtained modulation.

To adjust the index factor, a variable gain $G$ between the signal from the $CH_1$ and the summing input $Z$ is required. Build this variable gain amplifier, by using a TL081 biased under $\pm 12V$, following the scheme given in figure 4.22.

![Figure 4.22: Scheme of variable gain amplifier.](image)

Use this amplifier in the modulator between the $CH_1$ and the summing input $Z$. Observe the evolution of the index factor on the output of the modulator $AM_3$. 
2. Plot the two extreme cases of index modulation reach.

3. Try to determine $m_{\text{min}}$ and $m_{\text{max}}$ by using time waveform. In practice, which effects limit the $m$ range?

### 4.5.4 Envelope detection

Build the rectifier following the figure 4.23:

![Figure 4.23: Scheme of a half wave rectifier.](image)

1. Check the operation of the rectifier, using a $6V_{pp}$ sine-wave. Plot the waveform of the output signal $V_{out}$.

2. Place a capacitor in parallel with the resistor (Fig. 4.24) to obtain $f_C = 40kHz$. Measure this cutoff frequency.

3. Connect the modulated signal to the input of the rectifier. Measure and plot output waveform and spectrum of the rectifier with and without the capacitor. Repeat this measurement for a modulation index from 0.5, 1 to 2.

4. Increase the carrier frequency up to 2 MHz. What is happening? Comment.

![Figure 4.24: Envelope detector.](image)

Disassemble and clean
4.5. AMPLITUDE MODULATION AS A SIMPLE MULTIPLICATION

4. MODULATION
Polynomials filter tables

Butterworth, Chebyshev (3 dB and 1 dB), Bessel and Legendre polynomials tables needed for filter synthesis:

### Butterworth polynomials

<table>
<thead>
<tr>
<th>n</th>
<th>Polynomial</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>$s^2 + 1.4142s + 1$</td>
</tr>
<tr>
<td>3</td>
<td>$(s + 1)(s^2 + s + 1)$</td>
</tr>
<tr>
<td>4</td>
<td>$(s^2 + 0.7654s + 1)(s^2 + 1.8478s + 1)$</td>
</tr>
<tr>
<td>5</td>
<td>$(s + 1)(s^2 + 0.618s + 1)(s^2 + 1.618s + 1)$</td>
</tr>
<tr>
<td>6</td>
<td>$(s^2 + 0.5176s + 1)(s^2 + 1.4142s + 1)(s^2 + 1.9319s + 1)$</td>
</tr>
<tr>
<td>7</td>
<td>$(s + 1)(s^2 + 0.445s + 1)(s^2 + 1.247s + 1)(s^2 + 1.8019s + 1)$</td>
</tr>
<tr>
<td>8</td>
<td>$(s^2 + 0.3902s + 1)(s^2 + 1.1111s + 1)(s^2 + 1.6629s + 1)(s^2 + 1.9616s + 1)$</td>
</tr>
<tr>
<td>9</td>
<td>$(s + 1)(s^2 + 0.3473s + 1)(s^2 + s + 1)(s^2 + 1.5321s + 1)(s^2 + 1.8794s + 1)$</td>
</tr>
</tbody>
</table>

### Chebyshev polynomials (ripple 3dB $\equiv \epsilon = 1 \rightarrow H_{even,n} = 2^{-n/3} \approx 0.707$)

<table>
<thead>
<tr>
<th>n</th>
<th>Polynomial</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>$1.4125s^2 + 0.9109s + 1$</td>
</tr>
<tr>
<td>3</td>
<td>$(3.3487s^2 + 1)(1.1916s^2 + 0.3559s + 1)$</td>
</tr>
<tr>
<td>4</td>
<td>$(5.1026s^2 + 2.0984s + 1)(1.1073s^2 + 0.1886s + 1)$</td>
</tr>
<tr>
<td>5</td>
<td>$(5.6328s^2 + 3.2132s + 1)(1.9164s^2 + 0.4003s + 1)(1.0473s^2 + 0.0801s + 1)$</td>
</tr>
<tr>
<td>6</td>
<td>$(7.9061s^2 + 1)(4.8959s^2 + 1.1159s + 1)(1.5942s^2 + 0.2515s + 1)(1.0347s^2 + 0.0582s + 1)$</td>
</tr>
<tr>
<td>7</td>
<td>$(19.8831s^2 + 4.3139s + 1)(3.1163s^2 + 0.3561s + 1)(1.3164s^2 + 0.1294s + 1)(1.0209s^2 + 0.0348s + 1)$</td>
</tr>
</tbody>
</table>
### APPENDIX A. POLYNOMIALS FILTER TABLES

#### Chebyshev polynomials (ripple 1dB $\equiv \epsilon = 0.5 \rightarrow H_{even} = \frac{1}{\sqrt{1+0.25\epsilon^2}} \approx 0.894$)

<table>
<thead>
<tr>
<th>n</th>
<th>Chebyshev polynomials</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>$0.907s^2 + 0.9956s + 1$</td>
</tr>
<tr>
<td>3</td>
<td>$(2.023s + 1)(1.0058s^2 + 0.497s + 1)$</td>
</tr>
<tr>
<td>4</td>
<td>$(3.5791s^2 + 2.4113s + 1)(1.0136s^2 + 0.2828s + 1)$</td>
</tr>
<tr>
<td>5</td>
<td>$(3.454s + 1)(1.0118s^2 + 0.181s + 1)(2.3293s^2 + 1.0911s + 1)$</td>
</tr>
<tr>
<td>6</td>
<td>$(1.793s^2 + 0.6092s + 1)(1.0093s^2 + 0.125s + 1)(8.0188s^2 + 3.7217s + 1)$</td>
</tr>
<tr>
<td>7</td>
<td>$(4.868s + 1)(1.0073s^2 + 0.092s + 1)(1.5303s^2 + 0.3919s + 1)(4.3939s^2 + 1.6061s + 1)$</td>
</tr>
<tr>
<td>8</td>
<td>$(1.0058s^2 + 0.0704s + 1)(2.9337s^2 + 0.8754s + 1)(1.382s^2 + 0.2755s + 1)/(14.2326s^2 + 5.0098s + 1)$</td>
</tr>
<tr>
<td>9</td>
<td>$(6.276s + 1)(1.2896s^2 + 0.2054s + 1)(1.0047s^2 + 0.0556s + 1)(2.2801s^2 + 0.5566s + 1)/(7.0242s^2 + 2.1033s + 1)$</td>
</tr>
</tbody>
</table>

#### Bessel polynomials (normalised to 3dB attenuation at $\omega/\omega_C = 1 \rightarrow Cf$ lecture)

<table>
<thead>
<tr>
<th>n</th>
<th>Bessel polynomials</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>$0.618s^2 + 1.3616s + 1$</td>
</tr>
<tr>
<td>3</td>
<td>$(0.756s + 1)(0.4771s^2 + 0.9996s + 1)$</td>
</tr>
<tr>
<td>4</td>
<td>$(0.4889s^2 + 1.3396s + 1)(0.3889s^2 + 0.7742s + 1)$</td>
</tr>
<tr>
<td>5</td>
<td>$(0.66s + 1)(0.3245s^2 + 0.621s + 1)(0.4128s^2 + 1.1401s + 1)$</td>
</tr>
<tr>
<td>6</td>
<td>$(0.2756s^2 + 0.513s + 1)(0.3504s^2 + 0.9686s + 1)(0.3887s^2 + 1.2217s + 1)$</td>
</tr>
<tr>
<td>7</td>
<td>$(0.593s + 1)(0.238s^2 + 0.4332s + 1)(0.301s^2 + 0.8303s + 1)(0.394s^2 + 1.0944s + 1)$</td>
</tr>
<tr>
<td>8</td>
<td>$(0.2087s^2 + 0.3727s + 1)(0.2621s^2 + 0.7202s + 1)(0.2979s^2 + 0.9753s + 1)/(0.3161s^2 + 1.111s + 1)$</td>
</tr>
<tr>
<td>9</td>
<td>$(0.536s + 1)(0.231s^2 + 0.6319s + 1)(0.1854s^2 + 0.3257s + 1)(0.2635s^2 + 0.8710s + 1)/(0.2834s^2 + 1.0243s + 1)$</td>
</tr>
</tbody>
</table>

#### Legendre polynomials

<table>
<thead>
<tr>
<th>n</th>
<th>Legendre polynomials</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>$s^2 + 1.4142s + 1$</td>
</tr>
<tr>
<td>3</td>
<td>$(1.612s + 1)(1.0744s^2 + 0.7417s + 1)$</td>
</tr>
<tr>
<td>4</td>
<td>$(1.0552s^2 + 0.4889s + 1)(2.3213s^2 + 2.5522s + 1)$</td>
</tr>
<tr>
<td>5</td>
<td>$(2.136s + 1)(1.0406s^2 + 0.3196s + 1)(2.0115s^2 + 1.5614s + 1)$</td>
</tr>
<tr>
<td>6</td>
<td>$(1.7155s^2 + 1.06s + 1)(1.0313s^2 + 0.2376s + 1)(3.9963s^2 + 3.508s + 1)$</td>
</tr>
<tr>
<td>7</td>
<td>$(2.617s + 1)(1.0241s^2 + 0.1765s + 1)(1.5102s^2 + 0.7171s + 1)(3.2679s^2 + 2.2825s + 1)$</td>
</tr>
<tr>
<td>8</td>
<td>$(1.3927s^2 + 0.5411s + 1)(1.0195s^2 + 0.1405s + 1)(5.9688s^2 + 4.3832s + 1)/(2.6116s^2 + 1.5684s + 1)$</td>
</tr>
<tr>
<td>9</td>
<td>$(3.07s + 1)(1.3043s^2 + 0.4103s + 1)(2.1574s^2 + 1.0724s + 1)(1.0158s^2 + 0.1119s + 1)/(4.7851s^2 + 2.9606s + 1)$</td>
</tr>
</tbody>
</table>
Butterworth low pass filter $n = 2$ to $5$
Chebyshev 3dB low pass filter $n = 2$ to $5$
Chebyshev 1dB low pass filter $n = 2$ to $5$
Bessel and Legendre low pass filter $n = 2$ to $5$
Bessel and Legendre low pass filter $n = 2$ to $5$
Basic trigonometric identities:

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>( \cos(-a) = \cos a )</td>
<td>( \sin(-a) = -\sin a )</td>
<td>( \tan(-a) = -\tan a )</td>
</tr>
<tr>
<td>( \cos(a + \pi) = -\cos a )</td>
<td>( \sin(a + \pi) = -\sin a )</td>
<td>( \tan(a + \pi) = \tan a )</td>
</tr>
<tr>
<td>( \cos(\pi - a) = -\cos a )</td>
<td>( \sin(\pi - a) = \sin a )</td>
<td>( \tan(\pi - a) = -\tan a )</td>
</tr>
<tr>
<td>( \cos(\frac{\pi}{2} + a) = -\cos a )</td>
<td>( \sin(\frac{\pi}{2} + a) = \cos a )</td>
<td>( \tan(\frac{\pi}{2} + a) = -\tan a )</td>
</tr>
<tr>
<td>( \cos\left(\frac{\pi}{2} - a\right) = \sin a )</td>
<td>( \sin\left(\frac{\pi}{2} - a\right) = \cos a )</td>
<td>( \tan\left(\frac{\pi}{2} - a\right) = \frac{1}{\tan a} )</td>
</tr>
</tbody>
</table>

Sum and Difference of Angles:

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>( \cos(a + b) = \cos a \times \cos b - \sin a \times \sin b )</td>
<td>( \cos(a - b) = \cos a \times \cos b + \sin a \times \sin b )</td>
<td></td>
</tr>
<tr>
<td>( \sin(a + b) = \sin a \times \cos b + \cos a \times \sin b )</td>
<td>( \sin(a - b) = \sin a \times \cos b - \cos a \times \sin b )</td>
<td></td>
</tr>
<tr>
<td>( \tan(a + b) = \frac{\tan a + \tan b}{1 - \tan a \times \tan b} )</td>
<td>( \tan(a - b) = \frac{\tan a - \tan b}{1 + \tan a \times \tan b} )</td>
<td></td>
</tr>
</tbody>
</table>

and for \( a = b \):

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>( \sin^2 a \times \cos^2 a = 1 )</td>
<td></td>
</tr>
<tr>
<td>( \cos 2a = \cos^2 a - \sin^2 a = 2 \times \cos^2 a - 1 = 1 - 2 \times \sin^2 a )</td>
<td></td>
</tr>
<tr>
<td>( 2 \times \cos^2 a = 1 + \cos 2a )</td>
<td></td>
</tr>
<tr>
<td>( 2 \times \sin^2 a = 1 - \cos 2a )</td>
<td></td>
</tr>
<tr>
<td>( \sin 2a = 2 \times \sin a \times \cos a )</td>
<td></td>
</tr>
<tr>
<td>( 2 \times \tan a )</td>
<td></td>
</tr>
<tr>
<td>( 1 - \tan^2 a )</td>
<td></td>
</tr>
</tbody>
</table>

Multiplication of 2 Trigonometric Functions:

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>( 2 \times \cos a \times \cos b = (\cos (a + b) + \cos (a - b)) )</td>
<td></td>
</tr>
<tr>
<td>( 2 \times \sin a \times \sin b = (\cos (a - b) - \cos (a + b)) )</td>
<td></td>
</tr>
<tr>
<td>( 2 \times \sin a \times \cos b = (\sin (a + b) + \sin (a - b)) )</td>
<td></td>
</tr>
</tbody>
</table>
Trigonometric circle:

- $x$ coordinate is the cosine of the angle $\theta$
- $y$ coordinate is the sine of the angle $\theta$
- $\sin \theta / \cos \theta = \tan \theta$ is the tangent of the angle $\theta$
- $\cos \theta / \sin \theta = \cot \theta$ is the cotangent of the angle $\theta$
TL081

GENERAL PURPOSE J-FET SINGLE OPERATIONAL AMPLIFIERS

- WIDE COMMON-MODE (UP TO $V_{CC}$) AND DIFFERENTIAL VOLTAGE RANGE
- LOW INPUT BIAS AND OFFSET CURRENT
- HIGH INPUT IMPEDANCE J-FET INPUT STAGE
- INTERNAL FREQUENCY COMPENSATION
- HIGH SLEW RATE: 16V/μs (typ)

DESCRIPTION
The TL081, TL081A and TL081B are high speed J-FET input single operational amplifiers incorporating well matched, high voltage J-FET and bipolar transistors in a monolithic integrated circuit.

The devices feature high slew rates, low input bias and offset currents, and low offset voltage temperature coefficient.

ABSOLUTE MAXIMUM RATINGS

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>M, AM, BM</th>
<th>TL081l, AI, BI</th>
<th>C, AC, BC</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CC}$</td>
<td>Supply voltage - note ¹⁾</td>
<td>±18</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$V_i$</td>
<td>Input Voltage - note ²⁾</td>
<td>±15</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$V_{id}$</td>
<td>Differential Input Voltage - note ³⁾</td>
<td>±30</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$P_{tot}$</td>
<td>Power Dissipation</td>
<td>680</td>
<td></td>
<td></td>
<td>mW</td>
</tr>
<tr>
<td>$T_{oper}$</td>
<td>Output Short-circuit Duration - note ⁴⁾</td>
<td>Infinito</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$T_{oper}$</td>
<td>Operating Free-air Temperature Range</td>
<td>-55 to +125</td>
<td>-40 to +105</td>
<td>0 to +70</td>
<td>°C</td>
</tr>
<tr>
<td>$T_{stg}$</td>
<td>Storage Temperature Range</td>
<td>-65 to +150</td>
<td></td>
<td></td>
<td>°C</td>
</tr>
</tbody>
</table>

ORDER CODE

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Temperature Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>TL081M/AM/BM</td>
<td>-55°C, +125°C</td>
</tr>
<tr>
<td>TL081I/AI/BI</td>
<td>-40°C, +105°C</td>
</tr>
<tr>
<td>TL081C/AC/BC</td>
<td>0°C, +70°C</td>
</tr>
</tbody>
</table>

Example: TL081CD, TL081IN
## ELECTRICAL CHARACTERISTICS

\( V_{CC} = \pm 15V, \ T_{amb} = +25^\circ C \)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>TL081, M, AC, AL, AM, BC, BI, BM</th>
<th>TL081C</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>±( V_{\text{op}} )</td>
<td>Output Voltage Swing ( T_{\text{amb}} = +25^\circ C )</td>
<td>( RL = 2k\Omega )</td>
<td>10</td>
<td>12</td>
</tr>
<tr>
<td></td>
<td>( T_{\text{amb}} = +25^\circ C )</td>
<td>( RL = 10k\Omega )</td>
<td>12</td>
<td>13.5</td>
</tr>
<tr>
<td></td>
<td>( T_{\text{min}} &lt; T_{\text{amb}} &lt; T_{\text{max}} )</td>
<td>( RL = 2k\Omega )</td>
<td>10</td>
<td>12</td>
</tr>
<tr>
<td></td>
<td>( T_{\text{min}} &lt; T_{\text{amb}} &lt; T_{\text{max}} )</td>
<td>( RL = 10k\Omega )</td>
<td>12</td>
<td>12</td>
</tr>
<tr>
<td>SR</td>
<td>Slow Rate ( T_{\text{amb}} = +25^\circ C )</td>
<td>( V_{in} = 10V, RL = 2k\Omega, C_L = 100pF, \text{unity gain} )</td>
<td>8</td>
<td>16</td>
</tr>
<tr>
<td>GBP</td>
<td>Gain Bandwidth Product ( T_{\text{amb}} = +25^\circ C )</td>
<td>( V_{in} = 10mV, RL = 2k\Omega, C_L = 100pF, f = 100kHz )</td>
<td>2.5</td>
<td>4</td>
</tr>
<tr>
<td>( R_i )</td>
<td>Input Resistance</td>
<td></td>
<td>10^{12}</td>
<td>10^{12}</td>
</tr>
<tr>
<td>( \epsilon_n )</td>
<td>Equivalent Input Noise Voltage ( R_i = 100\Omega, f = 1KHz )</td>
<td></td>
<td>15</td>
<td>15</td>
</tr>
</tbody>
</table>
**LM311 Comparator**

The LM311 series is a monolithic, low input current voltage comparator. The device is also designed to operate from dual or single supply voltage.

- Low input bias current : 250nA (Max)
- Low input offset current : 50nA (Max)
- Differential Input Voltage : ±30V
- Power supply voltage : single 5.0V to ±15V
- Offset voltage null capability.

## Absolute Maximum Ratings

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total Supply Voltage</td>
<td>VCC</td>
<td>36</td>
<td>V</td>
</tr>
<tr>
<td>Output to Negative Supply Voltage LM311</td>
<td>V_O - V_EE</td>
<td>40</td>
<td>V</td>
</tr>
<tr>
<td>Ground to Negative voltage</td>
<td>V_EE</td>
<td>-30</td>
<td>V</td>
</tr>
<tr>
<td>Differential Input Voltage</td>
<td>V_I(diff)</td>
<td>30</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>V_I</td>
<td>±15</td>
<td>V</td>
</tr>
</tbody>
</table>

## Electrical Characteristics

*(V_CCC = 15V, T_A = 25°C, unless otherwise specified)*

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Voltage Gain</td>
<td>G_V</td>
<td></td>
<td>40</td>
<td>200</td>
<td>-</td>
<td>V/mV</td>
</tr>
<tr>
<td>Response Time</td>
<td>TRES</td>
<td></td>
<td>-</td>
<td>200</td>
<td>-</td>
<td>ns</td>
</tr>
<tr>
<td>Saturation Voltage</td>
<td>V_SAT</td>
<td>IO =50mA, V_I &lt; -10mV</td>
<td>-</td>
<td>0.75</td>
<td>1.5</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>V_CCC ≥ 4.5V, V_EE =0V</td>
<td>-</td>
<td>0.23</td>
<td>0.4</td>
<td>V</td>
</tr>
</tbody>
</table>
Zener Voltage Regulators

Features
- Zener Voltage Range – 3.3 V to 200 V
- ESD Rating of Class 3 (>16 kV) per Human Body Model
- Surge Rating of up to 180 W @ 8.3 ms
- Maximum Limits Guaranteed on up to Six Electrical Parameters
- Pb-Free Packages are Available*

ELECTRICAL CHARACTERISTICS (Ta = 25°C unless otherwise noted, Vf = 1.2 V Max @ If = 1.0 A for all types)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vz</td>
<td>Reverse Zener Voltage @ IzT</td>
</tr>
<tr>
<td>IZT</td>
<td>Reverse Current</td>
</tr>
<tr>
<td>ZzT</td>
<td>Maximum Zener Impedance @ IzT</td>
</tr>
<tr>
<td>IZh</td>
<td>Reverse Current</td>
</tr>
<tr>
<td>ZzH</td>
<td>Maximum Zener Impedance @ IzH</td>
</tr>
<tr>
<td>IN</td>
<td>Reverse Leakage Current @ VN</td>
</tr>
<tr>
<td>VN</td>
<td>Breakdown Voltage</td>
</tr>
<tr>
<td>IF</td>
<td>Forward Current</td>
</tr>
<tr>
<td>VF</td>
<td>Forward Voltage @ IF</td>
</tr>
<tr>
<td>IS</td>
<td>Maximum Surge Current @ Ta = 25°C</td>
</tr>
<tr>
<td>ΔVZ</td>
<td>Reverse Zener Voltage Change</td>
</tr>
<tr>
<td>IZM</td>
<td>Maximum DC Zener Current</td>
</tr>
</tbody>
</table>

AXIAL LEAD

Zener Voltage Regulator
BDX54/A/B/C
Hammer Drivers, Audio Amplifiers Applications
Power Liner and Switching Applications

PNP Epitaxial Silicon Transistor

Absolute Maximum Ratings \( T_C=25^\circ\text{C} \) unless otherwise noted

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Value</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{CBO} )</td>
<td>Collector-Base Voltage : BDX54</td>
<td>- 45</td>
<td>V</td>
</tr>
<tr>
<td>( V_{CEO} )</td>
<td>Collector-Emitter Voltage : BDX54</td>
<td>- 45</td>
<td>V</td>
</tr>
<tr>
<td>( V_{EBO} )</td>
<td>Emitter-Base Voltage</td>
<td>- 5</td>
<td>V</td>
</tr>
<tr>
<td>( I_C )</td>
<td>Collector Current (DC)</td>
<td>- 8</td>
<td>A</td>
</tr>
<tr>
<td>( I_{CP} )</td>
<td>*Collector Current (Pulse)</td>
<td>- 12</td>
<td>A</td>
</tr>
<tr>
<td>( I_B )</td>
<td>Base Current</td>
<td>- 0.2</td>
<td>A</td>
</tr>
</tbody>
</table>

Electrical Characteristics \( T_C=25^\circ\text{C} \) unless otherwise noted

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Min.</th>
<th>Max.</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_{EBO} )</td>
<td>Emitter Cut-off Current</td>
<td>( V_{EB} = - 5\text{V}, I_C = 0 )</td>
<td>- 2</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>( h_{FE} )</td>
<td>* DC Current Gain</td>
<td>( V_{CE} = - 3\text{V}, I_C = - 3\text{A} )</td>
<td>750</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

* Pulse Test: \( \text{PW=300\mu s, duty Cycle=1.5\%} \) Pulsed
Rectifier Data Sheet

1N4001 THRU 1N4007
GENERAL PURPOSE SILICON RECTIFIER
VOLTAGE RANGE 50 TO 1000 Volts Current 1 Ampere

FEATURES
Low forward voltage drop
High current capability
High reliability
High surge current capability
Exceeds environmental standards of MIL-S-19500/228

ELECTRICAL CHARACTERISTICS*

<table>
<thead>
<tr>
<th>Rating</th>
<th>Symbol</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum Instantaneous Forward Voltage Drop, ( I_F = 1.0 \text{ Amp, } T_J = 25^\circ\C )</td>
<td>( V_F )</td>
<td>0.93</td>
<td>1.1</td>
<td>V</td>
</tr>
<tr>
<td>Maximum Full-Cycle Average Forward Voltage Drop, ( I_D = 1.0 \text{ Amp, } T_L = 75^\circ\C, 1 \text{ inch leads} )</td>
<td>( V_{R(AV)} )</td>
<td>-</td>
<td>0.8</td>
<td>V</td>
</tr>
<tr>
<td>Maximum Reverse Current (rated DC voltage) ( T_J = 25^\circ\C ) ( T_J = 100^\circ\C )</td>
<td>( I_R )</td>
<td>0.06</td>
<td>10</td>
<td>( \mu A )</td>
</tr>
<tr>
<td>Maximum Full-Cycle Average Reverse Current, ( I_O = 1.0 \text{ Amp, } T_L = 75^\circ\C, 1 \text{ inch leads} )</td>
<td>( I_{R(AV)} )</td>
<td>-</td>
<td>30</td>
<td>( \mu A )</td>
</tr>
</tbody>
</table>

MAXIMUM RATINGS

<table>
<thead>
<tr>
<th>Rating</th>
<th>Symbol</th>
<th>1N4001</th>
<th>1N4002</th>
<th>1N4003</th>
<th>1N4004</th>
<th>1N4005</th>
<th>1N4006</th>
<th>1N4007</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>*Peak Repetitive Reverse Voltage Working Peak Reverse Voltage DC Blocking Voltage</td>
<td>( V_{R_{RM}} ) ( V_{DRM} ) ( V_R )</td>
<td>50</td>
<td>100</td>
<td>200</td>
<td>400</td>
<td>600</td>
<td>800</td>
<td>1000</td>
<td>V</td>
</tr>
<tr>
<td>*Non-Repetitive Peak Reverse Voltage (halfwave, single phase, 60 Hz)</td>
<td>( V_{RSM} )</td>
<td>60</td>
<td>120</td>
<td>240</td>
<td>480</td>
<td>720</td>
<td>1000</td>
<td>1200</td>
<td>V</td>
</tr>
<tr>
<td>*RMS Reverse Voltage</td>
<td>( V_{R(\text{RMS})} )</td>
<td>35</td>
<td>70</td>
<td>140</td>
<td>280</td>
<td>420</td>
<td>560</td>
<td>700</td>
<td>V</td>
</tr>
<tr>
<td>*Average Rectified Forward Current (single phase, resistive load, 60 Hz, ( T_A = 75^\circ\C ))</td>
<td>( I_O )</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>1.0</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>A</td>
</tr>
<tr>
<td>*Non-Repetitive Peak Surge Current (surge applied at rated load conditions)</td>
<td>( I_{FSM} )</td>
<td>-</td>
<td>-</td>
<td>30 (for 1 cycle)</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>A</td>
</tr>
<tr>
<td>Operating and Storage Junction Temperature Range</td>
<td>( T_J ) ( T_{MJ} )</td>
<td>-65 to +175</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>°C</td>
</tr>
</tbody>
</table>

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LM158 Data Sheet

LM158
Low Power Dual Operational Amplifiers

General Description
The LM158 series consists of two independent, high gain, internally frequency compensated operational amplifiers which were designed specifically to operate from a single power supply over a wide range of voltages. Operation from split power supplies is also possible and the low power supply current drain is independent of the magnitude of the power supply voltage.

Application areas include transducer amplifiers, dc gain blocks and all the conventional op amp circuits which now can be more easily implemented in single power supply systems. For example, the LM158 series can be directly operated off of the standard +5V power supply voltage which is used in digital systems and will easily provide the required interface electronics without requiring the additional ±15V power supplies.

Unique Characteristics
• In the linear mode the input common-mode voltage range includes ground and the output voltage can also swing to ground, even though operated from only a single power supply voltage.

Absolute Maximum Ratings
Supply Voltage, $V^+$ 32V
Differential Input Voltage 32V
Input Voltage $-0.3V$ to $+32V$

Electrical Characteristics

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Conditions</th>
<th>Min</th>
<th>Typ</th>
</tr>
</thead>
<tbody>
<tr>
<td>Large Signal</td>
<td>$V^+ = 15V$, $T_A = 25^\circ C$, $R_L \geq 2$ kΩ, (For $V_O = 1V$ to $11V$)</td>
<td>50</td>
<td>100</td>
</tr>
</tbody>
</table>

Advantages
• Two internally compensated op amps
• Eliminates need for dual supplies
• Allows direct sensing near GND and $V_{OUT}$ also goes to GND

Features
• Internally frequency compensated for unity gain
• Large dc voltage gain: 100 dB
• Wide bandwidth (unity gain): 1 MHz
• Wide power supply range:
  — Single supply: 3V to 32V
  — or dual supplies: ±1.5V to ±16V
• Very low supply current drain (500 μA)—essentially independent of supply voltage
• Low input offset voltage: 2 mV
• Input common-mode voltage range includes ground
• Differential input voltage range equal to the power supply voltage
• Large output voltage swing
CD4046BC

Micropower Phase-Locked Loop

General Description

The CD4046BC micropower phase-locked loop (PLL) consists of a low power, linear, voltage-controlled oscillator (VCO), a source follower, a zener diode, and two phase comparators. The two phase comparators have a common signal input and a common comparator input. The signal input can be directly coupled for a large voltage signal, or capacitively coupled to the self-biasing amplifier at the signal input for a small voltage signal.

Phase comparator I, an exclusive OR gate, provides a digital error signal (phase comp. I Out) and maintains 90° phase shifts at the VCO center frequency. Between signal input and comparator input (both at 50% duty cycle), it may lock onto the signal input frequencies that are close to harmonics of the VCO center frequency.

Phase comparator II is an edge-controlled digital memory network. It provides a digital error signal (phase comp. II Out) and lock-in signal (phase pulses) to indicate a locked condition and maintains a 0° phase shift between signal input and comparator input.

The linear voltage-controlled oscillator (VCO) produces an output signal (VCO Out) whose frequency is determined by the voltage at the VCOIN input, and the capacitor and resistors connected to pin C1A, C1B, R1 and R2.

The source follower output of the VCO2 (demodulator Out) is used with an external resistor of 10 kΩ or more. The INHIBIT input, when high, disables the VCO and source follower to minimize standby power consumption. The zener diode is provided for power supply regulation, if necessary.

Features

- Wide supply voltage range: 3.0V to 18V
- Low dynamic power consumption: 70 μW (typ.) at f = 10 kHz, VDD = 5V
- VCO frequency: 1.3 MHz (typ.) at VDD = 10V
- Low frequency drift: 0.08%/°C at VDD = 10V with temperature
- High VCO linearity: 1% (typ.)

Applications

- FM demodulator and modulator
- Frequency synthesis and multiplication
- Frequency discrimination
- Data synchronization and conditioning
- Voltage-to-frequency conversion
- Tone decoding
- FSK modulation
- Motor speed control
<table>
<thead>
<tr>
<th>Symbol</th>
<th>Pin</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCP_OUT</td>
<td>1</td>
<td>phase comparator pulse output</td>
</tr>
<tr>
<td>PC1_OUT</td>
<td>2</td>
<td>phase comparator 1 output</td>
</tr>
<tr>
<td>COMP_IN</td>
<td>3</td>
<td>comparator input</td>
</tr>
<tr>
<td>VCO_OUT</td>
<td>4</td>
<td>VCO output</td>
</tr>
<tr>
<td>INH</td>
<td>5</td>
<td>inhibit input</td>
</tr>
<tr>
<td>C1A</td>
<td>6</td>
<td>capacitor C1 connection A</td>
</tr>
<tr>
<td>C1B</td>
<td>7</td>
<td>capacitor C1 connection B</td>
</tr>
<tr>
<td>VSS</td>
<td>8</td>
<td>ground supply voltage</td>
</tr>
<tr>
<td>VCO_IN</td>
<td>9</td>
<td>VCO input</td>
</tr>
<tr>
<td>SF_OUT</td>
<td>10</td>
<td>source-follower output</td>
</tr>
<tr>
<td>R1</td>
<td>11</td>
<td>resistor R1 connection</td>
</tr>
<tr>
<td>R2</td>
<td>12</td>
<td>resistor R2 connection</td>
</tr>
<tr>
<td>PC2_OUT</td>
<td>13</td>
<td>phase comparator 2 output</td>
</tr>
<tr>
<td>SIG_IN</td>
<td>14</td>
<td>signal input</td>
</tr>
<tr>
<td>ZENER</td>
<td>15</td>
<td>Zener diode input for regulated supply</td>
</tr>
<tr>
<td>V DD</td>
<td>16</td>
<td>supply voltage</td>
</tr>
</tbody>
</table>

**Typical Waveforms**

- **Signal In**: $V_{DD}$
- **Comparison In**: $V_{SS}$
- **Phase Comparator I Out**: $V_{OH}$
- **Phase Comparator II Out**: $V_{OL}$

**Typical Center Frequency vs $C1$**

For $R_1 = 10 \text{ k} \Omega$, $100 \text{ k} \Omega$ and $1 \text{ M} \Omega$.

$T_A = 25 \text{ C}$

$V_{DD} = 15V$

$V_{COO} = V_{SS}$

$V_{COI} = V_{DD}$

$R_2 = \infty$

$V_{DD} = 10V$

$V_{DD} = 5V$

$C1 = VCO TIMING \text{ CAPACITOR \ (\mu F)}$

**Typical Frequency vs $C1$**

For $R_2 = 10 \text{ k} \Omega$, $100 \text{ k} \Omega$ and $1 \text{ M} \Omega$.

$T_A = 25 \text{ C}$

$V_{DD} = 15V$

$V_{COO} = V_{SS}$

$V_{COI} = V_{DD}$

$R_2 = \infty$

$V_{DD} = 10V$

$V_{DD} = 5V$

$C1 = VCO TIMING \text{ CAPACITOR \ (\mu F)}$

**Typical Performance Characteristics**

- **Signal In**: $V_{DD}$
- **Comparison In**: $V_{SS}$
- **Phase Comparator I Out**: $V_{OH}$
- **Phase Comparator II Out**: $V_{OL}$

**Typical Waveform Employing Phase Comparator I in Locked Condition**

**Typical Waveform Employing Phase Comparator II in Locked Condition**
$T_{\text{amb}} = 25 \, ^{\circ}C$; VCO\_IN at 0.5V\_DD; INH\_IN at V\_SS; R2 = \infty.

Lines (1), (4), and (7): V\_DD = 15 \, V;
Lines (2), (5), and (8): V\_DD = 10 \, V;
Lines (3), (6), and (9): V\_DD = 5 \, V;
Lines (1), (2), and (3): R1 = 10 \, k\Omega;
Lines (4), (5), and (6): R1 = 100 \, k\Omega;
Lines (7), (8), and (9): R1 = 1 \, M\Omega.

Typical center frequency as a function of capacitor C1
$T_{amb} = 25 \, ^oC; \text{ VCO\_IN at } V_{SS}; \text{ INH\_IN at } V_{SS}; R1 = \infty.$

Lines (1), (4), and (7): $V_{DD} = 15 \, V$;

Lines (2), (5), and (8): $V_{DD} = 10 \, V$;

Lines (3), (6), and (9): $V_{DD} = 5 \, V$;

Lines (1), (2), and (3): $R2 = 10 \, k\Omega$;

Lines (4), (5), and (6): $R2 = 100 \, k\Omega$;

Lines (7), (8), and (9): $R2 = 1 \, M\Omega$.

**Typical frequency offset as a function of capacitor C1**
Line (1): $V_{DD} = 5 \text{ V}$
Line (2): $V_{DD} = 10 \text{ V}, 15 \text{ V}$.

Typical ratio of $R_2/R_1$ as a function of the ratio $f_{max}/f_{min}$
## APPENDIX J. CD4046 DATA SHEET

### Using Phase Comparator I

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Frequency</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency Capture Range</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Loop Filter Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Phase Angle Between Harmonics of Center Frequency</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Signal Input Noise Rejection</td>
<td>High</td>
<td>Low</td>
</tr>
</tbody>
</table>

### Using Phase Comparator II

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Frequency</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency Capture Range</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Loop Filter Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Phase Angle Between Harmonics of Center Frequency</td>
<td>Always 0° in lock</td>
<td>No</td>
</tr>
<tr>
<td>Signal Input Noise Rejection</td>
<td>High</td>
<td>Low</td>
</tr>
</tbody>
</table>

### Design Information

This information is a guide for approximating the value of the design. In addition to the given design information, refer to Figure 5, Figure 6, Figure 7 for R1, R2 and C1 component selection. The selected external components must be within the following range: R1, R2 ≥ 10 kΩ, C1 ≥ 10 nF, C1 ≥ 20 pF.

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Given: f0, Use f0 with Figure 5 to determine R1 and C1.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Using Phase Comparator I

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Given: f0, Use f0 with Figure 5 to determine R1 and C1.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Using Phase Comparator II

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Given: f0, Use f0 with Figure 5 to determine R1 and C1.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Using Phase Comparator II

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>VCO Without Offset</th>
<th>VCO With Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCO Component Selection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Given: f0, Use f0 with Figure 5 to determine R1 and C1.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Design Information

This information is a guide for approximating the value of the design. In addition to the given design information, refer to Figure 5, Figure 6, Figure 7 for R1, R2 and C1 component selection. The selected external components must be within the following range: R1, R2 ≥ 10 kΩ, C1 ≥ 10 nF, C1 ≥ 20 pF.
CMOS Presettable Divide-By-'N' Counter

High Voltage Types (20 Volt Rating)

- CD4018B types consist of 5 Johnson-Counter stages, buffered Q outputs from each stage, and counter preset control gating. CLOCK, RESET, DATA, PRESET ENABLE, and 5 individual DATA inputs are provided. Divide by 10, 8, 6, 4, or 2 counter configurations can be implemented by feeding the Q5, Q4, Q3, Q2, Q1 signals, respectively, back to the DATA inputs. Divide by 9, 7, 5, or 3 counter configurations can be implemented by the use of a CD40118 to gate the feedback connections to the DATA input. Divide-by functions greater than 10 can be achieved by use of multiple CD4018B units. The counter is advanced one count at the positive clock signal transition. Schmitt Trigger action on the clock line permits unlimited clock rise and fall times. A high RESET signal clears the counter to an all-zero condition. A high PRESET ENABLE signal allows information on the JAM inputs to preset the counter. Anti-look gating is provided to assure the proper counting sequence.

The CD4018B types are supplied in 16-lead hermetic dual-in-line ceramic packages (D and F suffixes), 16-lead dual-in-line plastic packages (E suffix), and in chip form (H suffix).

CD4018B Types

Features:
- Medium speed operation . . . . . . . . . . . 10 MHz (typ.) at
  VDD = VSS = 10 V
- Fully static operation
- 100% tested for quiescent current at 20 V
- Standardized, symmetrical output characteristics
- 5 V, 10 V, and 15 V parametric ratings
- Maximum input current of 1 μA at 5 V over full package-
  temperature range; 100 nA at 18 V and 25°C
- Noise margin (circuit package-temperature
  range) = 2 V at VDD = 5 V
  2 V at VDD = 10 V
  3.2 V at VDD = 15 V
- Meets all requirements of JEDEC Tentative
  Standard No. 13B, "Standard Specifications
  for Description of 'B' Series CMOS Devices"

Applications:
- Fixed and programmable divide-by-10, 9, 8,
  7, 6, 5, 4, 3, 2 counters
- Fixed and programmable counters greater
  than 10
- Programmable decade counters
- Divide-by-'N' counters/frequency
  synthesizers
- Frequency division
- Counter control/timers

MAXIMUM RATINGS, Absolute-Maximum Values:
DC SUPPLY-VOLTAGE RANGE (Vcc)
Input voltage range, all inputs .................................. VDD ± 0.5V
Input current, any one input .................................. ±10mA
APPENDIX K. CD4018 DATA SHEET

Fig. 15 - Timing diagram.

Fig. 16 - External connections for divide by 10, 3, 8, 7, 5, 4, 3, 2 operation.
AD633 Analog Multiplier

PRODUCT DESCRIPTION
The AD633 is a functionally complete, four-quadrant, analog multiplier. It includes high impedance, differential X and Y inputs and a high impedance summing input (Z). The low impedance output voltage is a nominal 10 V full scale provided by a buried Zener. The AD633 is the first product to offer these features in modestly priced 8-lead plastic DIP and SOIC packages.

The AD633 is laser calibrated to a guaranteed total accuracy of 2% of full scale. Nonlinearity for the Y-input is typically less than 0.1% and noise referred to the output is typically less than 100 μV rms in a 10 Hz to 10 kHz bandwidth. A 1 MHz bandwidth, 20 V/μs slew rate, and the ability to drive capacitive loads make the AD633 useful in a wide variety of applications where simplicity and cost are key concerns.

The AD633's versatility is not compromised by its simplicity. The Z-input provides access to the output buffer amplifier, enabling the user to sum the outputs of two or more multipliers, increase the multiplier gain, convert the output voltage to a current, and configure a variety of applications.

FEATURES
Four-Quadrant Multiplication
Low Cost 8-Lead Package
Complete—No External Components Req
Laser-Trimmed Accuracy and Stability
Total Error Within 2% of FS
Differential High Impedance X and Y Inputs
High Impedance Unity-Gain Summing Input
Laser-Trimmed 10 V Scaling Reference

APPLICATIONS
Multiplication, Division, Squaring
Modulation/Demodulation, Phase Detection
Voltage-Controlled Amplifiers/Attenuators
Filters

CONNECTION DIAGRAMS
8-Lead Plastic DIP (N) Package

ABSOLUTE MAXIMUM RATINGs
Supply Voltage .......................... ±18 V
Internal Power Dissipation^2 .......................... 500 mW
Input Voltages^3 .......................... ±18 V
Output Short Circuit Duration .......................... Indefinite
## APPENDIX L. AD633 DATA SHEET

### TRANSFER FUNCTION

\[
V_o = \frac{X_1 - X_2}{Y_1 - Y_2} \cdot Z
\]

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Conditions</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
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<tbody>
<tr>
<td><strong>MULTIPLIER PERFORMANCE</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Total Error</td>
<td>(-10 \text{ V} &lt; X, \ Y &lt; +10 \text{ V})</td>
<td>±1</td>
<td>±2</td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>T_{MIN} to T_{MAX}</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Scale Voltage Error</td>
<td>S0 = 10.00 V Nominal</td>
<td>±3</td>
<td></td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>Supply Rejection</td>
<td>VS = ±14 V to ±16 V</td>
<td>±0.01</td>
<td></td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>Nonlinearity, X</td>
<td>X = ±10 V, Y = ±10 V</td>
<td>±0.4</td>
<td>±1</td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>Nonlinearity, Y</td>
<td>Y = ±10 V, X = ±10 V</td>
<td>±0.1</td>
<td>±0.4</td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>X Feedthrough</td>
<td>Y Naired, X = ±10 V</td>
<td>±0.3</td>
<td>±1</td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>Y Feedthrough</td>
<td>X Naired, Y = ±10 V</td>
<td>±0.1</td>
<td>±0.4</td>
<td></td>
<td>% Full Scale</td>
</tr>
<tr>
<td>Output Offset Voltage</td>
<td></td>
<td>±5</td>
<td>±50</td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td><strong>DYNAMICS</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Small Signal BW</td>
<td>V0 = 0.1 V rms</td>
<td>1</td>
<td></td>
<td></td>
<td>MHz</td>
</tr>
<tr>
<td>Slope Rate</td>
<td>Vt = ±20 V p-p</td>
<td>20</td>
<td></td>
<td></td>
<td>V/mV</td>
</tr>
<tr>
<td>Settling Time to 1%</td>
<td>A V0 = 20 V</td>
<td>2</td>
<td></td>
<td></td>
<td>μs</td>
</tr>
<tr>
<td><strong>OUTPUT NOISE</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Spectral Density</td>
<td>f = 10 Hz to 5 MHz</td>
<td>0.8</td>
<td></td>
<td></td>
<td>μV/Hz</td>
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<tr>
<td>Wideband Noise</td>
<td>f = 10 Hz to 10 MHz</td>
<td>1</td>
<td>50</td>
<td></td>
<td>μV/Hz</td>
</tr>
<tr>
<td><strong>OUTPUT</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Voltage Swing</td>
<td>R0 = 0 Ω</td>
<td>±11</td>
<td>30</td>
<td>40</td>
<td>V</td>
</tr>
<tr>
<td>Short Circuit Current</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td><strong>INPUT AMPLIFIERS</strong></td>
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<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Signal Voltage Range</td>
<td>Differential</td>
<td>±10</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Common Mode</td>
<td></td>
<td>±10</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Offset Voltage X, Y</td>
<td></td>
<td>±5</td>
<td>±30</td>
<td></td>
<td>μV</td>
</tr>
<tr>
<td>CMRR X, Y</td>
<td>V_{CM} = ±10 V, f = 50 Hz</td>
<td>60</td>
<td>80</td>
<td>2.0</td>
<td>dB</td>
</tr>
<tr>
<td>Bias Current X, Y, Z</td>
<td></td>
<td>0.8</td>
<td>2.0</td>
<td>20</td>
<td>μA</td>
</tr>
<tr>
<td>Differential Resistance</td>
<td></td>
<td>10</td>
<td>20</td>
<td></td>
<td>MΩ</td>
</tr>
</tbody>
</table>
FUNCTIONAL DESCRIPTION

The AD633 is a low cost multiplier comprising a translinear core, a buried Zener reference, and a unity gain connected output amplifier with an accessible summing node. Figure 1 shows the functional block diagram. The differential X and Y inputs are converted to differential currents by voltage-to-current converters. The product of these currents is generated by the multiplying core. A buried Zener reference provides an overall scale factor of 10 V. The sum of \(X \times Y\)/10 + Z is then applied to the output amplifier. The amplifier summing node Z allows the user to add two or more multiplier outputs, convert the output voltage to a current, and configure various analog computational functions.

\[
\Phi = \frac{(X_1 - X_2)(Y_1 - Y_2)}{10} + Z
\]  
(Equation 1)

ERROR SOURCES

Multiplicative errors consist primarily of input and output offsets, scale factor error, and nonlinearity error. The input and output offsets can be eliminated by using the optional trim of Figure 2. This scheme reduces the net error to scale factor errors (gain error) and an irreducible nonlinearity component in the multiplying core. The X and Y nonlinearities are typically 0.4% and 0.1% of full scale, respectively. Scale factor error is typically 0.03% of full scale. The high impedance Z input should always be referenced to the ground point of the driven system, particularly if this is remote. Likewise, the differential X and Y inputs should be referenced to their respective grounds to realize the full accuracy of the AD633.

APPLICATIONS

The AD633 is well suited for such applications as multiplication and demodulation, automatic gain control, power measurement, voltage controlled amplifiers, and frequency doublers. Note that these applications show the pin connections for the AD633J (8-lead SOIC) which differs from the AD633JR pinout (8-lead DIP), which differs from the AD633JR pinout (8-lead SOIC).

Multiplier Connections

Figure 3 shows the basic connections for multiplication. The X and Y inputs will normally have their negative nodes grounded, but they are fully differential, and in many applications the grounded inputs may be reversed to facilitate interfacing with signals of a particular polarity, while achieving some desired output polarity or both may be driven.

Squaring and Frequency Doubling

As Figure 4 shows, squaring of an input signal, \(E\), is achieved simply by connecting the X and Y inputs in parallel to produce an output of \(E^2/10\) V. The input may have either polarity, but the output will be positive. However, the output polarity may be reversed by interchanging the X or Y inputs. The Z input may be used to add a further signal to the output.

When the input is a sine wave \(E\) sin \(\omega\), this squarer behaves as a frequency doubler, since

\[
\frac{E^2}{10} \sin^2 \omega = \frac{E^2}{201} (1 - \cos 2\omega) \]
(Equation 2)

Equation 2 shows a dc term at the output which will vary strongly with the amplitude of the input, \(E\). This can be avoided using the connections shown in Figure 5, where an RC network is used to generate two signals whose product has no dc term. It uses the identity

\[
\cos 2\theta = 2 \cos^2 \theta - 1
\]
(Equation 3)
At \( m_0 = 1/2 \), the X input leads the input signal by 45° (and is attenuated by \( \sqrt{2} \)), and the Y input lags the X input by 45° (and is also attenuated by \( \sqrt{2} \)). Since the X and Y inputs are 90° out of phase, the response of the circuit will be (satisfying Equation 3):

\[
W = \frac{1}{4|V|} \frac{E}{\sqrt{2}} \left( \sin \omega_{X} - 45^\circ \right) \frac{E}{\sqrt{2}} \left( \sin \omega_{Y} - 45^\circ \right)
\]

\[
\text{(Equation 4)}
\]

which has no dc component. Resistors R1 and R2 are included to assure the output amplitude to \( 10 \) V for an input amplitude of 1 V.

The amplitude of the output is only a weak function of frequency; the output amplitude will be 0.5% too low at \( \omega = 0.9 \omega_0 \) and \( \omega = 1.1 \omega_0 \).

Generating Inverse Functions

Inverse functions of multiplication, such as division and square rooting, can be implemented by placing a multiplier in the feedback loop of an op amp. Figure 6 shows how to implement a square rooter with the transfer function:

\[
W = \sqrt{(10V)^2}
\]

\[
\text{(Equation 5)}
\]

for the condition \( \omega < 0 \).

Likewise, Figure 7 shows how to implement a divider using a multiplier in a feedback loop. The transfer function for the divider is:

\[
W = \frac{E}{R}\frac{E}{R}
\]

\[
\text{(Equation 6)}
\]

Figure 8. Connections for Variable Scale Factor

Variable Scale Factor

In some instances, it may be desirable to use a scaling voltage other than 10 V. The connections shown in Figure 8 increase the gain of the system by the ratio \((R1 + R2)/R1\). This ratio is limited to 100 in practical applications. The summing input, \( S \), may be used to add an additional signal to the output or it may be grounded.

Current Output

The AD633’s voltage output can be converted to a current output by the addition of a resistor \( R \) between the AD633’s \( W \) and \( Z \) pins as shown in Figure 9 below. This arrangement forms
the basis of voltage-controlled integrators and oscillators as will be shown later in this Applications section. The transfer function of this circuit has the form
\[ I_o = \frac{1}{R} \left[ \frac{X_i - X_f}{X_i - X_f} \right] \frac{1}{R} \]

(Equation 7)

Linear Amplitude Modulator
The AD633 can be used as a linear amplitude modulator with
no external components. Figure 10 shows the circuit. The
carrier and modulation inputs to the AD633 are multiplied to
produce a double-sideband signal. The carrier signal is fed
forward to the AD633’s Z input where it is summed with the
double-sideband signal to produce a double-sideband with
carrier output.

Voltage Controlled Low-Pass and High-Pass Filters
Figure 11 shows a single multiplier used to build a voltage con-
trolled low-pass filter. The voltage at output A is a result of
filtering, \( E_c \). The break frequency is modulated by \( E_c \),
the control input. The break frequency, \( \omega_b \), equals
\[ \omega_b = \frac{E_c}{20V} \frac{1}{R C} \]

(Equation 8)
and the rolloff is 9 dB per octave. This output, which is at a
high impedance point, may need to be buffered.

The voltage at output B, the direct output of the AD633, has
the same response up to frequency \( \omega_b \), the natural
breakpoint of RC filter,
\[ \omega_b = \frac{1}{2 \pi R C} \]
then levels off to a constant attenuation of \( 1/\omega_b \) at \( E_c/10 \).

![Figure 10. Linear Amplitude Modulator](image)

Voltage Controlled Quadrature Oscillator
Figure 13 shows two multipliers being used to form integrators
with controllable time constants in a 2nd order differential
equation feedback loop. R2 and R3 provide controlled current
output operation. The currents are integrated in capacitors C1
and C2, and the resulting voltages at high impedance are applied
to the X inputs of the “master” AD633. The frequency control
input, \( E_{VC} \), connected to the Y inputs, varies the integrator gains
with a calibration of 100 Hz/V. The accuracy is limited by the
Y-input offsets. The practical tuning range of this circuit is
100 Hz. C1 (proportional to C1 and C2), R1, and R3 provide
regenerative feedback to start and maintain oscillation. The
diode bridge, D1 through D4 (IN914), and Zener diode D5
give economical temperature stabilization and amplitude
stabilization at ±5.5 V by degenerative damping. The output
from the second integrator (10 V sin ωt) has the lowest
distortion.

AGC AMPLIFIERS
Figure 14 shows an AGC circuit that uses an rms–dc converter
to measure the amplitude of the output waveform. The AD633
and A1, 1/2 of an AD712 dual op amp, form a voltage con-
trolled amplifier. The rms–dc converter, an AD716, measures
the rms value of the output signal. Its output drives A2, an
integrator/comparator, whose output controls the gain of the
voltage controlled amplifier. The EN4445A diode prevents
the output of A2 from going negative. R8, a 99-kΩ variable resistor,
sets the circuit’s output level. Feedback around the loop forces
the voltages at the inverting and noninverting inputs of A3 to be
equal, thus the AGC.
Signal diode Data Sheet

High-speed diodes 1N4148

- Hermetically sealed leaded glass SOD27 (DO-35)
- High switching speed: max. 4 ns
- General application
- Continuous reverse voltage: max. 100 V
- Repetitive peak reverse voltage: max. 100 V
- Repetitive peak forward current: max. 450 mA.

APPLICATIONS
- High-speed switching.

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>MAX. ELECTRICAL CHARACTERISTICS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_f$</td>
<td>forward voltage $I_f = 10 \text{ mA}$</td>
</tr>
<tr>
<td>$I_r$</td>
<td>reverse current $V_R = 20 \text{ V}; T_j = 100 \text{ °C}$</td>
</tr>
<tr>
<td>$C_d$</td>
<td>diode capacitance $f = 1 \text{ MHz}; V_R = 0 \text{ V}$</td>
</tr>
</tbody>
</table>

Forward current as a function of forward voltage.

(1) $T_j = 175 \text{ °C}$; typical values.
(2) $T_j = 25 \text{ °C}$; typical values.
(3) $T_j = 25 \text{ °C}$, maximum values.
LM78XX LINEAR INTEGRATED CIRCUIT

3-TERMINAL 1A POSITIVE VOLTAGE REGULATOR

DESCRIPTION
The Contek 78XX family is monolithic fixed voltage regulator integrated circuit. They are suitable for applications that required supply current up to 1 A.

FEATURES
* Output current up to 1.5 A
* Fixed output voltage of 5V, 6V, 8V, 9V, 10V, 12V, 15V, 18V and 24V available
* Thermal overload shutdown protection
* Short circuit current limiting
* Output transistor SOA protection

LM7805 ELECTRICAL CHARACTERISTICS

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output Voltage</td>
<td>Vo</td>
<td>Tj=25 C, Io=5mA A - 1.0A</td>
<td>4.05</td>
<td>5.0</td>
<td>5.25</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Vi=7.5V to 20V, Io=5mA A - 1.0A, PD=15W</td>
<td>4.75</td>
<td>5.25</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Load Regulation</td>
<td>△Vo</td>
<td>Tj=25 C, Io=5mA A - 1.5A</td>
<td>50</td>
<td></td>
<td></td>
<td>mV</td>
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<td>Tj=25 C, Io=0.25A A - 0.75A</td>
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<td>Line regulation</td>
<td>△Vo</td>
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<td></td>
<td></td>
<td>mV</td>
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<td></td>
<td></td>
<td>Vi=7.5V to 20V, Tj=25 C, Io=1A</td>
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<td></td>
<td></td>
<td>mV</td>
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<tr>
<td>Quiescent Current</td>
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<td>Tj=25 C, Io&lt;1A</td>
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<td>mA</td>
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<td>Quiescent Current Change</td>
<td>△Iq</td>
<td>Vi=7.5V to 20V</td>
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<td>mA</td>
</tr>
<tr>
<td>Output Noise Voltage</td>
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<td>Tj=25 C</td>
<td>40</td>
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<td>μV</td>
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<td>Temperature coefficient of Vo</td>
<td>△Vo/AT</td>
<td>Io=5mA</td>
<td>-0.6</td>
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<td>mV/C</td>
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<td>Ripple Rejection</td>
<td>RR</td>
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<td>dB</td>
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<td>Peak Output Current</td>
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<td>Short-Circuit Current</td>
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<td>Dropout Voltage</td>
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<td></td>
<td>V</td>
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